

LEC-1

Pre-Modern era of Physics - 4000 BC - 1900 AD

Celestial Mechanics \longrightarrow Universal Law of Gravitation
 \Downarrow
Observation of celestial bodies

* After the development of mechanics \approx

(*) General Relativity
 \Downarrow
Differential Geometry

Concept of a field (E & M)

Early calendars \rightarrow developed based on motion

of heavenly bodies \rightarrow But sunrise to sunrise time not always constant. Later refined as midday to midday \Rightarrow More accurate

Day \Rightarrow Sunrise to Sunrise

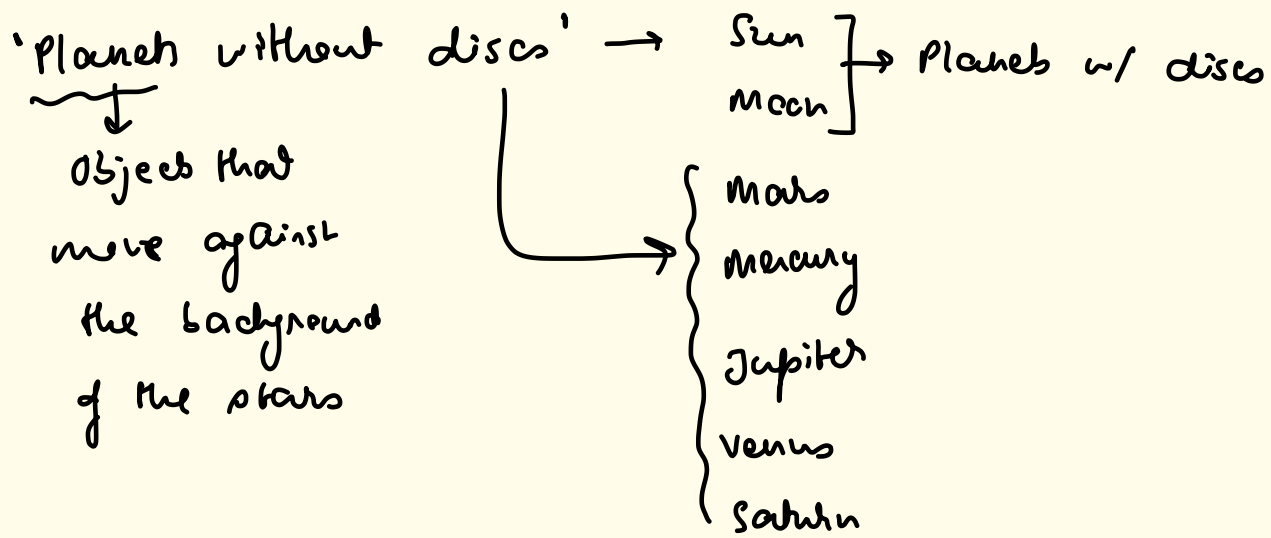
Year \Rightarrow Time in which the stars regain the same position in the night sky

Sub-units of a year

Month
- Lunar cycle
(New moon to New moon)

Week
- Why 7 days?

LEC-5

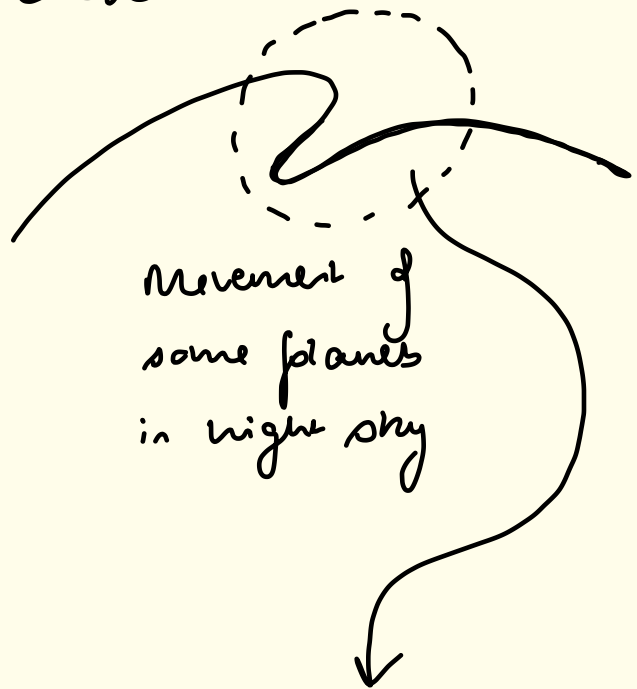
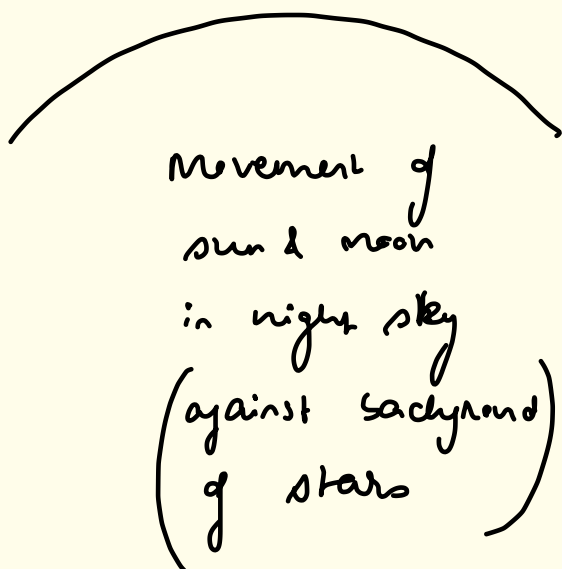


Current celestial objects

→ sun & moon that move on their own spheres which also rotate w/ Earth at their own speed

→ stars fixed on celestial sphere that rotate w/ Earth

However, none of these explain retrograde motion in planets



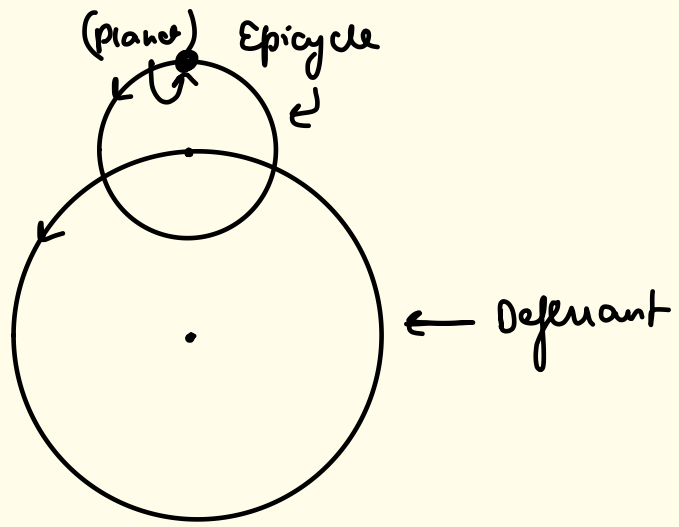
Aristotle - 'motion in the heavens is perfect'

Retrograde motion

How would you explain retrograde motion being confined to Aristotelian philosophy?

Appollonius & Hipparchus
came up w/ an
explanation

↓
Epicycles



It was believed that planetary rotation in epicycle
as well as the motion of the cycle itself were
constant

However, data over the next few centuries contradicted
this theory → Ptolemy came up with
a model

(Still Aristotian
theory)

↓
Concept of
Equant

2nd century AD

There was the elephant in the room

↓
CATHOLIC CHURCH → For some reason
they liked Aristotle's
philosophy

Still kinda
needs of
Aristotian
philosophy

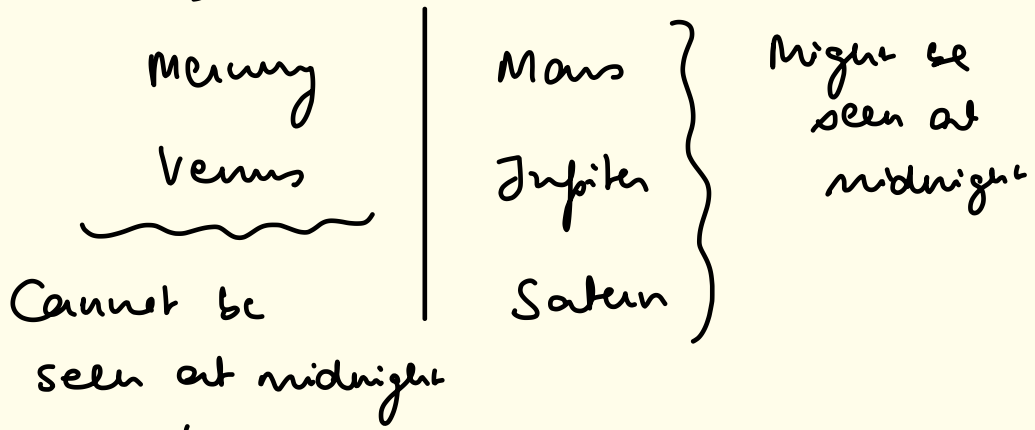
And so
was the story
until

15th century AD

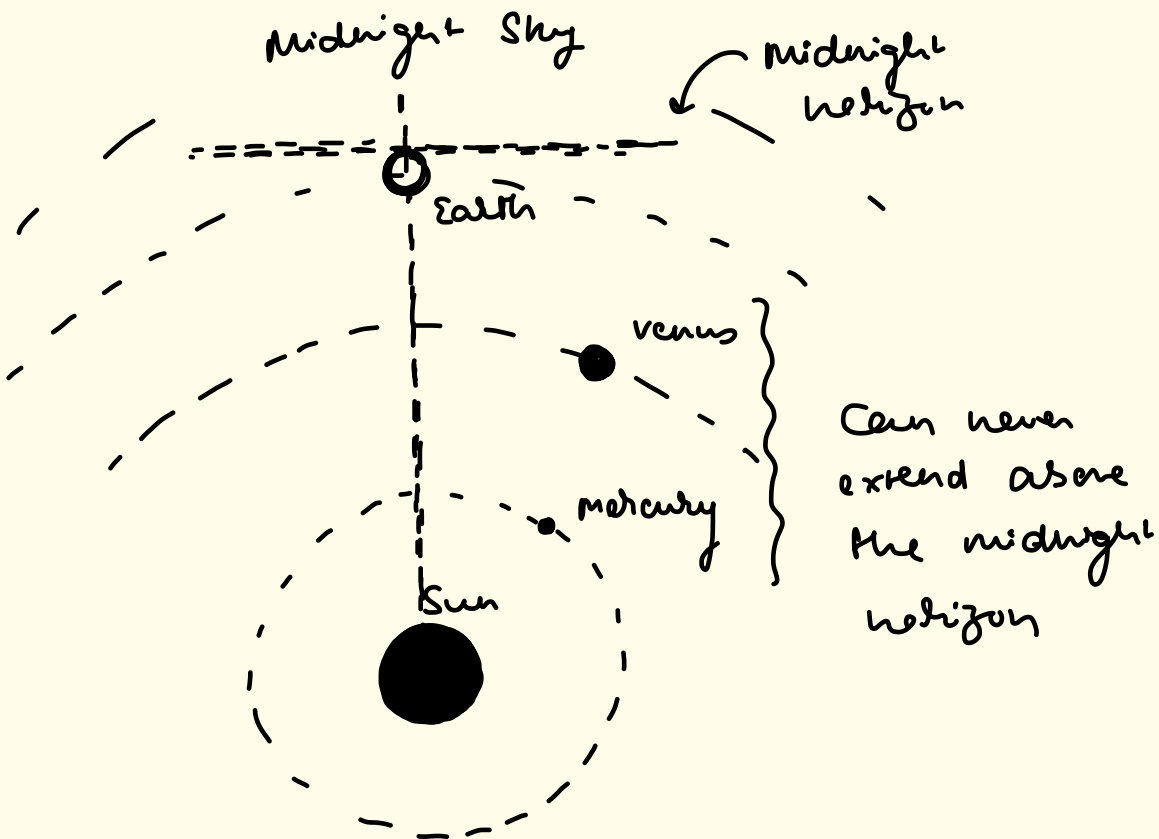
Nicholas Copernicus → Heliocentric
theory

↓
[Planets (incl. Earth excl. Moon) revolve
in a circular path around the Sun
w/ constant angular philosophy]

* Even observationally, we can make a distinction b/w planets



↓
Not enough angular displacement from the Sun.



Tycho Brahe → created one of the best naked eye observationaries w/ help from King of Denmark

He then pissed himself to death in a royal banquet and Johannes Kepler got hold of his observations

Kepler was the first one to bin Aristotle and any pre-conceived notions, which led him to ↓

Kepler's Laws
of Planetary
Motion

→ Popularised
by Galileo

→ Discovery of Law
of Gravitation by Newton

LEC-6

Themes of this course so far

1. Motion in Heavens is perfect
2. Only those ideas supported by data are given the distinction of being called theories
3. There are universal laws which hold true in heaven and on Earth

Galileo (16th century)

- Italian, hence devout catholic

- Started to question Aristotle

↳ "Heavier objects fall faster" (Allegedly)

Realised through experimentation and observation that time period of a pendulum is independent of its mass

Galileo also came up w/ eqns of motion by letting objects fall down inclined plane

Galileo thought of as first modern scientist
↓
"Only ideas supported by data are valid theories"

Galileo's astronomical discoveries using a telescope

↳ Milky way

↳ 4 moons of Jupiter

↳ features of surface of the moon

} → Against Aristotle

Then dude wrote this → 'Dialogue on Two World Systems'

↳ wanted to bitchslap Aristotle once and for all.

- No equations

- Conversation b/w three people

- First pop-sci book

- Argued for heliocentrism in a manner the general public could understand

* The people arguing for the respective theories

→ Heliocentrism - Sagredo (Sage)

→ Geocentrism - Simplicio (Dumbass)

Church kinda didn't like that... there was a trial
and he had to apologize so the higher-ups at
Church didn't get their nips in a twist (and so
Galileo didn't get tortured)



then kept on
house arrest for
the rest of his life

Next dude → Huygens (17th century)

→ Analysed uniform circular
motion and identified centripetal
force → (before Newton)

→ Built on Tautochrone

↓
kind of
clock

⇓
used oscillations
in a cycloidal
shape to produce
constant time period
irrespective of
amplitude

⊛ pendulum clocks
depending on simple
harmonic oscillation
were unreliable

→ If amplitude large,
time period differs from
expected time period

→ If amplitude small,
difficult to practically
deal with problems caused
by friction

Newton

→ Childhood trauma

→ fairly brilliant student, got into Cambridge

→ College closed due to plague outbreak, Newton sent home

→ Bored Newton looked at apple falling and moon in the sky

Apple falling → apple accelerating
Moon revolving around Earth → moon accelerating

} Newton decided to work on relation b/w the two

Newton's leap of imagination
 $a \propto \frac{1}{d^2}$ → Universal Law of Gravitation

During this time, he also casually invented calculus

↓
Used it to find a relation b/w inverse square law and Kepler's laws (They both, in fact, imply each other)

He found

$$\frac{a_{\text{apple}}}{a_{\text{moon}}} = \frac{g}{\omega^2 R} = \left(\frac{R}{R_{\text{Earth}}}\right)^2$$

→ $a_{\text{apple}} \propto \frac{1}{(\text{dist. of apple from centre of Earth})^2}$
Same case for moon

↓
"There are universal laws which hold true in heaven and on Earth."

LEC-7

up hill now, Galileo → Huygens → Newton

Law of inertia (Newton's 1st law)

An object which does not have a force acting on it is either at rest or in a state of uniform velocity

Revolutionised the very way people thought of physics

but really we came up with first

Law of kinematics

Emphasised the role of time

⇒

The concept of time as an independent variable that helps describing motion of objects



Galileo

Uniform Circular motion

→ Huygens



Requires centripetal force

These were concepts known before Newton

Now comes the man himself →

Newton's 2nd Law



Newton's 3rd Law

Every action has an equal and opposite reaction.

$$\vec{F} = m\vec{a}$$

Describes the motion of every single moving body in the universe.

$$\vec{F}(\vec{r}) = m \cdot \frac{d^2 \vec{r}}{dt^2}$$



"Ordinary differential equation in modern language."

Ever since Newton, physicists solve stuff by making differential equations \Rightarrow Newton is our Aristotle lol

There are theorems regarding differential equations

→ Ordinary Diff. Eqn of n th order has ' n ' independent solutions

→ To obtain a unique solution, you need ' n ' initial conditions.

* Independent soln \rightarrow No linear combination of the two solns will be zero for every value in their domain

"Now after praising Newton so much let us look at the creativity he did" - Prof Uma Sankar

Looking at the eqn for 2nd law,

\vec{r} is only defined at a single point



CM of the body

But forces acting on surface of the body, not on CM

So what? $\vec{F} =$ Sum of forces acting on the body.

