MA 110 Linear Algebra and Differential Equations Lecture 18

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Recall that we proved the following Spectral Theorems.

- Let $\mathbf{A} \in \mathbb{C}^{n \times n}$. Then
 - **A** is normal \iff **A** is unitarily diagonalizable

and

- A is self-adjoint \iff A is unitarily diagonalizable and all eigenvalues of A are real
- Let $\mathbf{A} \in \mathbb{R}^{n \times n}$. Then

 ${f A}$ is symmetric $\iff {f A}$ is orthogonally diagonalizable

We also outlined a constructive procedure whereby knowing the distinct eigenvalues of a normal matrix A ∈ C^{n×n}, we can find a unitary matrix U and a diagonal matrix D such that D = U*AU. In case A is real symmetric, then one gets a diagonal matrix D ∈ R^{n×n} and an orthogonal matrix C ∈ R^{n×n} such that D = C^TAC.

Spectral Representation of a Matrix

Suppose $\mathbf{A} \in \mathbb{C}^{n \times n}$ be normal. By Spectral Theorem, there is an orthonormal set of eigenvectors $\mathbf{u}_1, \ldots, \mathbf{u}_n$ of \mathbf{A} corresponding to the eigenvalues $\lambda_1, \ldots, \lambda_n \in \mathbb{C}$. If $\mathbf{x} \in \mathbb{C}^{n \times 1}$, then $\mathbf{x} = \langle \mathbf{u}_1, \mathbf{x} \rangle \mathbf{u}_1 + \cdots + \langle \mathbf{u}_n, \mathbf{x} \rangle \mathbf{u}_n$. Hence we obtain the following spectral representation of \mathbf{A} .

$$\mathbf{A}\,\mathbf{x} = \lambda_1 \langle \mathbf{u}_1, \, \mathbf{x} \rangle \mathbf{u}_1 + \dots + \lambda_n \langle \mathbf{u}_n, \, \mathbf{x} \rangle \mathbf{u}_n \quad \text{ for all } \mathbf{x} \in \mathbb{C}^{n \times n}$$

Let $k \in \mathbb{N}$. Then $\mathbf{A}^k(\mathbf{u}_j) = \lambda_j^k \mathbf{u}_j$ for each $j = 1, \dots, n$, and so

$$\mathbf{A}^k \mathbf{x} = \sum_{j=1}^n \lambda_j^k \langle \mathbf{u}_j, \, \mathbf{x}
angle \mathbf{u}_j \quad \text{ for all } \mathbf{x} \in \mathbb{C}^{n imes n}$$

More generally, if p(t) is any polynomial, then

$$p(\mathbf{A}) \, \mathbf{x} = \sum_{j=1}^n p(\lambda_j) \langle \mathbf{u}_j, \, \mathbf{x}
angle \mathbf{u}_j \quad ext{ for all } \mathbf{x} \in \mathbb{C}^{n imes n}$$

Real Quadratic Forms

Let $n \in \mathbb{N}$. A real *n*-ary quadratic form Q is a homogeneous polynomial of degree 2 in *n* variables with coefficients in \mathbb{R} . Thus

$$Q(x_1,\ldots,x_n) := \sum_{j=1}^n \sum_{k=1}^n \alpha_{jk} x_j x_k$$

=
$$\sum_{j=1}^n \alpha_{jj} x_j^2 + \sum_{1 \le j \le k \le n} (\alpha_{jk} + \alpha_{kj}) x_j x_k,$$

where $\alpha_{jk} \in \mathbb{R}$ for $j, k = 1, \ldots, n$.

Examples Let $a, b, c, a', b', c' \in \mathbb{R}$. $n = 1 : Q(x) := a x^2$ (unary quadratic form) $n = 2 : Q(x, y) := a x^2 + b y^2 + a' xy$ (binary quadratic form) $n = 3 : Q(x, y, z) := a x^2 + b y^2 + c z^2 + a' xy + b' yz + c' zx$ (ternary quadratic form) For $n \in \mathbb{N}$, consider an $n \times n$ real matrix $\mathbf{A} := [a_{jk}]$. Then for $\mathbf{x} := \begin{bmatrix} x_1 & \cdots & x_n \end{bmatrix}^{\mathsf{T}}$, $\mathbf{x}^{\mathsf{T}}\mathbf{A}\mathbf{x} = \begin{bmatrix} x_1 & \cdots & x_n \end{bmatrix} \begin{bmatrix} \sum_{k=1}^n a_{1k}x_k \\ \vdots \\ \sum_{k=1}^n a_{nk}x_k \end{bmatrix} = \sum_{j=1}^n \left(\sum_{k=1}^n a_{jk}x_k\right)x_j$ $= \sum_{j=1}^n a_{jj}x_j^2 + \sum_{1 \le j < k \le n} (a_{jk} + a_{kj})x_jx_k$,