Even in law of gravity, when Newton described motion of Earth and Sun, he considered their entire mass at their CM



Later Newton proved that for all gravitational purposes, solid sphere \equiv point at CM

Moreover, another complication w/ IRL objects

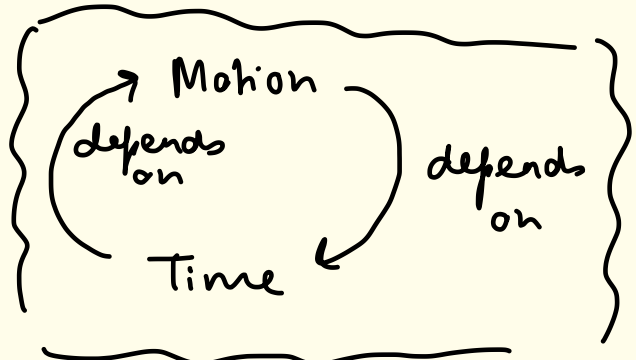


Solid objects rotate \Rightarrow Later solved by Euler.

Now, Newton's actual cheating

$$\vec{F}(\vec{r}) = \frac{d^2 \vec{r}}{dt^2}$$

$\frac{d^2}{dt^2} \rightarrow$ Time \Rightarrow measured by looking at motion of celestial objects



or motion of objects in an inertial frame

Circular argument

Newton just hacked the problem to pieces \rightarrow

Said there was 'Absolute time' which is independent of any motion

Now, we knew $\vec{F} = m\vec{a}$ true only in "inertial frames"

Newton simply declared that there exists 'Absolute space', and that any frame moving with constant velocity wrt that frame is hence inertial.

↓
what is that?

$$\vec{F}_{NI} = \vec{F}_{pseudo} + \vec{F}_{Real} = m\vec{a}_{NI}$$

Restoration
of Newton's law
for Non-inertial
frames

* Newton's law of gravity

$$\vec{F}_{gn} = -\frac{GMm}{r^2} \hat{r}$$

Important discovery because of Newton's Law

↓
Discovery of Uranus

on observation over a period of time, people realize Uranus was not moving in a Kepler orbit. So either

↓
Newton was wrong
(GOD PLEASE NO)

↓
there is another massive body very close to Uranus that affects its orbit of

⇓
found to be Neptune

LEC 8

Bernoulli \longrightarrow Brachistochrone problem

D'Alembert



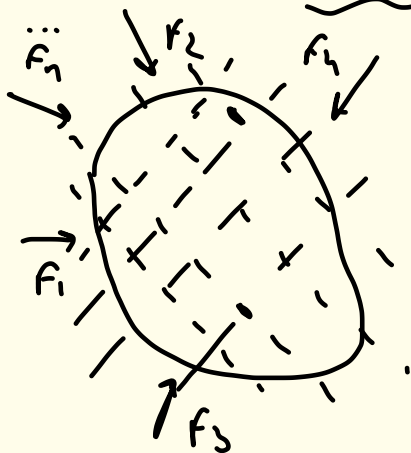
Euler }
Lagrange } $\longrightarrow *$

Hamilton

Find curve such that you could travel from A to B in the least amount of time.

Euler derived that Newton's 2nd law can be reduced to the following form

$$\vec{F}_{res} = M \left(\frac{d^2 \vec{r}_{cm}}{dt^2} \right)$$



$N (\gg 1)$ pieces

for i th piece \equiv point mass,

$$m_i \frac{d^2 \vec{r}_i}{dt^2} = \vec{f}_{i,ext} + \vec{f}_{i,int}$$

$$\therefore \sum m_i \frac{d^2 \vec{r}_i}{dt^2} = \sum \vec{f}_{i,ext} + \sum \vec{f}_{i,int}$$

$$\Rightarrow \frac{d^2}{dt^2} \left(\sum m_i \vec{r}_i \right) = \vec{F}_{res} \Rightarrow M \cdot \frac{d^2 \vec{r}_{cm}}{dt^2} = \vec{F}_{res}$$

$\underbrace{\qquad\qquad\qquad}_{M \cdot \vec{r}_{cm}}$

* Euler's theorem for motion of a rigid body

↓
Arbitrary motion
involves translation of
CM and rotation
about CM

$$m_i \frac{d^2 \bar{r}_i}{dt^2} = \bar{f}_i^{\text{ext}} + \bar{f}_i^{\text{int}}$$

$$\therefore \bar{r}_i \times m_i \frac{d^2 \bar{r}_i}{dt^2} = \bar{r}_i \times (\bar{f}_i^{\text{ext}} + \bar{f}_i^{\text{int}})$$

$$\bar{r}_i \times \frac{d}{dt} (m_i \bar{v}_i) = \bar{r}_i \times (\bar{f}_i^{\text{ext}} + \bar{f}_i^{\text{int}})$$

$$\bar{v}_i = \bar{\omega} \times \bar{r}_i = \bar{\omega} \times \bar{r}_i$$

↳ All particles have same $\bar{\omega}$

$$\therefore \bar{r}_i \times \frac{d}{dt} (m_i (\bar{\omega} \times \bar{r}_i)) = \bar{r}_i \times (\bar{f}_i^{\text{ext}} + \bar{f}_i^{\text{int}})$$

$$\bar{l}_i = \bar{r}_i \times \bar{p}_i$$

$$= \bar{r}_i \times (m_i \bar{v}_i)$$

$$\therefore \frac{d\bar{l}_i}{dt} = \frac{d\bar{r}_i}{dt} \times (m_i \bar{v}_i) + \bar{r}_i \times \frac{d}{dt} (m_i \bar{v}_i)$$

$$= \bar{r}_i \times m_i \left(\frac{d^2 \bar{r}_i}{dt^2} \right)$$

$$\frac{d\bar{L}}{dt} = \frac{d}{dt} \sum_i \bar{L}_i$$

$$= \frac{d}{dt} \sum \bar{r}_i \times (m_i \cdot \bar{\omega} \times \bar{r}_i)$$

$$= \frac{d}{dt} \left[\underset{\substack{\downarrow \\ I}}{(\cdot) \bar{\omega}} \right] = \sum_i \bar{r}_i \times (\bar{f}_{i, \text{ext}} + \bar{f}_{i, \text{int}})$$

$$= \underbrace{\sum_i \bar{r}_i \times \bar{f}_{i, \text{ext}}}_{\downarrow} + \sum_i \bar{r}_i \times \bar{f}_{i, \text{int}}$$

$$\frac{d\bar{L}}{dt} = \bar{\tau}_{\text{ext}}$$

All internal forces appear as action-reaction pairs
net moment of such pairs about any axis is zero

$$\textcircled{*} \bar{p} = m\bar{v}$$

$$\bar{L} = I\bar{\omega}$$

Are m & I similar quantities?

They appear to be so, but not really

\bar{p} & \bar{v} must be in same direction

\bar{L} & $\bar{\omega}$ may not be in same direction

Scalar \rightarrow Number

vector \rightarrow Set of 3 numbers

\rightarrow Components (which we then treat as scalars)

$$\begin{bmatrix} p_1 \\ p_2 \\ p_3 \end{bmatrix} = m \cdot \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \rightarrow \text{Tensor}$$

$$\begin{bmatrix} L_1 \\ L_2 \\ L_3 \end{bmatrix} = \begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} \begin{bmatrix} \omega_1 \\ \omega_2 \\ \omega_3 \end{bmatrix}$$

$$\begin{aligned} (3 \times 1) &= \text{scalar} \cdot (3 \times 1) \\ (3 \times 1) &= (3 \times 3) \cdot (3 \times 1) \end{aligned}$$

$$\vec{A} = A_1 \hat{u} + A_2 \hat{v} + A_3 \hat{z}$$

$$\vec{B} = B_1 \hat{u} + B_2 \hat{v} + B_3 \hat{z}$$

$$\begin{aligned} (\vec{A} \cdot \vec{B}) &= (A_1 \hat{u} + A_2 \hat{v} + A_3 \hat{z}) \cdot (B_1 \hat{u} + B_2 \hat{v} + B_3 \hat{z}) \\ &= \underbrace{A_1 B_1 \hat{u} \hat{u} + A_1 B_2 \hat{u} \hat{v} \dots}_{\downarrow} \Rightarrow 9 \text{ terms} \\ &\quad \text{Tensor (of order 2)} \end{aligned}$$

$$\otimes \text{ Young's Modulus} = \frac{\text{Stress}}{\text{Strain}}$$

$$\text{Strain} = \frac{\overline{\text{force}}}{\overline{\text{Area}}} \rightarrow \text{Impossible to take ratio of vectors}$$

$$\Rightarrow \overline{\text{force}} = (\text{Strain}) \overline{\text{Area}}$$

\downarrow
Tensor - 2

$$\text{Strain} = \frac{\overline{\text{Change in length}}}{\overline{\text{length}}} \Rightarrow \overline{\text{Change in length}} = \text{Strain} \cdot \overline{\text{length}}$$

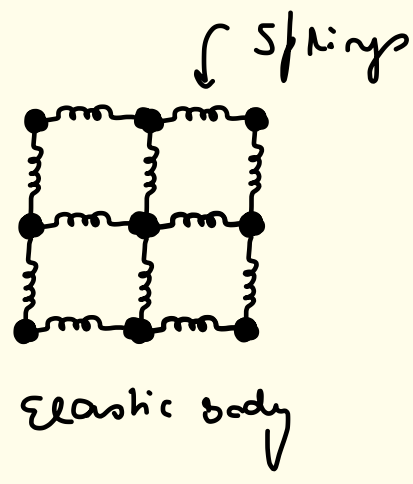
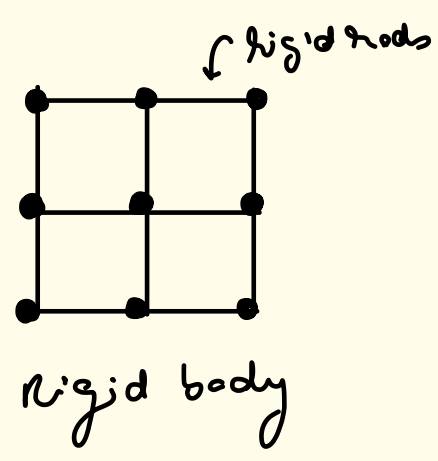
\uparrow
Tensor - 2

$$\text{Similarly, Stress} = (\underbrace{\quad}_{\downarrow \text{Tensor of order 4}} \underbrace{\quad}_{\downarrow \text{T-2}}) \cdot \text{Strain}$$

\downarrow
T-2

Rigid body \rightarrow No matter how it moves, the distance b/w any two mass points on a rigid body remains constant.

But all solids do deform sooner or later, so what happens when these points translate wrt each other/ the distance b/w them changes



* Index notation
 $\bar{A} = A_i$ ($i=1,2,3$)
 implicit

Strain tensor \rightarrow fn of position of mass point

$$g_{ij}(u)$$

Related to non-Euclidean geometry

Eucl. geo $\rightarrow ds^2 = [dx \ dy \ dz] \begin{bmatrix} dx \\ dy \\ dz \end{bmatrix}$

Non Eucl. geo $\rightarrow [dx \ dy \ dz] \cdot f(x) \begin{bmatrix} dx \\ dy \\ dz \end{bmatrix}$

In Euclidean geometry, displacement is irrespective of where the point initially was

In non Euclidean geometry, even the displacement is a function of the position of the point

LEC 9

Fluid Dynamics

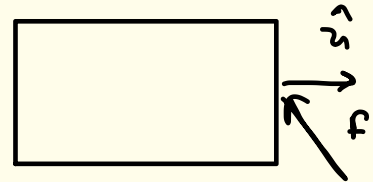
Technical defⁿ of a fluid

↓
Fluids can't support shear stress

$$\vec{F} = [\sigma] \vec{A}$$

$$\begin{bmatrix} F_1 \\ F_2 \\ F_3 \end{bmatrix} = \begin{bmatrix} \sigma_{11} & \cdot & \cdot \\ \sigma_{21} & \cdot & \cdot \\ \sigma_{31} & \cdot & \cdot \end{bmatrix} \begin{bmatrix} A \\ 0 \\ 0 \end{bmatrix}$$

Area having only one component



Shear stress

⇒ Component of stress due to force applied perpendicular to area

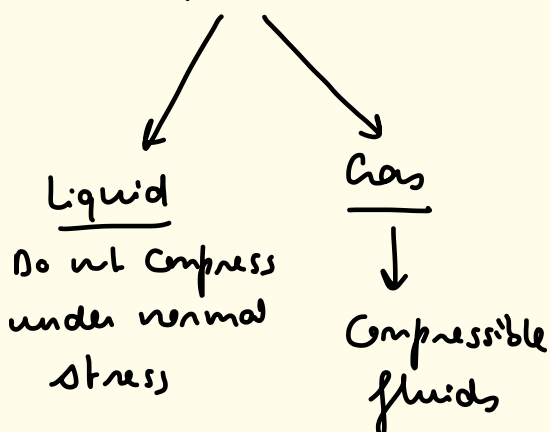
$$\sigma_{11} \rightarrow F_1 (\Rightarrow) A_1$$

$$\sigma_{21} \rightarrow F_2 (\Rightarrow) A_2$$

$$\sigma_{31} \rightarrow F_3 (\Rightarrow) A_3$$

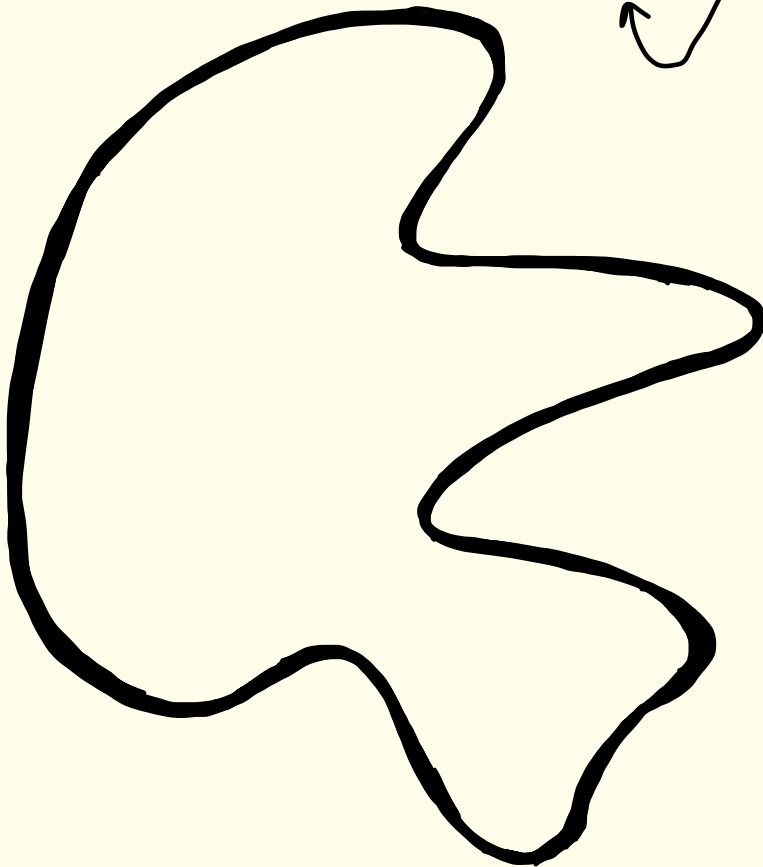
... and so on

Fluids



Formalism for fluid mechanics \rightarrow Defines a macroscopic body of fluid called a continuum

No gaps in between



* Transcendental no.s



No.s which cannot be obtained as the root of an algebraic eqn

No. of integers
III

No. of fractions
III

(No. of algebraic no.s)

obtained as root of alg. eqn

Integers, fractions, surds
 \mathbb{Z}
Even: rationals

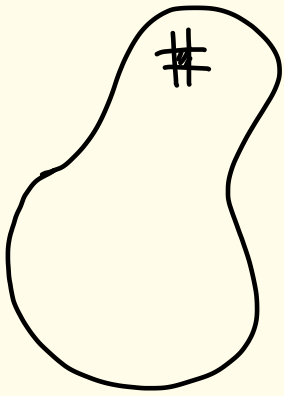
However,

No. of transcendental no.s

All of these



Real no. line is filled with transcendental numbers.