which is an *n*-ary quadratic form. In fact, $Q(x_1, \ldots, x_n) = \mathbf{x}^T \mathbf{A} \mathbf{x}$ for all $\mathbf{x} := \begin{bmatrix} x_1 & \cdots & x_n \end{bmatrix}$ in $\mathbb{R}^{n \times 1}$ if and only if

$$\alpha_{jk} + \alpha_{kj} = a_{jk} + a_{kj}$$
 for all $j, k = 1, \dots, n$.

In general, many $n \times n$ matrices induce the same quadratic form. For example, the matrices $\begin{bmatrix} 3 & 4 \\ 6 & 2 \end{bmatrix}, \begin{bmatrix} 3 & 5 \\ 5 & 2 \end{bmatrix}, \begin{bmatrix} 3 & -1 \\ 11 & 2 \end{bmatrix}$ induce the same binary quadratic form.

But if we require the matrix $\mathbf{A} := [a_{jk}]$ inducing the quadratic form Q to be symmetric, that is, $a_{jk} = a_{kj}$ for all j, k, then

$$a_{jk} = rac{1}{2}(lpha_{jk} + lpha_{kj}) \quad ext{for all } j, k = 1, \dots, n.$$

Thus given an *n*-ary quadratic form Q, there is a unique $n \times n$ real symmetric matrix **A** such that $Q(x_1 \dots, x_n) = \mathbf{x}^T \mathbf{A} \mathbf{x}$ for all $\mathbf{x} = \begin{bmatrix} x_1 & \cdots & x_n \end{bmatrix} \in \mathbb{R}^{n \times 1}$; in fact

$$\mathbf{A}:=[a_{jk}], \quad ext{where } a_{jk}:=rac{1}{2}(lpha_{jk}+lpha_{kj}), \ j,k=1,\ldots,n.$$

This real symmetric matrix **A** is called the **matrix associated** with the quadratic form Q, and we write $Q = Q_A$.

A real *n*-ary quadratic form Q is said to be a **diagonal quadratic form** if there are $\lambda_1, \ldots, \lambda_n \in \mathbb{R}$ such that

$$Q(x_1,\ldots,x_n)=\lambda_1x_1^2+\cdots+\lambda_nx_n^2.$$

It is clear that a quadratic form Q is diagonal if and only if Q is associated with a diagonal matrix **D**, that is, $Q = Q_{\rm D}$. Using the spectral theorem for real symmetric matrices, we show that every quadratic form can be orthogonally transformed to a diagonal quadratic form.

Theorem (Principal Axis Theorem)

Let Q be a real quadratic form and let $\mathbf{A} \in \mathbb{R}^{n \times n}$ be the symmetric matrix associated with Q. If \mathbf{C} is an orthogonal matrix such that the matrix $\mathbf{D} := \mathbf{C}^{\mathsf{T}} \mathbf{A} \mathbf{C}$ is diagonal, then $Q(\mathbf{x}) = Q_{\mathsf{D}}(\mathbf{y})$, where $\mathbf{y} := \mathbf{C}^{\mathsf{T}} \mathbf{x}$ for all $\mathbf{x} \in \mathbb{R}^{n \times 1}$.