Taking a volume element

↓
 $d^3 u_i$
 with mass

$$dm_i = \rho(u_i) d^3 u_i$$

velocity pattern
 of fluids
 ↓
 $\vec{v}(u, y, z)$

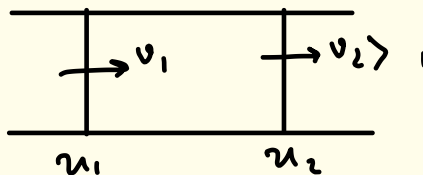
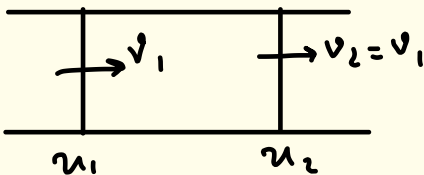
$$V = \int d^3 u$$

$$M = \int \rho(u) d^3 u$$

for simplicity's
 sake, let us
 assume there is →
 no explicit dependence
 of velocity of time

No change in
 flow pattern
 with time
 ↓

Steady State
 flow



Considering no
 leaks/loss/gain
 of water

perhaps there is somehow
 a source of water in the pipe

relⁿ blow surface
 integral of velocity field
 and its source

any function
 depending on
 spatial coordinates

closed surface $\oint_S \vec{v} \cdot d\vec{A} = (v_2 - v_1) A > 0$ (so is the claim)

Physics - Matter cannot be created or destroyed (c. ages ago - 1930ish)

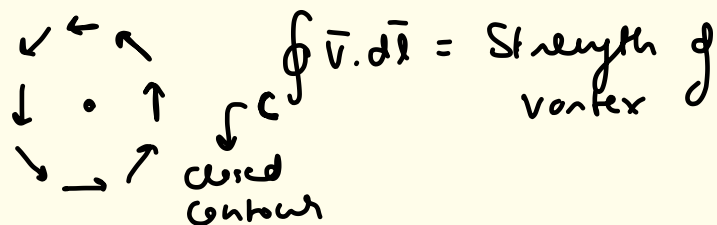
Mass flowing out of the volume is greater than mass flowing into the volume

\therefore our velocity flux is related somehow to strength of source pumping water into the canal

Physical action causing such motion

we see this in E&M

* Vortex



Here, we abruptly end our conversation on fluid mechanics and jump into...

\therefore Integrals of a vector field over a closed loop or surface contain crucial physical info about what produces it.

Electricity and Magnetism

$$\vec{F}_{12} = \left(\frac{1}{4\pi\epsilon_0} \right) \frac{q_1 q_2 (\vec{r}_1 - \vec{r}_2)}{|\vec{r}_1 - \vec{r}_2|^3}$$

$$\vec{F}_{21} = -\vec{F}_{12}$$

↓
force on q_1 due to q_2

Similarly, Ampere's law for force b/w closed loops

Newton said - figure out what the force is, then figure out the movement caused by such forces



both Coulomb

& Ampere work

their eqns in

terms of force

→ Under Newton's influence

But Faraday's POV



If there is q_2 at \vec{r}_2 ,

then Electric field \vec{E}_1 at

\vec{r}_1 is given as follows

$$\vec{E}_1 = \left(\frac{1}{4\pi\epsilon_0} \right) \frac{q_2 (\vec{r}_1 - \vec{r}_2)}{|\vec{r}_1 - \vec{r}_2|^3}$$

If there happens to be a charge q_1 at \vec{r}_1 ,

then force on $q_1 = q_1 \cdot \vec{E}_1(\vec{r}_1)$

LEC - 10

Concept of field introduced by Faraday

Usefulness → Allowed us to think of electrostatic forces as a charge somehow interacting with an 'aura' produced by a 'source' charge

thanks to fluid mech,
we had vast amt of mathematical machinery to deal with these kinds of problems

Similarly, a magnetic field was also defined

$$d\vec{B}(\vec{r}_1) = \frac{\mu_0}{4\pi} \cdot \frac{I_2 \cdot d\vec{l}_2 \times (\vec{r}_1 - \vec{r}_2)}{|\vec{r}_1 - \vec{r}_2|^3}$$



'Ampere' produced at \vec{r}_1 due to tiny length of $d\vec{l}_2$ carrying current I_2 located at \vec{r}_2 .

$$d\vec{F}_{12} = I_1 \cdot d\vec{l}_1 \times d\vec{B}(\vec{r}_1)$$

↳ This formulation of magnetic force on current elements doesn't satisfy Newton's third law \Rightarrow Small current elements do not exist in physical reality, current always flows in loops



Integrating this expression over the loop results in equal and opposite forces on both bodies

We know source \Rightarrow field

But also, field \Rightarrow source

"Given a field on a surface, how can we figure out the sources?"

Necessary mathematical machinery \rightarrow Calculus of fields

Field = some physical quantity whose value is a function of its location.

for a fn in two variables $f(x, y)$,

$$\begin{aligned}\Delta f &= f(x+\Delta x, y+\Delta y) - f(x, y) \\ &= \underbrace{f(x+\Delta x, y+\Delta y) - f(x+\Delta x, y)}_{\frac{\partial f}{\partial y} \cdot \Delta y} \\ &\quad + \underbrace{f(x+\Delta x, y) - f(x, y)}_{\frac{\partial f}{\partial x} \cdot \Delta x}\end{aligned}$$

now, for single variable fn $g(x)$,

$$\Delta g = \frac{dg}{dx} \Delta x$$

similarly, we can argue there must be a similar relⁿ b/w Δf & $\Delta \vec{r}$

$$\text{i.e. } \Delta f = \vec{\nabla} f \cdot \Delta \vec{r}$$

$\vec{\nabla}$ del operator

$$\vec{\nabla} f = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j}$$

$$\Delta \vec{r} = \Delta x \hat{i} + \Delta y \hat{j}$$

$$\therefore \Delta f = \frac{\partial f}{\partial x} \Delta x + \frac{\partial f}{\partial y} \Delta y$$

$$\vec{\nabla} = \hat{i} \cdot \frac{\partial}{\partial x} + \hat{j} \cdot \frac{\partial}{\partial y}$$

Differential operator

Takes one f^n as input and gives another function as output

How does del operator work on vector fields?

Considering a vector field $\vec{V} = v_1 \hat{x} + v_2 \hat{y} + v_3 \hat{z}$

$$\nabla \vec{V} = \left(\hat{x} \frac{d}{dx} + \hat{y} \frac{d}{dy} + \hat{z} \frac{d}{dz} \right) (v_1 \hat{x} + v_2 \hat{y} + v_3 \hat{z})$$

→ Tensor-2

$$\nabla \cdot \vec{V} = \frac{dv_1}{dx} \hat{x} + \frac{dv_2}{dy} \hat{y} + \frac{dv_3}{dz} \hat{z} \rightarrow \text{Divergence}$$

$$\nabla \times \vec{V} = \text{~~~~~} \rightarrow \text{Curl}$$

our jump → Divergence and curl are "sources" of a vector field

Helmholtz theorem - If divergence & curl of a vector field are known, then the vector field can be reconstructed provided the field vanishes as $\frac{1}{r^2}$ as $r \rightarrow \infty$ (or any higher exponent)

Electrostatic field

→ \vec{E} remains constant

w/ time.

$$\oint_S \vec{E} \cdot d\vec{A} = \frac{Q_{in}}{\epsilon_0}$$

$$\rightarrow \frac{1}{\epsilon_0} \int_V \rho(\vec{r}) dV$$

$$\int_V \left(\nabla \cdot \vec{E} - \frac{\rho(\vec{r})}{\epsilon_0} \right) dV = 0$$

Gauss Thm →
Gauss law

$$\oint_S \vec{E} \cdot d\vec{A} = \int_V (\nabla \cdot \vec{E}) dV$$

True for any arbitrary vector field

Vanishes for arbitrarily small closed loop
↓
only if integrand vanishes

$$\boxed{\therefore \nabla \cdot \bar{E} = \frac{\rho(\vec{r})}{\epsilon_0}}$$

\Rightarrow Divergence of electric field at a point

\propto Charge density at that point

By similar argument,

$$\boxed{(\nabla \times \bar{B}) = \mu_0 \cdot \bar{J}(\vec{r})}$$

(By Stokes' Theorem)

LEC-11

Two thems of vector calculus

\rightarrow Gauss' Theorem -
$$\oint_S \bar{v} \cdot d\bar{A} = \int_V \nabla \cdot \bar{v} dV$$

\rightarrow Stokes' Theorem -
$$\oint_C \bar{v} \cdot d\bar{l} = \int_S (\nabla \times \bar{v}) \cdot d\bar{A}$$

} True for any arbitrary vector field

$$\nabla \cdot \bar{E} = \frac{\rho(\vec{r})}{\epsilon_0}$$

$$\nabla \times \bar{E} = 0 \quad (\text{for electrostatic field})$$

$$\nabla \cdot \bar{B} = 0$$

$$\nabla \times \bar{B} = \mu_0 \bar{J}(\vec{r})$$

Two more thems of vector calculus

$\rightarrow \nabla \times \nabla \phi(\vec{r}) = 0$

\downarrow
curl of gradient of any scalar field is zero

$\rightarrow \nabla \cdot (\nabla \times \bar{v}(\vec{r})) = 0$

\downarrow
Divergence of curl of any arbitrary vector field is zero.

We know

$$\nabla \times \bar{E} = 0 \rightarrow \text{Def'n of potential}$$

$$\therefore \bar{E} = -\nabla \cdot \phi(\vec{r})$$

$$\nabla \cdot (-\nabla \cdot \phi(\vec{r})) = \frac{\rho(\vec{r})}{\epsilon_0}$$

$$\Rightarrow \boxed{\frac{\rho(\vec{r})}{\epsilon_0} = -\nabla^2 \phi(\vec{r})}$$

our beloved 2nd order differential eqn just like Newton

Poisson's Equation

Also,

$$\bar{\nabla} \cdot \bar{B} = 0$$

$$\therefore \bar{B} = \bar{\nabla} \times \bar{A} \rightarrow \text{Some vector field}$$

$$\nabla \times (\nabla \times \bar{A}) = \mu_0 \bar{J}(\vec{r})$$

$$= \nabla(\nabla \cdot \bar{A}) - \nabla^2 \bar{A}$$

↓ ∂
"Throat me
bro"
- Prof

$$\boxed{\mu_0 \bar{J}(\vec{r}) = -\nabla^2 \bar{A}(\vec{r})}$$

How to solve Poisson's eqn → Analogue w/ Newton's 2nd law

$$\frac{d^2 u}{dt^2} = \frac{f(u)}{m}$$

we need

$u(0), \dot{u}(0)$ → Condition at initial pt

To get a unique eqn

$$\left\{ \begin{array}{l} \text{or} \\ u(0), u(T) \\ \dot{u}(0), \dot{u}(T) \end{array} \right\}$$

Conditions at boundary pts

$$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2}$$

$$= -\frac{\rho(\vec{r})}{\epsilon_0}$$

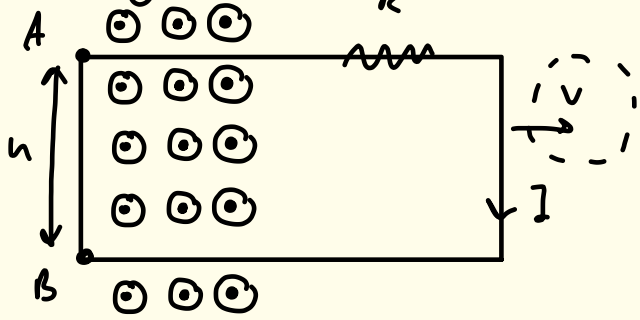
Boundary Cond's →

In two dimensions, we need to specify conditions over a closed contour to get a unique soln (can extend to 3D)

↓
Dirichlet generalised this concept over higher dimensions

LEC-12

Talking this experimental setup



when wire is moved with velocity \vec{v} , a current starts flowing through the wire



what causes this charge flow?



Lorentz force

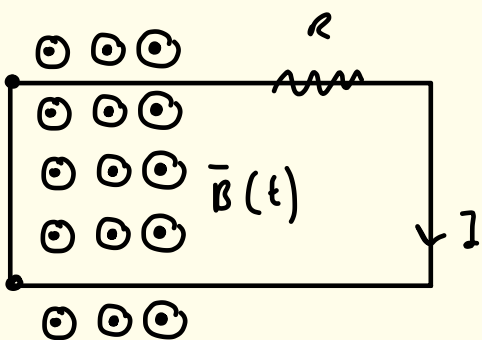
$$\begin{aligned} \vec{F}_{\text{Lor}} &= q(\vec{v} \times \vec{B}) \\ &= q(v\hat{v} \times B\hat{z}) \\ &= -qvB\hat{y} \end{aligned}$$

$$\text{EMF (potential diff)} = \int_A^B \frac{\vec{F}}{q} \cdot d\vec{l} = \left. \begin{aligned} &= vBh \\ &= \frac{dl}{dt} \cdot B \cdot h \\ &= B \cdot \frac{dA}{dt} \end{aligned} \right\} \text{ignoring signs}$$

$$\text{EMF} = -\frac{d\Phi_B}{dt}$$

Lenz's law

However, now talking experimental setup

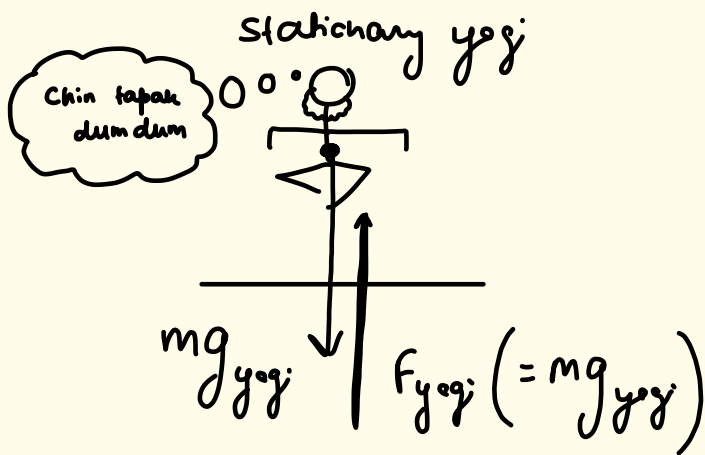
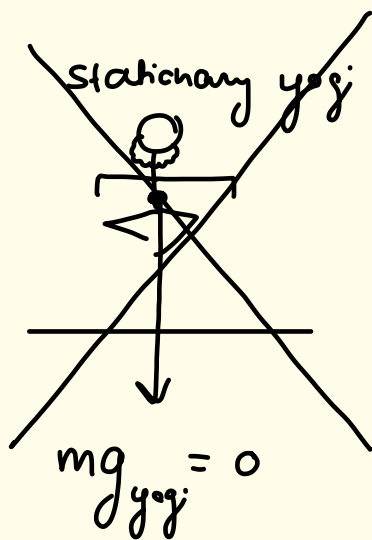


a similar but different

magnetic field is taken as a function of time.

current flows through the wire. what is the force that causes the current to flow?

Faraday's proposal



Faraday merely concluded that the force causing charges to move inside the wire is produced by the changing magnetic field.

↓
 This changing magnetic field produced an induced electric field that applied force on charges inside the wire

$$\oint_C \vec{\epsilon} \cdot d\vec{l} = \int_A (\nabla \times \vec{\epsilon}) \cdot d\vec{a} = -\frac{d}{dt} [\vec{B} \cdot \vec{A}]$$

↙ Area vector

$$= \int_A -\frac{d\vec{B}}{dt} \cdot d\vec{a}$$

$$\therefore \int_A (\nabla \times \vec{\epsilon} + \frac{d\vec{B}}{dt}) \cdot d\vec{a} = 0 \Rightarrow \boxed{\nabla \times \vec{\epsilon}_{ind} = -\frac{d\vec{B}}{dt}}$$

Slight cheating but they Faraday's Law

Meanwhile, $\nabla \cdot \bar{\epsilon}_{ind} = 0$

Static electric field \rightarrow Non-zero divergence but zero curl

Induced electric field \rightarrow Non-zero curl but zero divergence



Resembles magnetic field

$$\bar{\epsilon} = \bar{\epsilon}_{ind} + \bar{\epsilon}_{stat}$$

$$\nabla \cdot \bar{\epsilon} = \nabla \cdot \bar{\epsilon}_{stat} = \frac{\rho}{\epsilon_0}$$

$$\nabla \times \bar{\epsilon} = \nabla \times \bar{\epsilon}_{ind} = -\frac{\partial \mathbf{B}}{\partial t}$$

Now,

$$\nabla \times \bar{B} = \mu_0 \bar{J}$$

$$\nabla \cdot (\nabla \times \bar{B}) = \mu_0 \nabla \cdot \bar{J} = 0$$

Must necessarily be true \Rightarrow divergence of a curl is zero

However, $\nabla \cdot \bar{J}$ is only zero when \bar{J} is independent of time \Rightarrow Ampere's law doesn't hold for time varying \bar{J} .

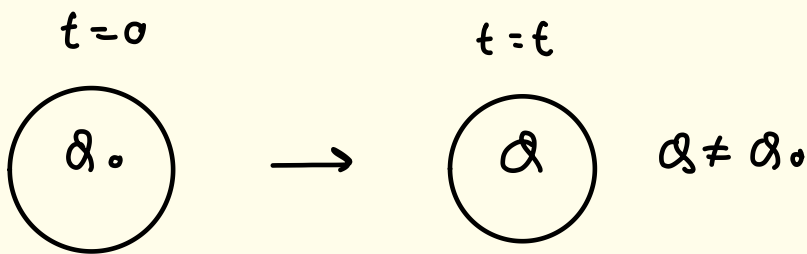
Maxwell's modification

$$\nabla \times \bar{B} = \mu_0 (\bar{J} + \bar{J}_0)$$

\downarrow
"unfortunate name"
Displacement current

$$\nabla \cdot \bar{J} + \nabla \cdot \bar{J}_0 = 0$$





$$\therefore \frac{dq}{dt} + \int \bar{J} \cdot d\bar{A} = 0$$

$$\frac{d}{dt} \int \rho \cdot dV + \int_V (\nabla \cdot \bar{J}) dV = 0$$

$$\Rightarrow \int_V \left(\nabla \cdot \bar{J} + \frac{d\rho}{dt} \right) dV = 0 \rightarrow \text{As it holds for arbitrarily small volumes,}$$

$$\nabla \cdot \bar{J}_0 + \frac{d}{dt} (\epsilon_0 \cdot \nabla \cdot \bar{E}) = 0$$

$$\nabla \cdot \bar{J}_0 + \frac{d\rho}{dt} = 0$$

$$\Rightarrow \nabla \cdot \left(\bar{J}_0 + \epsilon_0 \frac{d\bar{E}}{dt} \right) = 0$$

$$\therefore \bar{J}_0 = \epsilon_0 \frac{d\bar{E}}{dt}$$

\Rightarrow

$$\therefore \nabla \times \bar{B} = \mu_0 \bar{J} + \mu_0 \epsilon_0 \frac{d\bar{E}}{dt}$$

Meanwhile Faraday's manipulations were far more imaginative

\hookrightarrow Gave rise to a new kind of \bar{E} which resembles \bar{B} rather than regular static \bar{E}

Maxwell's manipulation



We get 'same kind' of $\bar{B} \Rightarrow \nabla \cdot \bar{B} = 0$

$$\nabla \times \bar{B} = \text{something}$$

Just the value changes

Imagination starts new



In a space, there exists

$$\begin{matrix} \bar{E}(\bar{r}, t) \\ \bar{B}(\bar{r}, t) \end{matrix} \left[\begin{matrix} \rho=0 \\ \bar{J}=0 \end{matrix} \right] \text{ in immediate environment}$$

$$\nabla \times \bar{E} = -\frac{d\bar{B}}{dt}$$

$$\nabla \times \bar{B} = \mu_0 \epsilon_0 \frac{d\bar{E}}{dt}$$

$$\nabla \times (\nabla \times \bar{E}) = -\nabla \times \left(\frac{d\bar{B}}{dt} \right)$$

$$= -\frac{d}{dt} (\nabla \times \bar{B})$$

$$= -\mu_0 \epsilon_0 \frac{d^2 \bar{E}}{dt^2}$$

$$\nabla(\nabla \cdot \bar{E}) - \nabla^2 \bar{E}$$

$$\begin{matrix} 0 \\ (\rho=0) \end{matrix}$$

$$\nabla^2 \bar{E} = \mu_0 \epsilon_0 \frac{d^2 \bar{E}}{dt^2}$$

Now, it's one dimensional analog

$$\frac{d^2 f}{dx^2} = \frac{1}{v^2} \frac{d^2 f}{dt^2} \rightarrow \text{wave eqn in one dimension}$$

Describes a wave w/
wave function \bar{E} moving
with speed $\frac{1}{\sqrt{\mu_0 \epsilon_0}} = c$

Imagination



Light is an electromagnetic wave consisting of \bar{E} & \bar{B} moving at speed c

Maxwell proved his leap in imagination by deriving laws of reflection and refraction from electromagnetic equations

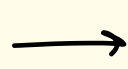


Maxwell's next leap in imagination



There exist other kinds of EM waves other than (visible) light

having their own wavelength & frequency



Radiowaves

Produced by Hertz

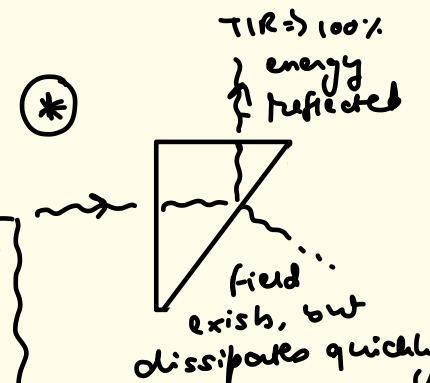
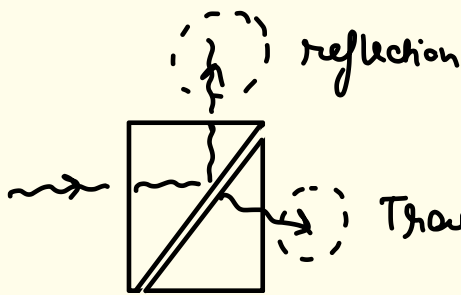
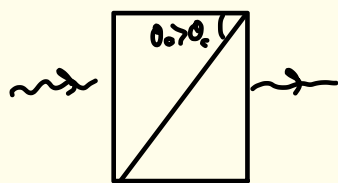
Earlier accepted to be empirical laws



Eqns derived purely from a large number of observations

Soon enough, microwaves were discovered

Experimented on by J.C. Bose → (crucial in proving Maxwell's split)



wave eqn in the form of derivatives
 ↓
 fields must be continuous at all points

Consequence of reqⁿ of the fields to be continuous
 ↓
 No energy propagation

LEC-13

Maxwell's EM Theory

→ Ampere's law is not consistent with local charge conservation

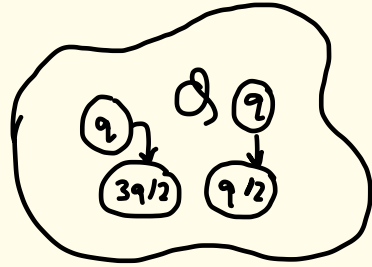
→ formulation of displacement current

However, charge conservation is also applicable in infinitesimally small volumes

↓
locality

⇓

We can trace the path of movement of a charge.



Charge conservation in large volume

In regions of $\rho=0, \vec{J}=0,$

\vec{E}, \vec{B} satisfy

$$\frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2} - \nabla^2 \vec{E} = 0$$

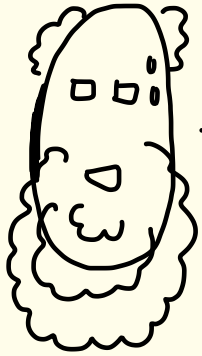
~~~~~  
wave eqn

⇒ light is an EM wave

↓

Lots of people weren't comfy with this idea

Up till that point, every wave had a medium it propagated in, so what medium did light propagate through?



Umm... there is a medium, it's called...  
Aether... yep... \*hods\*

So tenuous that it passes through all living matter

Such strong mechanical properties that it could transmit a wave of speed of the order  $10^8 \text{ms}^{-1}$



Yeah... of course... what? Why doesn't that make sense? It makes sense, trust me bro...

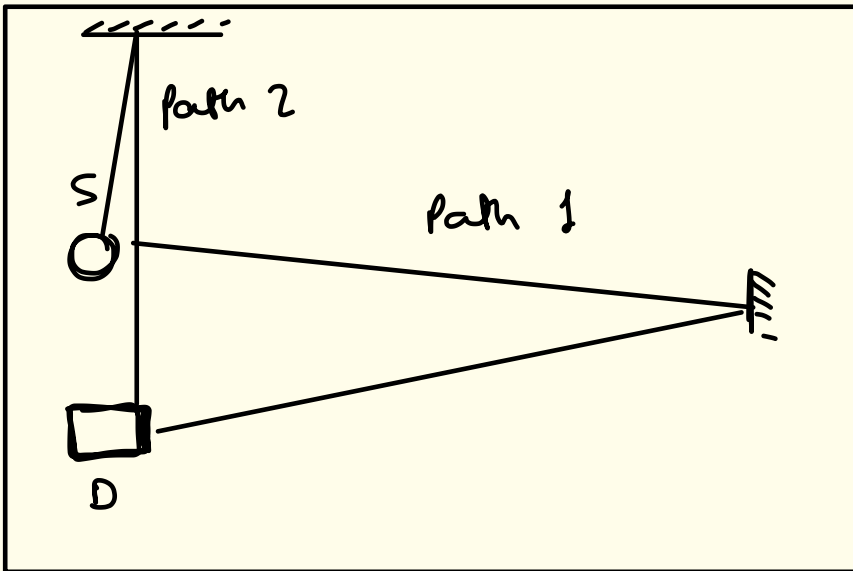
Scientists trusted the bro

Now, how to detect this Aether thing?



Michelson  
Experiment





Path 1  $\perp$  Path 2

$$l_1 = l_2$$

↓

Constructive interference should occur at detector

Some people argued  
 ↳ orient path 1 along motion of the Earth

Speed of travelling light in path 1 would be disturbed by movement of Earth, we wouldn't get perfectly constructive interference, there would be some fringe shift

↓  
 revolution of Earth around sun  
 ( $v_{orb} \gg v_{rot}$ )

Expected  $\rightarrow 0.4$  fringes  $\rightarrow \pm 0.1$  observed  $\rightarrow 0$

over the years, Michelson improved his experiment

Expected  $\rightarrow 40$   
 $\approx$  Error  $\rightarrow \pm 0.1$  observed  $\rightarrow 0$

So what is happening with Aether?



Uhh well actually-

Shut up you're dead now

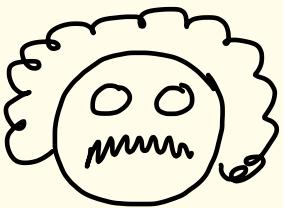
Proposed explanation - Lorentz - Fitzgerald Contraction



Could explain Michelson's results, but not further experiments

← 'Lengths along direction of motion are contracted'

But then came the man, the myth, the one and only...



No Aether lol

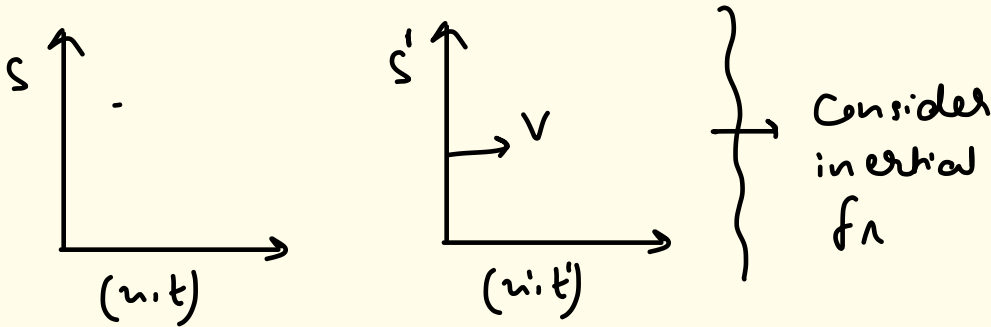
Why try to forcibly make sense of something that doesn't make sense?

Concept of inertial frame  $\rightarrow$  laws of physics should have same form in two different frames moving with constant relative velocity

$\Downarrow$   
 Unrigorous version of what Einstein stated

Another way to state Newton's 1st Law

## Galilean Relativity



$$u' = u - vt$$

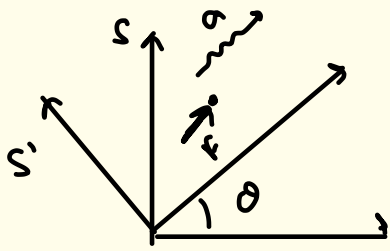
$$\begin{aligned} \vec{F} &= m\vec{a} \\ \vec{F}' &= m\vec{a}' \end{aligned}$$

Force wouldn't change

Acceleration is seen as the same in the two frames  $\rightarrow$

$\vec{a}$  remains constant on transformation from S to S', just like  $\vec{F}$

$\otimes$   $\vec{F}$  &  $\vec{a}$  are invariant under Galilean transformations



$$x' = x \cos \theta + y \sin \theta$$

$$y' = -x \sin \theta + y \cos \theta$$

$$\bar{F} = m a_x \hat{i} + m a_y \hat{j}$$

$$\bar{F}' = m a'_x \hat{i}' + m a'_y \hat{j}'$$

⊛  $\bar{F}$  &  $\bar{a}$  are  
covariant  
 under  
 rotation

$\bar{F} \rightarrow \bar{F}'$   
 $\Downarrow$  same transformation

$$a_x \leftrightarrow a'_x$$

$$a_y \leftrightarrow a'_y$$

Now, looking at  $\Sigma \Delta M$  eqns

$$\nabla \cdot \bar{E} = \frac{\rho}{\epsilon_0}$$

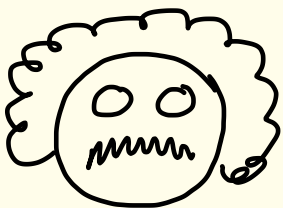
$$\nabla \times \bar{E} = -\frac{\partial \bar{B}}{\partial t}$$

$$\nabla \cdot \bar{B} = 0$$

$$\nabla \times \bar{B} = \mu_0 \left[ \bar{J} + \epsilon_0 \frac{\partial \bar{E}}{\partial t} \right]$$

Under rotations,  
 they are covariant

However, under  
 Galilean transformations,  
 they are neither  
invariant nor covariant!



Why y'all  
 be worried  
 'bout some  
 stupid ass  
 ether

Einstein pointed  
 out this very  
 crisis

How does Einstein solve this crisis? Stay tuned,  
we shall be back after a short (2 weeks) break

LEC-14

## Theory of Relativity

Arose from conflict b/w Newton's first law and

EM theory

↓  
Neither invariant  
nor covariant under  
Galilean transformation

↓  
Laws of Physics  
should have the  
same form in all  
inertial frames  
of reference

Newton defined inertial frames in terms of an  
"absolute space" → critiqued by Mach

⇓  
⊛ Foucault's pendulum  
People solved problems by  
considering a frame attached  
to Earth as a good enough  
approximation for absolute  
space

However, Foucault argued...



Objects on surface of Earth affected by acceleration  
(due to Earth's rotation)

→ Centrifugal force

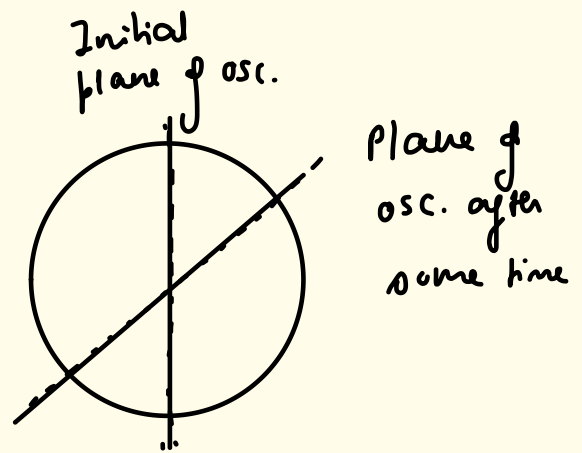
→ Coriolis force

Foucault argued we should start seeing effects of Coriolis force with a large enough pendulum over a large enough time period



Turned out to be true

Earth is a rotating frame

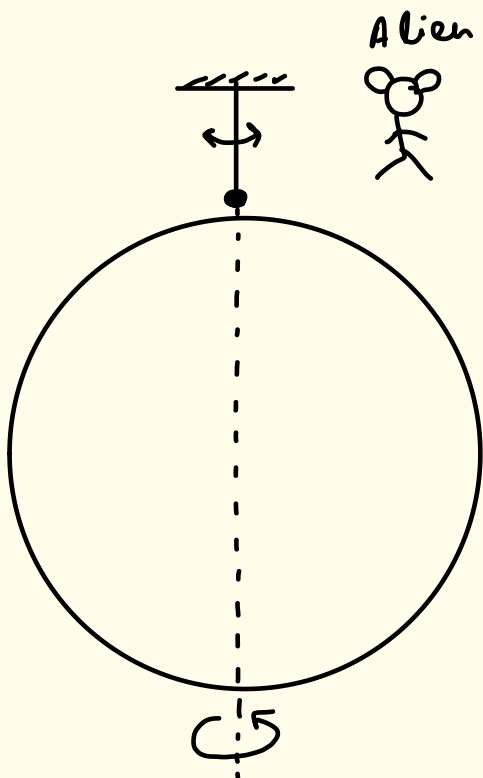


Time period of revolution of plane =  $24 \text{ hrs} \times \sin \lambda$

Time period of revolution of plane of osc. = 24 hrs

But an alien present in a coordinate system such that it sees the Earth's rotation observes the plane of oscillation as constant.

↳ How does the pendulum 'know' to keep its pl. of osc. constant?



## Galilean Transf

$$\rightarrow x' = x - vt$$

$$\rightarrow y' = y$$

$$\rightarrow z' = z$$

$$* \rightarrow t' = t$$

Can be shown that EM forces change on Galilean transformation.

Woldemar Voigt found a transformation such that EM eqns were invariant

$$\rightarrow x' = x - vt$$

$$\rightarrow y' = \frac{y}{\gamma}$$

$$\rightarrow z' = \frac{z}{\gamma}$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

Others who worked on this problem



Fitzgerald

Lorentz

Poincaré

$$\rightarrow t' = t - \frac{vx}{c^2} \quad \text{why?}$$

Recalling the electromagnetic wave eqn,

$$\mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} = \nabla^2 \cdot \vec{E}$$

Now, if there was an observer moving at speed  $c$ , it is logical to assume that they see a static solution  $\rightarrow$  however, no static soln exists for  $\vec{E}$ .

Einstein did similar math to Voigt and came up w/ same soln  $\rightarrow$   $t' \neq t$

Examining the consequences of such a revelation, Einstein published two papers on special relativity.

$$\begin{array}{l} \text{1st: } x' = \gamma(x - vt) \\ \underline{\underline{y' = y}} \\ z' = z \\ t' = \gamma\left(t - \frac{vx}{c^2}\right) \end{array} \left. \vphantom{\begin{array}{l} \text{1st: } x' = \gamma(x - vt) \\ \underline{\underline{y' = y}} \\ z' = z \\ t' = \gamma\left(t - \frac{vx}{c^2}\right) \end{array}} \right\} \rightarrow \text{Lorentz transformations}$$

↓  
name given  
first by Poincaré

2nd:  $E = mc^2$

Einstein did have two postulates, the acceptance of which allows us to derive any relativistic phenomena

→ The laws of physics must have the same form in all inertial frames (i.e. covariant)

→ Speed of light is constant in all inertial frames.

# LEC-16

for  $\underline{c \rightarrow \infty}$ , Lorentz Transf<sup>n</sup>  $\rightarrow$  Galilean Transf<sup>n</sup>

$v \ll c \rightarrow$  True for most day to day scenarios

But in Einstein's 2nd postulates, how does the speed of light suddenly pop up?

↓  
People had other points of view that tried to do away with Einstein's 2nd postulate

Eqs linking  $x'$  to  $x$  &  $t'$  to  $t$

$\rightarrow$  Proposed replacement

↓  
{ Transformation equations should form a group

↓  
This postulate implies the existence of a universal velocity

$\rightarrow$  Universal velocity unmeasurably large

↓  
Galilean Transf<sup>n</sup>

$\rightarrow$  universal velocity =  $c$

↓  
Lorentz Transf<sup>n</sup>

\* However, there must always be a time delay while making a measurement  
 $\Rightarrow$  we get different values in the same frame  
↓  
we assume there to be an infinite number of observers located at every point in spacetime, all with synchronised clocks

- Confusing shit about special relativity
- Time dilation → Pole-vaulters paradox
  - Length contraction → Loss of Simultaneity
  - Twin Paradox

\* Lorentz invariant interval

$$(\Delta s)^2 = c^2 (\Delta t_{2,1})^2 - (\Delta x_{2,1})^2$$

±ve if  $c|\Delta t_{2,1}| > |\Delta x_{2,1}|$

Symbol  
to denote  
RHS

↳ Not always  
true

Looking at Lorentz transf<sup>n</sup>,

$$x' = \gamma(x - vt)$$

$$t' = \gamma\left(t - \frac{vx}{c^2}\right)$$

$v$  → speed of signal  
b/w events 1 & 2

⇒ Any events in universe

$$= \left| \frac{\Delta x_{2,1}}{\Delta t_{2,1}} \right| < c \quad \text{if } LTI > 0$$

⇒ Light pulse transmitted from one event to another

$$= c \quad \text{if } LTI = 0$$

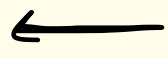
$$> c \quad \text{if } LTI < 0$$

↳ Events 1 and 2 are 'disconnected'

↓  
i.e. no causal connection

Causal Connection  
↓  
One event occurred due to another event occurring

\* If events are causally connected, LTI must be positive. Inverse not necessarily true



## LEC-17

### Length Contraction

$L =$  proper length  
↓  
length of a  
rod with a  
frame where it  
appears at  
rest

$$L_{\text{moving}} = \frac{L}{\gamma}$$
$$\gamma = \frac{1}{\sqrt{1 - v^2/c^2}}$$

Time Dilation → can be applied only in very  
specific circumstances



Event 1: first Hch  
 $(x_1, t_1), (x'_1, t'_1)$

Event 2: 2nd Hch  
 $(x_2, t_2), (x'_2, t'_2)$

$$\Delta t'_{21} = \gamma \left( \Delta t_{21} - \frac{v}{c^2} \Delta x_{21} \right)$$

$$\Delta x_{21} = 0$$

$$\Delta x'_{21} = x'_2 - x'_1$$

$$\Delta t_{21} = T$$

$$\Delta t'_{21} = T'$$

$$\therefore T' = \gamma T$$

\* Works only when  $\Delta x_{21} = 0$   
i.e. the time interval b/w  
two events is dilated in any  
other frame only when  
the two events occur at the  
same spatial position in  
some frame

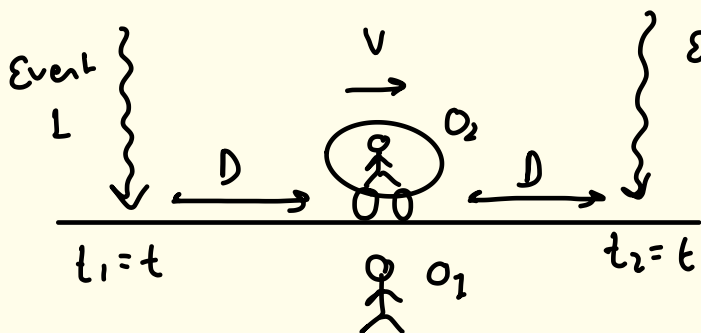
\* Whenever  $LI > 0$  b/w two events, then there exists a frame where the two events occur at the same spatial position i.e.  $\Delta x_{21} = 0$ . In such a frame, the period b/w the two events would be minimum

$\Rightarrow$  In any other frame,  
 $\Delta t'_{21} = \gamma \Delta t_{21}$  Always  $> 1$

As  $\Delta t'_{21}$  &  $\Delta t_{21}$  always have the same sign, the occurrence of the two events is always in the same order in every frame of reference

Demonstration of time dilation  
 ↓  
 Penetrating component of cosmic rays

\* It is impossible to truly say that two spatially separated events are 'simultaneous'



Event 2  $\Delta x = 2D$   
 $\Delta t = 0$   
 $\therefore LI < 0$



$O_1$  in stationary frame sees events occurring simultaneously  
 $O_2$  in moving frame sees Event 2 occurring first  
 Other observers see Event 1 first

When  $LI < 0$ , the order of events depends on the reference frame

⊛ Pole vaulters paradox & Twin paradox → HC Verma



# LEC-18

Some further topics to be discussed

→ Non-invariance / Covariance of Newton's 2nd law on Lorentz transformations



Discussion  
of energy and  
momentum

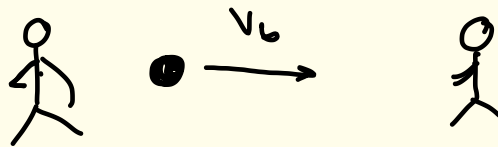
→ velocity addition

Lorentz transformations

$$\Delta x' = \gamma (\Delta x - v \Delta t)$$

$$\Delta t' = \gamma \left( \Delta t - \frac{v \Delta x}{c^2} \right)$$

Imagine



wrt frame at rest,

$$v_b = \frac{\Delta x}{\Delta t}$$

wrt frame moving with speed  $v$ ,

$$v_b' = \frac{\Delta x'}{\Delta t'}$$

$v_b' = f(v_b, v)$  such that if  $v_b = c$ ,  $v_b' = c$

↓  
This condition  
gives us velocity  
addition function

However, looking at Lorentz transformations,

' $\Delta u$ ' signifies direction of velocity of the object

$$\vec{v} = v_x \hat{x} + v_y \hat{y} \quad \times$$

↳ We cannot take two Lorentz transformations, one along  $\hat{x}$  & one along  $\hat{y}$

$$\vec{v} = v_x \hat{x} + v_y \hat{y} = \underbrace{\sqrt{v_x^2 + v_y^2}}_{\vec{v}} \hat{v} \quad \rightarrow \text{take Lorentz transf. along } \hat{v}$$

Moreover,

$$v_y \text{ (rather } v_{\perp} \text{ direction of Lorentz transf)} = \frac{\Delta y'}{\Delta t'} = \frac{\Delta y}{\Delta t} \neq \frac{\Delta y}{\Delta t}$$

All the more reason to take Lorentz transf. in direction of velocity

### Energy & Momentum in Relativity

$$\vec{p}_{\text{non-rel.}} = m\vec{v} \quad \rightarrow \quad \boxed{\vec{p}_{\text{rel.}} = \gamma m\vec{v}} \quad \gamma = \frac{1}{\sqrt{1 - v^2/c^2}}$$

$$\boxed{E_{\text{rel.}} = \gamma mc^2}$$

\* Def<sup>n</sup> of mass in rel.

Rest mass  $\rightarrow m_0$

$$\boxed{\text{'relativistic mass'} \rightarrow m = \gamma m_0}$$

We do not talk about this

For  $v \rightarrow 0$ ,  $\vec{p}_{rel} \rightarrow 0$

$E_{rel} \rightarrow mc^2$   $\rightarrow$  A particle with mass has an intrinsic energy

\*  $E_{rel}$  & 3 components of  $\vec{p}_{rel}$  form a four vector

$$\begin{aligned} E^2 - p^2 c^2 &= \gamma^2 m^2 c^4 - \gamma^2 m^2 v^2 c^2 \\ &= \frac{c^2}{c^2 - v^2} \cdot m^2 c^2 (c^2 - v^2) \\ &= m^2 c^4 \end{aligned}$$

$\downarrow$   
has a Lorentz  
invariance interval

$$\therefore E = \sqrt{m^2 c^4 + p^2 c^2}$$

$$= mc^2 \left( 1 + \frac{p^2}{(mc)^2} \right)^{1/2}$$

$$= mc^2 \left( 1 + \frac{p^2}{2(mc)^2} \right) \quad \left[ \text{in lim of } p \ll mc \right]$$

$$E = \underbrace{mc^2}_{\text{Energy content of a body in non relativistic limit}} + \frac{p^2}{2m} \rightarrow \text{KE}$$

$\downarrow$   
Energy content of  
a body in non relativistic  
limit

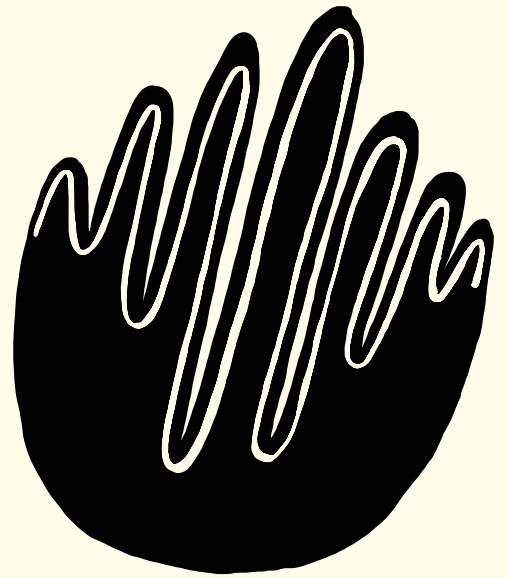
Newton's 2nd law

$$\downarrow$$
$$\vec{F} = \frac{d\vec{p}}{dt}$$

$$* \quad \frac{|\vec{p}|c}{E} = \frac{|\vec{v}|}{c}$$

# General Relativity - A glimpse

Not much, just some non-Euclidean geometry type shit.



## LEC-19

Ancient mathematics — natural no. operations — -ve no.s bad — solution of quadratic eqn — we don't talk about roots of -ves

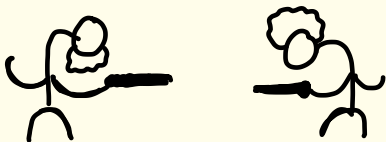
Skip to ~1500 years later  $\Rightarrow$  Now the drama starts

Scipione del Ferro  $\rightarrow$  figured out how to solve a reduced cubic

$$x^3 + px + q = 0$$
$$p, q \in \mathbb{Z}$$

Didn't publicise his solution

$\Downarrow$   
monetary reasons



Mathematical duels

Being able to solve a problem no one could solve was a bazooka up your sleeve

Only told one guy — his son-in-law Antonio Fiore

$\Downarrow$   
Made a bunch of money winning duels over this

$\Downarrow$   
Eventually beat by a guy Niccolò Tartaglia  $\rightarrow$  figured it out over the course of the duel

Eventually Tartaglia told this solution to Girolamo Cardano on the condition he keep it secret



Cardano used the result & further generalised the problem to

$$\text{solve } \rightarrow x^3 + ax^2 + bx + c = 0$$

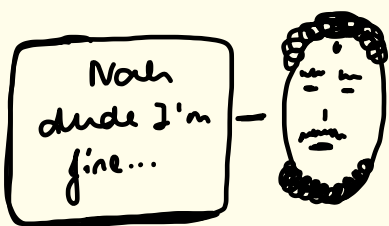
However, Cardano figured some important mathematical results in the meanwhile which he wanted to publish, but was unable to do so as it used Tartaglia's result.

Then he realised  $\rightarrow$  If Ferro posed the problem he must know the solution



Talked to him, and figured it was okay to publish Ferro's result instead of Tartaglia's result

Tartaglia was pissed... ←



okay new drama over back to math

Cardano's advancement  $\rightarrow$  Proved that equations involving square roots of -ve nos were solvable

His algorithm for solving cubic equations

1. Integers  $\Rightarrow$  Start

...

m.  $\sqrt{-()}$   $\Rightarrow$  Some intermediate

...

n. Rational  $\Rightarrow$  end

Earlier people would just give up whenever they came across the square root of a -ve no.

$\downarrow$   
Cardano proved these nos could be worked with

Eventually quartics were solved

$\sim$  1800 it was proved by Abel that it was impossible to find the solution to a general quintic eqn

(Galois also proved the same for quintic using diff argument that could also be extended for arbitrarily higher order equations)

$\downarrow$   
Introduced the concept of a Group

Ended up dead at 23 because he fucked around and found out  
(+ government conspiracy)  
(+ duels [non-mathematical])

# Group

→ A set

→ May have finite/infinite no. of elements

→ Must satisfy a set of properties

- $a, b \in \text{group } G \Rightarrow \underline{a \times b} \in G$

↓

"Group multiplication"  
 (but not really multiplication,  
 it could be any operation where  
 we get a third element from  
 combination of two elements)

- $\exists e \in G$  s.t.  $a \times e = e \times a = a \forall a \in G$

↓  
identity

- $\exists a^{-1} \in G$  s.t.  $a \times a^{-1} = a^{-1} \times a = e \forall a \in G$

↓  
inverse

- Associativity →  $a \times (b \times c) = (a \times b) \times c$

\*  $a \times b$  need not be  $b \times a$   
 If  $a \times b = b \times a \forall a, b \in G$ ,  
 then  $G \rightarrow$  Abelian Group

$C_1 \rightarrow$  group w/ 1 element

$C_2 \rightarrow$

$C_3 \rightarrow$

A group w/ zero elements is not possible. But groups w/ 1, 2, 3 elements possible -

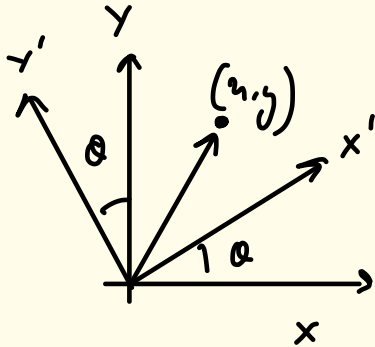
$$\left\{ \begin{array}{l} C_1 (1) \rightarrow n-1=0 \\ C_2 (1, -1) \rightarrow n^2-1=0 \\ C_3 (1, \omega, \omega^2) \rightarrow n^3-1=0 \end{array} \right.$$

↓  
Cyclic  
groups of order  
 $n$

Continuous parameter groups

Set of  $n \times n$  matrices with  $\det \neq 0$

→ called  $GL(n, \mathbb{R})$   
 (General linear matrix of  $n$  dimensions on the set of real nos)



$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$= \underbrace{R(\theta)} \begin{bmatrix} x \\ y \end{bmatrix}$$

Defines a relational matrix to transform a vector from one coordinate system to another.

Similarly,

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} R^t(\theta)$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} R^t(\theta) R(\theta) \begin{bmatrix} x \\ y \end{bmatrix}$$

↳ 'length' of vector

$$= \begin{bmatrix} x \\ y \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\hookrightarrow R^t(\theta) \cdot R(\theta) = I$$

$$= R(\theta) R^t(\theta)$$

Consider set matrices  $R$  s.t.

$R^t R = R R^t = I \rightarrow$  Set of  $R$  matrices forms a group

↳ Orthogonality condition



\*  $\det(R) = +1$  or  $-1$

$\hookrightarrow R$  s.t.  $\det(R) = +1 \Rightarrow$  is also a group  $\rightarrow$  group of rotations

$\hookrightarrow R$  s.t.  $\det(R) = -1 \Rightarrow$  NOT A GROUP



group of matrices  
having  $\det = -1$  cannot  
have identity

$\therefore$  Rotation matrices are those which satisfy orthogonality equation and have determinant = 1

⇓

i.e.

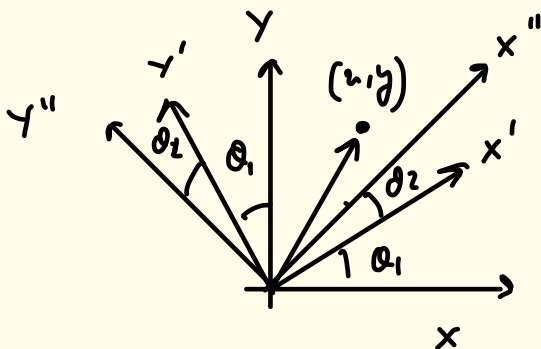
$$RR^t = R^tR = I$$

AND

$$\det(R) = 1$$

→ Rotational matrix

Applying a second rotation to the given axis



$$\begin{bmatrix} x'' \\ y'' \end{bmatrix} = \underbrace{R(\theta_2)R(\theta_1)}_{R(\theta_1 + \theta_2)} \begin{bmatrix} x \\ y \end{bmatrix} = R(\theta_1)R(\theta_2)$$



Rotations in 2D commute

\*  $C_{2D} \rightarrow \underline{SO(2)}$

Special orthogonal of 2 dimensions

$\det = 1$       $RR^t = R^tR = I$

\*  $R = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \rightarrow 4 \text{ n.s.}$

However, rotational matrices need only one parameter i.e. the angle of rotation

$\therefore$  How does one reduce 4 points of variation to 1

$\Downarrow$   
Apply three constraints

$RR^t = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

For arbitrary vector product, we would need 4 constraints to solve this eqn. However, we must remember that

$RR^t$  is a symmetric

$\hookrightarrow$  3 independent constraints

Counting the constraints, we have 2 diagonal constraints and 1 off-diagonal constraint

Remember, so far, purely mathematical arguments, no physics has actually started

Now let's move a dimension up

Taking set of  $3 \times 3$  matrices satisfying constraints of rotational matrices

$$R R^t = I \rightarrow R = 3 \times 3 \text{ matrix}$$

$$= \begin{bmatrix} \boxed{1} & 0 & 0 \\ 0 & \boxed{1} & 0 \\ 0 & 0 & \boxed{1} \end{bmatrix}$$

Using argument of symmetry, we now have 6 independent constraints

9 numbers  $\xrightarrow{6 \text{ ind. const.}}$  3 points of variation

$x, y, z$

Rotation in different planes

↓

$x, y, z \rightarrow \underline{3} c_2$  points of variation

Similarly, in 4 dimensions  
↓  
 $4 c_2 = 6$  points of variation

∴ In three dimensions, we have 3 independent

rotations  $\rightarrow O_x, O_y, O_z$  (rotation abt each axis)

$$R(\theta_x, \theta_y, \theta_z) = R(\theta_x, 0, 0) R(0, \theta_y, 0) R(0, 0, \theta_z)$$

$$\downarrow$$

$$SO(3) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos\theta_x & \sin\theta_x \\ 0 & -\sin\theta_x & \cos\theta_x \end{bmatrix} \begin{bmatrix} \cos\theta_y & 0 & -\sin\theta_y \\ 0 & 1 & 0 \\ \sin\theta_y & 0 & \cos\theta_y \end{bmatrix}$$

$$\begin{bmatrix} \cos\theta_z & \sin\theta_z & 0 \\ -\sin\theta_z & \cos\theta_z & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

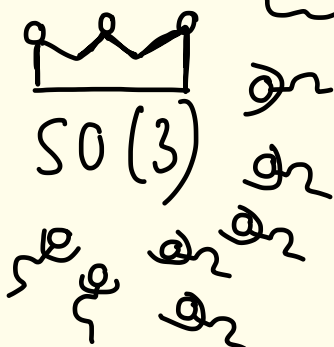
\* Rotations in 3d DO NOT COMMUTE  $\downarrow$  Non-Abelian Group  
 $\downarrow$  As well as higher dimensions

$$R(\theta_x, 0, 0) R(0, \theta_y, 0) - R(0, \theta_y, 0) R(\theta_x, 0, 0) \neq 0$$

The value of this difference follows a certain structure that rules the entire landscape of physics

All hail  $SO(3)$

Worship  $SO(3)$  with your heart and soul



$SO(3)$  is the truth of life and the universe

Probability

Gaussian distribution stuff

Quantum Quantum Quantum Quantum Quantum Quantum Quantum Quantum Quantum

One mole of ideal gas at temperature T

One mole of He at room temp.  $\Rightarrow U = \frac{3}{2} RT$   
(300K)  $\sim 4000J$

Taken to a height of 100m

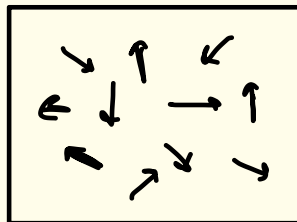
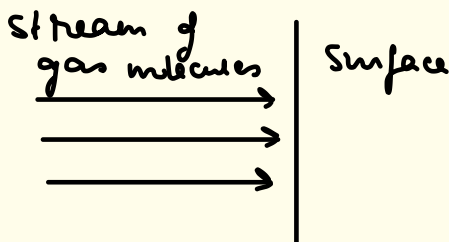
Mass of 1mol He = 4g

Potential energy =  $mgh$   
 $= 4J$

Total energy = 4004J, out of which we can utilise only 4J as work

Internal energy  $\rightarrow$  due to KE of gas molecules

We can't get any energy out of it as motion of gas molecules is completely random



Net momentum of system = 0  
Large no. of randomly moving particles  $\rightarrow$  their cumulative impact cancels out

The system as a whole does work on the surface } All gas molecules have a certain momentum, which changes uniformly on collision with a surface

# Entropy

$$\Delta S = T \Delta S$$

Helmholtz free Energy

$$H = U - TS$$

= 0 for a stationary gaseous system

\* Entropy is crucial in our conception of temperature



we need internal energy as well as entropy



We can only define temperature of a system when there is thermodynamic equilibrium



Maximum possible value of  $\rightarrow H=0$  entropy

\* 

$$\frac{1}{2} m v^2 \times A = \frac{3}{2} p T$$

$$\Rightarrow \langle v^2 \rangle = \frac{3kT}{m}$$

=

for the system

$$v \in (0, \infty)$$

Probability distribution function

$$P(v) dv = \left( \right) e^{-\frac{\frac{1}{2} m v^2}{kT}} dv$$

Probability of a particle to have speed in the range  $v$  to  $v+dv$

Boltzmann factor  $\equiv$

$$e^{-\frac{E}{kT}}$$

Generalised to energy in any form

# Blackbody Radiation

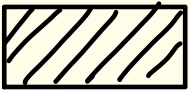
↓  
Perfectly  
absorbs & emits  
light of  
all frequencies

\* Stefan's Law  
Power emitted =  $\sigma T^4$

↓  
Σ Energy emitted  
over all frequencies

Emmissivity =  $A f(\nu, T)$

## \* Wien's Law

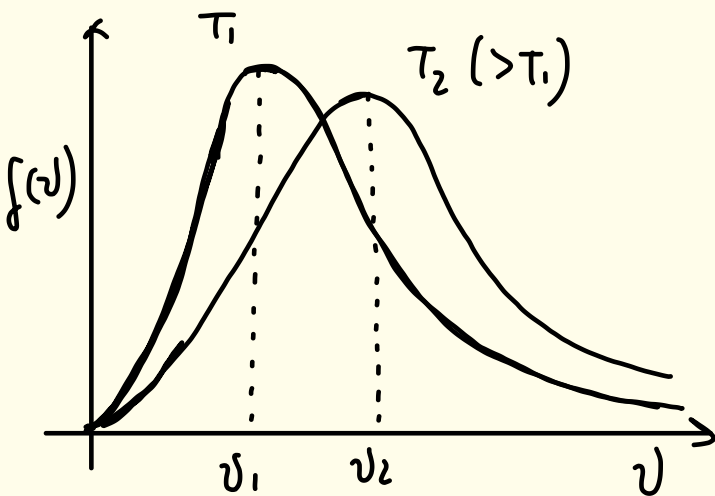


Black object  
immersed in an  
environment of radiation,  
in thermal eqbm w/  
radiation at temp T

$$f(\nu, T) \sim (\nu)^3 e^{-\beta \nu}$$

It appears  
that Wien  
maybe tried to  
imply a relation  
between energy  
& freq.

Went against  
ideas of classical  
electromagnetism  
⇓  
Energy related to  
amplitude of electromagnetic  
waves

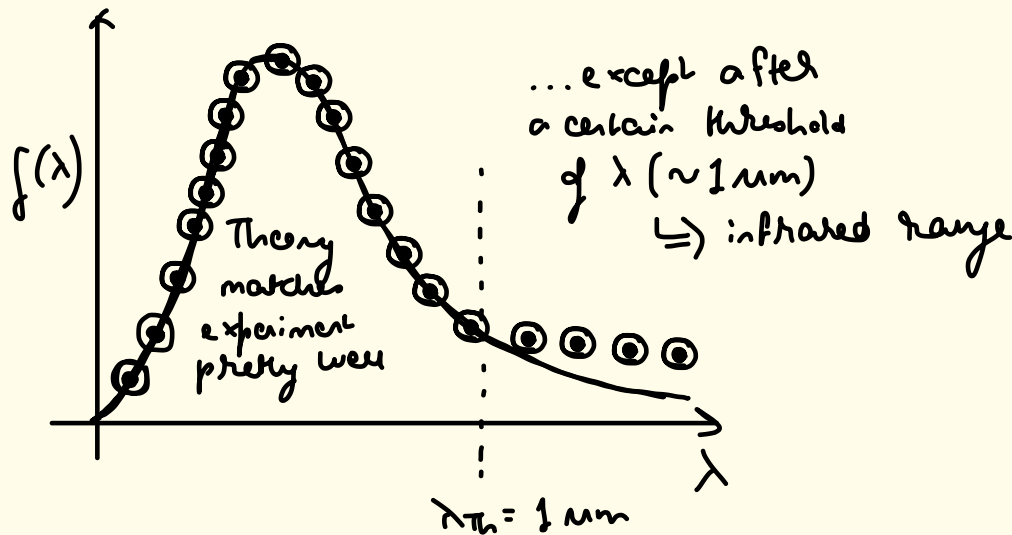


Wien's displacement law →

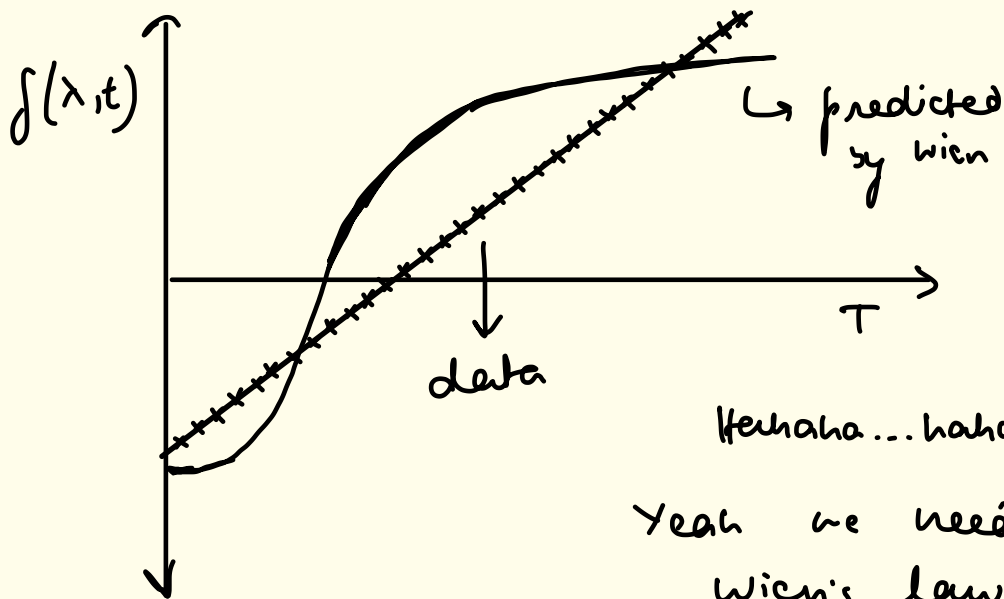
$$\lambda_{max} T = \text{constant}$$



Comparing theory with experiment,



Moreover, at far infrared frequencies, fixing  $\lambda$  and merely looking at variation w/ temperature



Max Planck came up with a solution

$$f(\nu, T) = \left( \right) \nu^3 \frac{1}{e^{\frac{h\nu}{kT}} - 1} \quad \left. \begin{array}{l} \nu \uparrow \Rightarrow \text{Wien's original law} \\ \nu \downarrow \Rightarrow \text{linear eqn} \end{array} \right\}$$

How did Planck justify his change without disturbing laws of statistics



Replace  $\int$  with  $\sum$

Declared that energy exists in quantised bundles of min. unit  $\rightarrow h\nu$

Einstein went further in his explanation of the photoelectric effect



Energy only exists in 'packages' of  $h\nu$ , unit size is never  $2h\nu$ ,  $3h\nu$  or so on.

→ In order to maximise entropy

Energy packages = photons



## LEC-22

Why do we need Quantum Theory?

- (a) Explain blackbody radiation
- (b) Atoms radiate at discrete frequencies
- (c) Photoelectric effect

Mathematical backbone arose from (a) & (c), but (b) is perhaps the most significant.

↓  
Hydrogen spectra → Dark lines in absorption spectrum  
Bright lines in emission spectrum.

Rydberg formula → 
$$E_{nm} = (-13.6 \text{ eV}) \left( \frac{1}{n^2} - \frac{1}{m^2} \right)$$
  
 $m > n$

Niels Bohr attempted to explain the absorption & emission spectra

↓  
As energy levels are quantised, so is frequency

↓  
First stated that classical rules merely don't apply at atomic scales

\* Bohr's postulates

1. Angular momentum of electrons is quantised

$$L = n\hbar$$

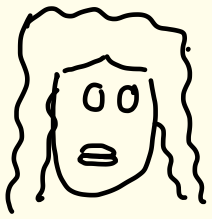
2. Only orbits satisfying above rule are allowed

Considering electrostatic force to provide centripetal force, the eqn for Energy we get

$$\longrightarrow E_n = -\frac{k}{n^2}, \quad k = 13.6 \text{ eV}$$

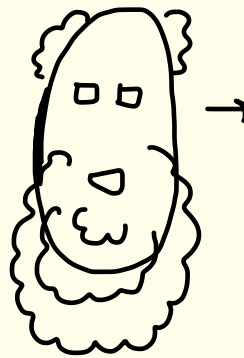
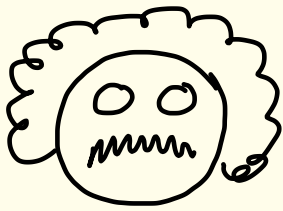
Matched eqns known at the time

Bohr ended up being totally wrong, but he introduced the idea of quantisation into atomic models



Watch me double slit experiment all over your theory

↓  
Light doth be corpuscular



→ Yup, plus look at Electromagnetism  
woooooow

Light do be pretty wavy

He's a quantum  
She's a quantum  
Light's a quantum  
Your mem's a quantum

Einstein said → light is a particle in that it appear as a bundle of energy  
→ light is a wave in that it has frequency & wavelength

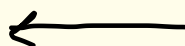
Now a young chap called de Broglie looked at electrons and thought "Hmmm..."

de Broglie said

- ~~light~~ <sup>Electron</sup> is a particle in that it appears as a bunch of energy <sup>↔ mass</sup>
- ~~light~~ <sup>Electron</sup> is a wave in that it has frequency? Hmmm...



found a relation for energy of an electron in terms of its momentum, which could be related to its  $v$  &  $\lambda$

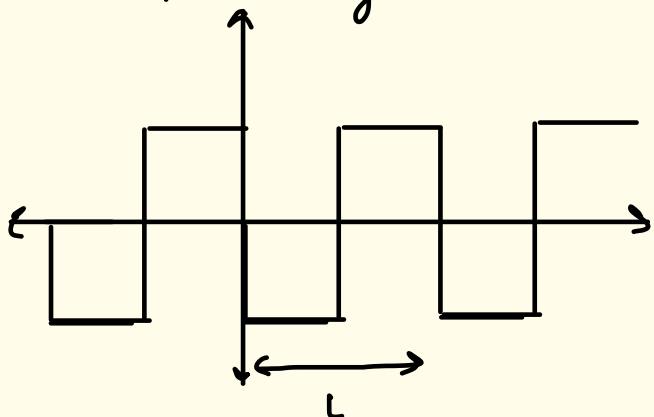


Eventually other wave properties of electrons were discovered

A mathematical solution to the problem was already available  $\Rightarrow$  Fourier Analysis

### 1. Fourier Series

Infinite series over an infinite range

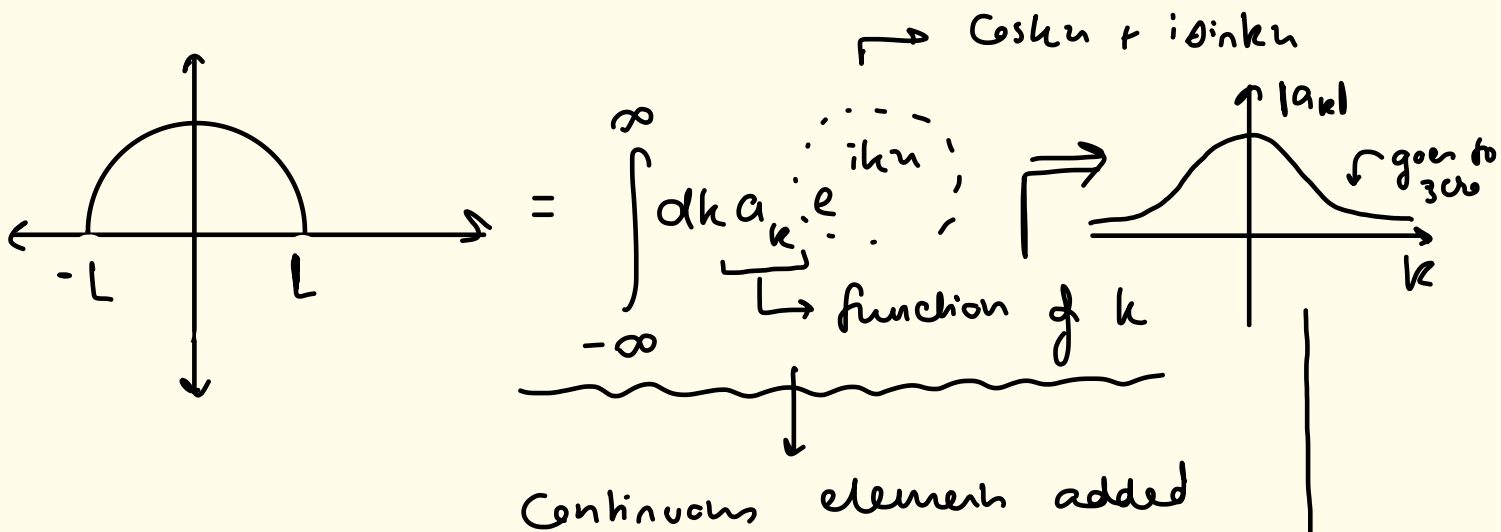


$$= \sum_{n=0}^{\infty} \left[ A_n \cos\left(\frac{2\pi n x}{L}\right) + B_n \sin\left(\frac{2\pi n x}{L}\right) \right]$$

Adding discrete harmonics

$$f(x+L) = f(x)$$

## 2. Fourier Integral



Taking  $f(x) \rightarrow$  has nonzero values in a limited range

Most important  
thm of Fourier  
analysis

Corresponding to it we have a function  $a_k$

$\downarrow$   
 nonzero values in limited range  $\rightarrow$  falls to zero faster

say  $f(x): (-L, L)$   
 $a_k: (-k_0, k_0)$

$\left. \begin{array}{l} \text{Range of } f \text{ in } x \\ \text{Range of } a \text{ in } k \end{array} \right\}$

$\parallel$   
 Number of  $\Rightarrow$  single digit  
 order 1 numbers

Representing an electron by a wave function  
↓  
uncertainty  $\Delta x$

Superposition of  
infinite w. of waves  
with wave numbers  
in range  $(k_{min}, k_{max})$

$$\Delta x \cdot \Delta k \rightarrow \text{order } 1$$

↓  
Uncertainty  
 $k_{max} - k_{min} = \Delta k$

## LEC-23

Major developments in quantum theory

1. Energy is quantised (Planck & Einstein)  
↓  
radiation

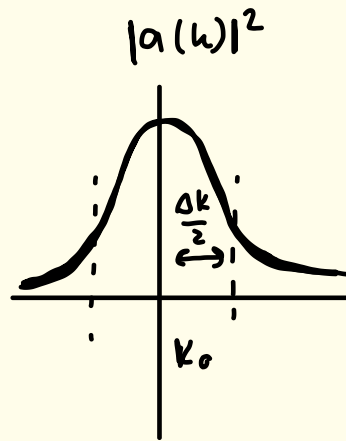
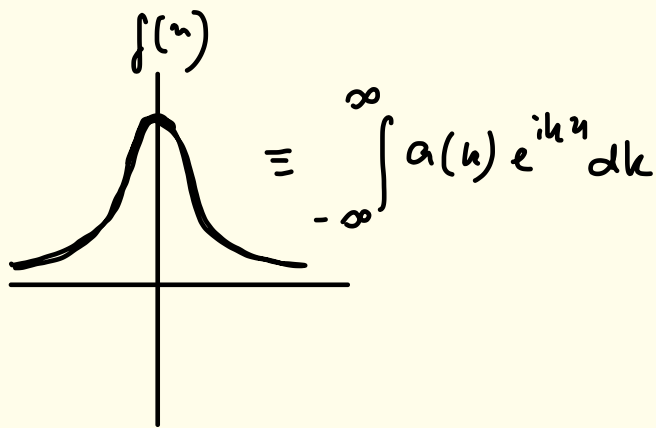
2. Angular momentum is quantised (Bohr)

↓  
Energy of  
electrons is  
quantised

\* Stated Bohr orbits  $\Rightarrow$  fit an integer no. of  
de Broglie wavelengths

de Broglie's insight  $\Rightarrow$  you need a wave eqn to  
represent a 'point' particle

Wave fn  $\rightarrow f(\bar{r}) \equiv f(x)$  in one dimension



Restricting our choice of wave nos. ( $k$ )

$$k \in \left( k_0 - \frac{\Delta k}{2}, k_0 + \frac{\Delta k}{2} \right)$$

## Schrödinger

$\rightarrow$  Thorough knowledge of differential equations

$\rightarrow$  de Broglie  $\Rightarrow$  particles show wave properties

Schrödinger  $\Rightarrow$  Every wave should have a wave eqn

$\downarrow$   
Always partial differential equations

$$\Psi(\bar{r}, t) \rightarrow \Psi(x, t)$$

in one D

Considering a free particle

$$E = \frac{p^2}{2m} \quad (\text{classical mechanics})$$



(de Broglie  $\rightarrow p = \frac{h}{\lambda} = \hbar k$ )

$$\hbar \omega = \frac{\hbar^2 k^2}{2m}$$

(Planck)



∴ The wave eqn of this particle -

$$\Psi(x,t) = A e^{i(kx - \omega t)}$$

$$\hbar \omega = \frac{\hbar^2 k^2}{2m}$$

⇓

$$\hbar \omega \Psi(x,t) = \frac{\hbar^2 k^2}{2m} \cdot \Psi(x,t) = -\frac{\partial^2 \Psi}{\partial x^2}$$

$i \frac{\partial \Psi}{\partial t}$

$$\Rightarrow \boxed{i\hbar \frac{\partial \Psi(x,t)}{\partial t} = -\frac{\hbar^2}{2m} \frac{\partial^2 \Psi(x,t)}{\partial x^2}}$$

Schrödinger's wave eqn.

$$\boxed{p \leftrightarrow -i\hbar \frac{d}{dx}}$$

Momentum identified by differential operator

In general coordinates,

$$\vec{p} \leftrightarrow -i\hbar \nabla$$

$$\vec{p} \cdot \vec{p} = p^2 \leftrightarrow -\hbar^2 \nabla^2$$

How we usually write it

⇓

$$\boxed{i\hbar \frac{\partial \Psi}{\partial t} = H \Psi}$$

Hamiltonian

Special case when potential only depends on spatial coords, not on velocity or time

⇓

$$H = PE + KE$$

$$= \frac{|\vec{p}|^2}{2m} + V(\vec{r})$$

General Schrödinger eqn



$$i\hbar \frac{\partial \Psi}{\partial t} = \left[ \frac{-\hbar^2}{2m} \cdot \nabla^2 + V(\mathbf{r}) \right] \Psi$$

Time dependent Schrödinger Equation

\* Suppose  $V(\mathbf{r}) = \frac{1}{2} m \omega^2 r^2$   
 $= \frac{1}{2} k r^2$

$$E_n = n\hbar\omega$$

} Planck  
 $= n\hbar\omega$

$$E_n = \left( n + \frac{3}{2} \right) \hbar\omega$$

related to angular momentum quantisation

$\frac{3}{2} \hbar\omega = \text{zero point energy}$

Time independent Schrödinger eqn.

$$i\hbar \frac{\partial \Psi(\mathbf{r}, t)}{\partial t} = \frac{-\hbar^2}{2m} \frac{\partial^2 \Psi}{\partial r^2} + V(\mathbf{r}) \cdot \Psi$$

Schrödinger solved the problem for

$$V(\mathbf{r}) = -\frac{e^2}{r}$$



Got same value for Bohr's energy, but didn't get angular momentum quantisation



Got something more intricate.

Schrödinger said that angular momentum quantisation not only dependent on n (principal quantum no.), but on two more numbers



l, m



\* Uniqueness thm



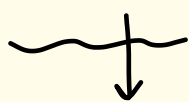
For a diff eqn with certain initial conditions, there is a unique soln to the eqn.

↓

Assuming  $\Psi(x,t) = T(t) \cdot \Psi(x)$

$$i\hbar \Psi \frac{dT}{dt} = \left( \frac{-\hbar^2}{2m} \frac{d^2\Psi}{dx^2} + V(x) \cdot \Psi \right) T(t)$$

$$i\hbar \frac{1}{T} \cdot \frac{dT}{dt} = \frac{1}{\Psi} \left( \frac{-\hbar^2}{2m} \frac{d^2\Psi}{dx^2} + V(x) \Psi \right)$$



only  
time  
related  
term



only  $x$   
related terms



$$G(t) = F(x) \rightarrow$$

for all  $x$  & all  $t$

$$G(t) = F(x) = \text{some const. } E$$

⇓  
only possible  
solution

$$\therefore \frac{dT}{dt} = -\frac{i}{\hbar} \cdot T E \Rightarrow \boxed{T(t) = T(0) e^{-\frac{iEt}{\hbar}}}$$

(similar to radioactive decay law)

Moreover,

$$\boxed{\left[ \frac{-\hbar^2}{2m} \frac{d^2}{dx^2} + V(x) \right] \Psi(x) = E \Psi(x)}$$

$H\Psi = E\Psi$   $\rightarrow$  Energy of particle w/ wave fn  $\Psi$

## \* Eigenvalues & Eigenvectors

$M \rightarrow n \times n$  matrix

$\bar{v} \rightarrow n \times 1$  column matrix

$M\bar{v} = \bar{w} \rightarrow n \times 1 \Rightarrow \bar{v}$  is called an eigenvector of  $M$  with eigenvalue  $\lambda$  if

'Matrix  $M$  multiplied by vector  $\bar{v}$ '  $\times$

$$\underline{M\bar{v} = \lambda\bar{v}}$$

$\Downarrow$   
'Matrix  $M$  acts upon vector  $\bar{v}$ '

Schrödinger's eqn is essentially an eigenvalue problem for differential eqns instead of matrices

$$H\Psi = E\Psi$$

$\Psi(x)$  is the energy eigen fn of the operator  $H$  with energy eigen value  $E$ .

## \* Sturm-Liouville Theory

$\downarrow$   
what kind of differential operators have the solution of eigenvalue form.

$$Df = \lambda f$$

$\Rightarrow$  Energy eigenvalues are quantised

Take certain free parameters  $\rightarrow$  we get solns for certain integer values of the free parameter.

## LEC-24

Schrödinger eqn  
↓

$$i\hbar \frac{d\Psi(x,t)}{dt} = H\Psi(x,t) \Rightarrow \text{Time dependent Schrödinger eqn (TDSE)}$$

Time independent Schrödinger eqn (TISE)  
↓

$$H\Psi(x) = E\Psi(x) \Rightarrow \text{Eigen value eqn}$$

↓                      ↓  
differential operator      Number

For differential operators there is a set of functions such that the operators act on those functions in a way so as to reproduce the function in a scaled form

Energy quantisation arises as  $\Psi(x)$  is not well behaved unless  $E$  takes well-defined discrete values

$\therefore$  Quantisation arises not due to Schrödinger's equation, but as a property of differential equations

# Example of quantisation in classical physics

↓  
vibration modes  
of a stretched  
string

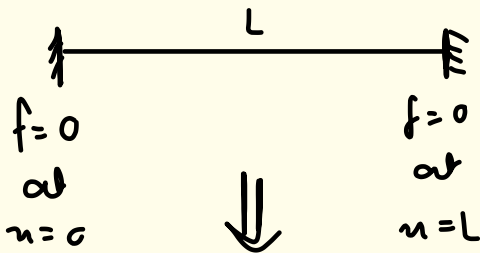
Defining a differential operator  $D = \frac{d^2}{dx^2}$

$$Df = ()f \rightarrow f = A \cos kx + B \sin kx$$

$k$  can take any value

$$Df = (-k^2)f$$

↓  
Imposing conditions on  $f$



This is the same problem we solve in quantum mechanics

we get well-behaved waveforms only for certain discrete values of  $k$

↓  
wave number is quantised

But Schrodinger couldn't clarify the physical meaning behind  $\Psi \rightarrow$  just a mathematical entity used to arrive at energy quantisation

Max Born proposed  $\rightarrow$  Probability interpretation

$|\Psi(x)^2| dx$  is probability of finding the particle  
in  $dx$  neighbourhood of  $x$

$\Downarrow$

$|\Psi(\vec{r})^2| dV =$  Probability of finding particle in  
 $dV$  neighbourhood of  $\vec{r}$ .

$\int_{\text{universe}} |\Psi(\vec{r})^2| dV = 1 \rightarrow$  for  $\Psi$  to be well behaved,

1.  $\Psi(\vec{r})$  has to be finite everywhere

2.  $\int |\Psi(\vec{r})^2| dV \rightarrow$  finite for any volume

$\Downarrow$

$\Psi(\vec{r}) \rightarrow 0$  as  $r \rightarrow \infty$

3.  $\frac{d^2\Psi}{dx^2}$  must exist

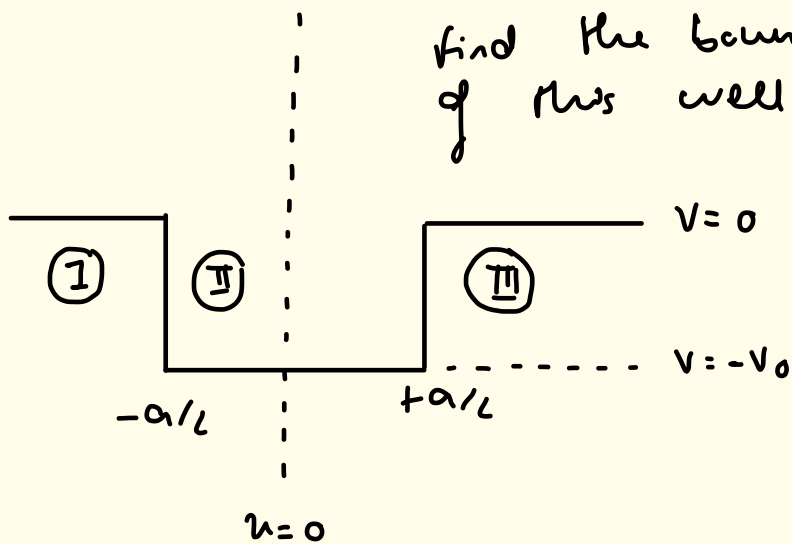
$\Downarrow$

$\Psi$  &  $\frac{d\Psi}{dx}$  must

be continuous

# Finite potential well

find the bound states of this well



Three regions (I), (II), (III) each with their own form of wave function of the particle  $\Psi_I, \Psi_{II}, \Psi_{III}$

In a classical system,

$$\left. \begin{array}{l} \text{Lower bound} = -V_0 \\ \text{Upper bound} = 0 \end{array} \right\} \rightarrow -V_0 < E < 0$$

E may have values in a continuous range from  $-V_0$  to 0

However, in a quantum mechanical system,

$-V_0 < E < 0 \rightarrow$  still true,

but there are a finite number of valid bound states

$$\textcircled{I}: -\frac{\hbar^2}{2m} \cdot \frac{d^2 \Psi_I}{dx^2} = E \Psi_I = -|E| \Psi_I \quad \Rightarrow \text{form of wave function in region I}$$

$$\Rightarrow \frac{d^2 \Psi_I}{dx^2} = \frac{2m|E|}{\hbar^2} \Psi_I = \kappa^2 \Psi_I \quad \rightarrow \quad \Psi_I = A e^{\kappa x} + B e^{-\kappa x}$$

As  $x \rightarrow -\infty$   
 $\Psi_I \rightarrow 0$



Similarly,  $\Psi_{III} = F e^{-\kappa u} + \cancel{G} e^{\kappa u}$

(II):  $-\frac{\hbar^2}{2m} \cdot \frac{d^2 \Psi_{II}}{du^2} + (-V_0) \Psi_{II} = -|E| \Psi_{II}$

$\therefore \frac{d^2 \Psi_{II}}{du^2} = -\frac{2m}{\hbar^2} (V_0 - |E|) \Psi_{II} = -k^2 \cdot \Psi_{II}$

$\therefore \Psi_{II} = C \cos ku + \cancel{D} \sin ku$

Theorem  $\rightarrow$  If potential has symmetry, then the lowest energy state shares the same symmetry

$\Downarrow$   
As  $\Psi$  is symmetric about y axis in regions beyond  $\pm a/2$ , so should be the case in the potential well.

$\Downarrow$   
 $\Psi$  must be an even function,  $\sin$  is odd fn

$\Psi$  &  $\frac{d\Psi}{du}$  both

continuous at

$u = \pi/2$

$\downarrow$

$C \cos k \frac{a}{2} = A e^{-\kappa a/2}$

$C k \sin k \frac{a}{2} = \kappa A e^{-\kappa a/2}$

$\Downarrow$

$\tan \frac{ka}{2} = \frac{\kappa}{k}$

$\Rightarrow \boxed{\frac{ka}{2} \tan \frac{ka}{2} = \frac{\kappa a}{2}}$

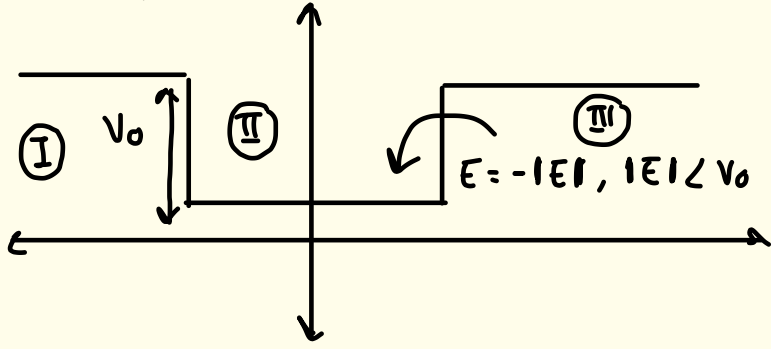
$k^2 + \kappa^2 = \frac{2m}{\hbar^2} (V_0 - |E|) + \frac{2m|E|}{\hbar^2} \Rightarrow \boxed{\left(\frac{ka}{2}\right)^2 + \left(\frac{\kappa a}{2}\right)^2 = \frac{mV_0 a^2}{2\hbar^2}}$

Enforcing boundary conditions gives us quantisation of energy

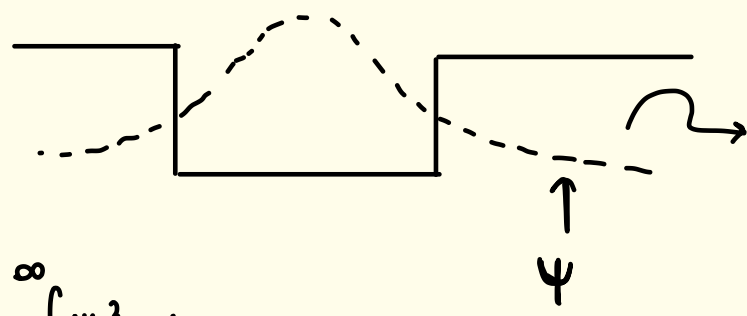


LEC-25

Finite potential well



In region II,  $E > -V_0$ ,  
 $\therefore E > PE \Rightarrow KE > 0$   
 But in regions I & III,  
 $E < 0, PE = 0 \Rightarrow KE < 0$



Non-zero probability of particle being located here  $\Rightarrow$  K.E.  $< 0$

$$\int_{-\infty}^{\infty} |\Psi|^2 dx = 1$$

$|\Psi|^2 dx =$  Prob of particle being b/w  $x$  &  $x+dx$

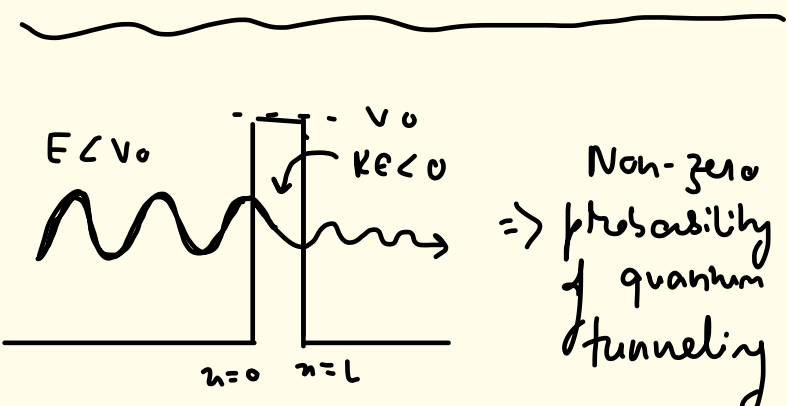
We can't observe the particle in these spaces, but they do exist

$$\frac{p^2}{2m} = -|E|$$

$$\Rightarrow p = \sqrt{-2m|E|}$$

So momentum is imaginary?

"Quantum Quantum Quantum"

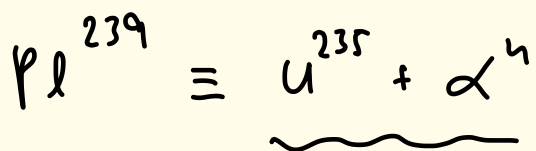


Non-zero probability of quantum tunneling

Tunneling through a barrier

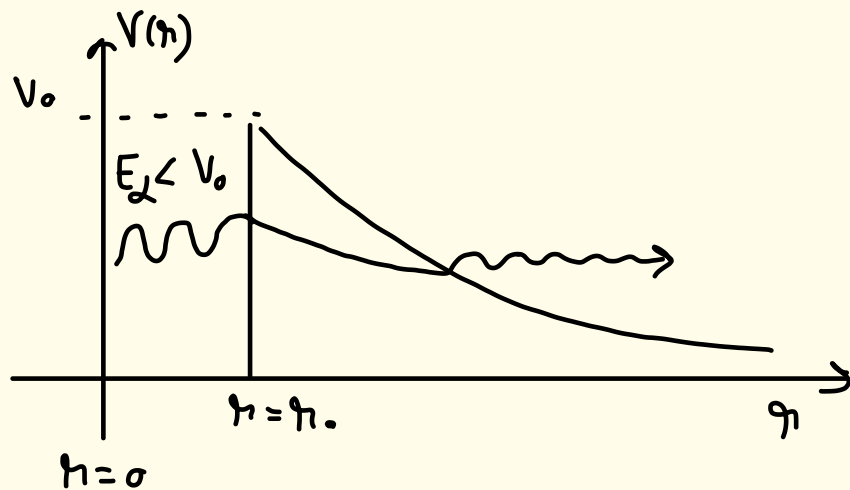
George Gamow  
 $\rightarrow$  Science  
 $\sim$  50 years ago  
 • One, Two, Three Infinity  
 • Mr. Tompkins in Wonderland

$\rightarrow$  Explained concept of  $\alpha$ -decay using quantum tunneling



loosely bound together  $\rightarrow$  strong nuclear force

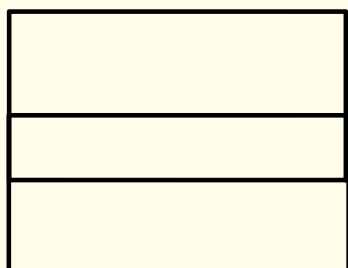
Bound  $\equiv$  Potential well



Also explains properties of solids  $\rightarrow$  Electrical conduction  
 Earlier theory  $\Rightarrow$  free electrons

Using quantum mechanics  $\Rightarrow$  Band theory of solids

Conductors



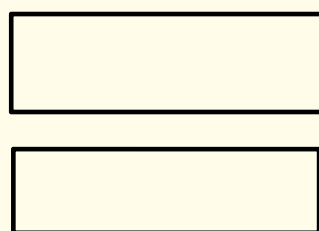
Conduction Band

Valence Band

$\downarrow$   
 Highest energy band above which there are no e<sup>-</sup>s



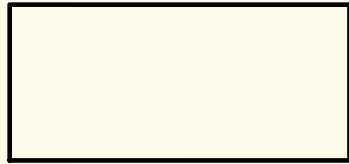
Allowed energy levels form continuous bands



# Insulators



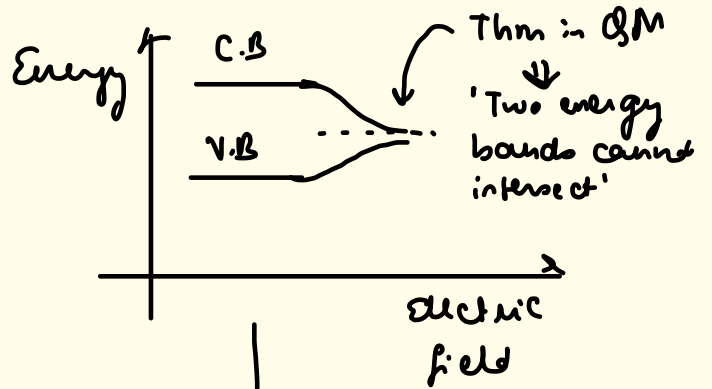
Conduction Band



Valence Band

# Zener diode

Zener assumed the existence of materials where by modulating strength of electric field, the energy levels get affected



Eventually such materials were discovered with diode properties imagined by Zener

\* Dirac → Relativistic version of Schrodinger's Equation

!!!

Dirac Equation

Suggestions of negative energy particles



Why don't we see -ve energy electrons around us?

Dirac: All -ve energy states are occupied

Everyone: ... WTF?

Dirac: All e's around us are excitations of -ve energy e's that we consider the ground state

$$E = mc^2$$

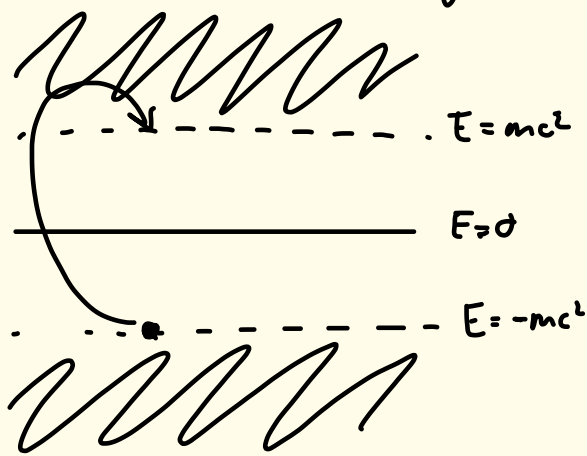
$$E = 0$$

$$E = -mc^2$$

Dirac eqn  $\Rightarrow |E| > mc^2$   
 $\Rightarrow E > mc^2$  or  $E < -mc^2$

Dirac eventually went on to mathematically prove this shz

Even more crazy shit

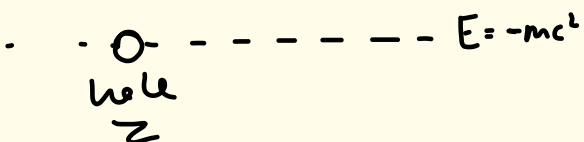
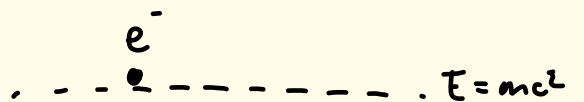


Suppose an  $e^-$  in the -ve energy levels was given enough energy to move into a +ve level

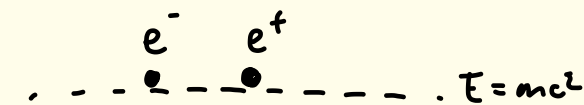


formation of an  $e^-$ -hole pair

Now how do we comprehend this hole?



Hole = lack of -ve charge  
 |||  
 +ve charge



However, this hole also  
 ↓  
 lack of -ve energy  
 |||  
 +ve energy



Dirac eqn suggested the existence of a particle with the same physical properties as an electron but with +ve charge

↳ Now called a positron

→ we eventually observed this particle

↓  
Antimatter exists

## ⊛ Measurement in QM

Say we want to solve the problem of  $e^-$ 's bound in an atom

$\Psi(\vec{r})$  describes the 'state' of the electron

↓  
Any physical quantity we want to measure

$|\Psi^2(\vec{r})| d^3\vec{r} \rightarrow$  Prob of finding an  $e^-$  in  $d^3\vec{r}$  neighbourhood of  $\vec{r}$



Ground state energy eigenvalue of an electron

Position measurement



Collapse of wavefunction  
into a small region

LEC-26 → ⊛ Bonus - Prof Sai Edition

Early era of Physics - How does the world work?

Modern era of Physics - Can we apply techniques of Physics to stuff very closely related to our daily lives?

Now, Quantum computers



I give you computer ⇒ How to give it ultimate performance

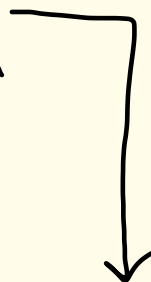
→ Hardware constraints

→ Software constraints



Physicists ☺

If the laws of Physics are true, and the Universe is causal, then



Must be true

Bell's Inequality

"Measurement outcomes are inherently random"

Quantum mechanics ⇒ Can't do 'phase space physics'



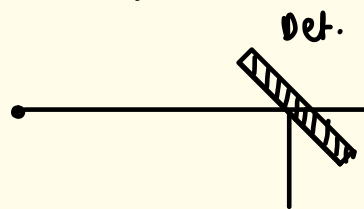
$F = ma$

Physics involving momentum & stuff

If you send a single photon through



Detector will give you one click



output ⇒ inherently random

No amt of previous data can predict future data



'Inherently random'



It is impossible to predict future outcomes no matter the observer or previous data collected

It is simply impossible to comprehend physics of small particles through lens of  $u$  &  $p$

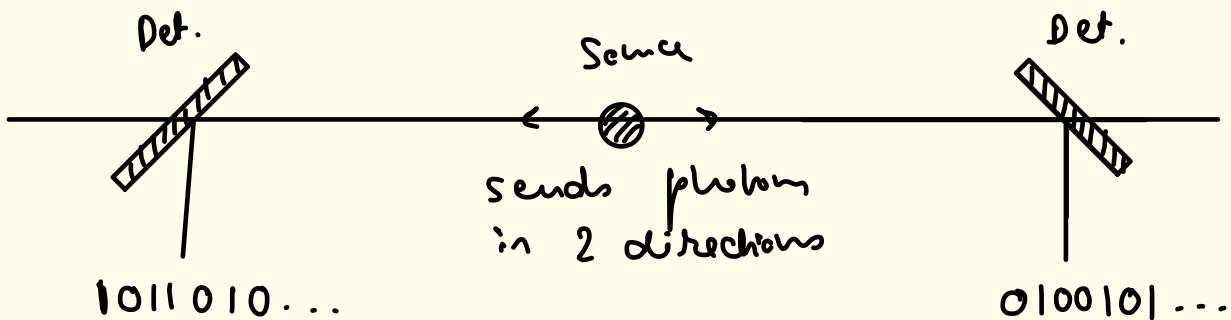
Why?

Law of large numbers



Statistical mech

Proof → EPR paradox



Observation → Results in each direction are anti-correlated

\* Targent - Bertlman's socks



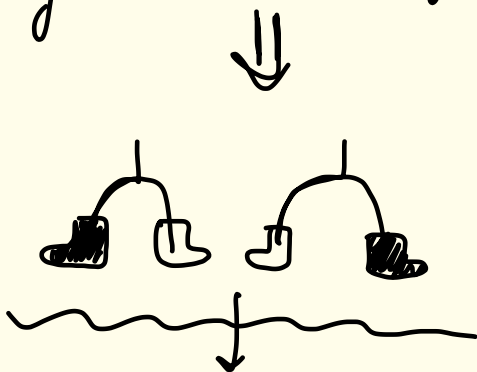
used to wear different colored socks in each foot.

say someone is a very good friend of Bertlman's

↓  
Has a pair of blue socks

Bertlman → pair of red socks

They both exchange a sock



Their socks are 'anti-correlated'

say Bertlman is in another galaxy far far away → apparent violation of causality

↑↑  
No matter how far Bertlman and his friend are from each other

Now, say someone hasn't met them that day, but knows of their peculiar behaviour

↓  
say the person meets Bertlman's friend. As soon as they see the friend's feet, they

← instantaneously knew what Bertlman is wearing

## Differences

- Preparation uncertainty vs Identical preparation
- In quantum mechanics, the colour of the socks isn't defined beforehand, it 'pops' into existence' as soon as we make a measurement

Paradox lies in the fact that identical preparation leads to random outcomes AND anti-correlation still holds

According to E, P & R, maybe there is some 'hidden variable' which affects things

How does stuff hide?

→ Size

→ Lack of interaction strength



- 'BSs eff all this quantum BS classical for the win !

Einstein said that QM is nothing but CM with some hidden variables

↳ Philosophical + Causality reasons

Bell's intuition  $\rightarrow$  Classical mechanics generate probability theories  
 $\downarrow$   
Worked at CERN

If classical mechanics is correct

$$\langle A_0 B_0 \rangle + \langle A_0 B_1 \rangle + \langle A_1 B_0 \rangle - \langle A_1 B_1 \rangle < 2$$

Every result  $\rightarrow \pm 1$   
Pre-determined reality

If Q.M is correct

$$\langle A_0 B_0 \rangle + \langle A_0 B_1 \rangle + \langle A_1 B_0 \rangle - \langle A_1 B_1 \rangle < 2\sqrt{2}$$

No pre-determined reality

You have to take a (ig?) wide range of outcomes, which expands the range of possibilities.