Proof. Let $\mathbf{x} \in \mathbb{R}^{n \times 1}$ and $\mathbf{y} := \mathbf{C}^{\mathsf{T}} \mathbf{x} = \mathbf{C}^{-1} \mathbf{x}$. Then $\mathbf{x} = \mathbf{C} \mathbf{y}$ and $Q_{\mathsf{A}}(\mathbf{x}) = \mathbf{x}^{\mathsf{T}} \mathbf{A} \mathbf{x} = (\mathbf{C} \mathbf{y})^{\mathsf{T}} \mathbf{A}(\mathbf{C} \mathbf{y}) = \mathbf{y}^{\mathsf{T}} (\mathbf{C}^{\mathsf{T}} \mathbf{A} \mathbf{C}) \mathbf{y} = \mathbf{y}^{\mathsf{T}} \mathbf{D} \mathbf{y} = Q_{\mathsf{D}}(\mathbf{y}).$

To diagonalise a real *n*-ary quadratic form Q, we first write down the (real symmetric) matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$ associated with Q. We then find an orthonormal basis $\mathbf{u}_1, \ldots, \mathbf{u}_n$ consisting of eigenvectors of **A** corresponding to its eigenvalues $\lambda_1, \ldots, \lambda_n$ counted according to their algebraic multiplicities. If we let

$$\mathbf{C} := \begin{bmatrix} \mathbf{u}_1 & \cdots & \mathbf{u}_n \end{bmatrix} \text{ and } \mathbf{D} := \operatorname{diag}(\lambda_1, \dots, \lambda_n),$$

Then $Q(\mathbf{x}) = \lambda_1 y_1^2 + \cdots + \lambda_n y_n^2$, where $\mathbf{y} := \mathbf{C}^{\mathsf{T}} \mathbf{x} = \begin{bmatrix} \mathbf{u}_1^{\mathsf{T}} \\ \vdots \\ \mathbf{u}_n^{\mathsf{T}} \end{bmatrix} \mathbf{x}.$
Example

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Let us transform the quadratic form $Q(\mathbf{x}) = x_1^2 + x_2^2 + x_3^2 + 4x_1x_2 + 4x_2x_3 - 4x_3x_1$ to a diagonal form. Here $\mathbf{A} := \begin{bmatrix} 1 & 2 & -2 \\ 2 & 1 & 2 \\ -2 & 2 & 1 \end{bmatrix}$ is the associated matrix.

We have seen before that $\mathbf{u}_1 := \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \end{bmatrix}^T$, $\mathbf{u}_2 := \begin{bmatrix} -1/\sqrt{6} & 1/\sqrt{6} & 2/\sqrt{6} \end{bmatrix}^T$ and $\mathbf{u}_3 := \begin{bmatrix} 1/\sqrt{3} & -1/\sqrt{3} & 1/\sqrt{3} \end{bmatrix}^T$ are eigenvectors of \mathbf{A} corresponding to the eigenvalues 3, 3 and -3 respectively, and they form an orthonormal basis for $\mathbb{R}^{3 \times 1}$. Hence let

$$\label{eq:constraint} \boldsymbol{\mathsf{C}} := \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{6} & 1/\sqrt{3} \\ 1/\sqrt{2} & 1/\sqrt{6} & -1/\sqrt{3} \\ 0 & 2/\sqrt{6} & 1/\sqrt{3} \end{bmatrix} \quad \text{and} \quad \boldsymbol{\mathsf{D}} := \text{diag}(3,3,-3).$$

Then $\mathbf{C}^{\mathsf{T}}\mathbf{A}\mathbf{C} = \mathbf{D}$, and so $Q(\mathbf{x}) = 3(y_1^2 + y_2^2 - y_3^2)$, where

$$\begin{split} \mathbf{y} &= \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} := \mathbf{C}^\mathsf{T} \mathbf{x} = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ -1/\sqrt{6} & 1/\sqrt{6} & 2/\sqrt{6} \\ 1/\sqrt{3} & -1/\sqrt{3} & 1/\sqrt{3} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \\ \text{that is, } y_1 &= (x_1 + x_2)/\sqrt{2}, \ y_2 &= (-x_1 + x_2 + 2x_3)/\sqrt{6} \text{ and} \\ y_3 &= (x_1 - x_2 + x_3)/\sqrt{3}. \end{split}$$

Conic Sections

A conic section is the locus in \mathbb{R}^2 of an equation

$$a x^{2} + b y^{2} + c xy + a'x + b'y + c' = 0,$$

where $a, b, c, a', b', c' \in \mathbb{R}$ and at least one among a, b, c is nonzero. We assume WLOG that not both a and b are negative. It can be proved that the conic is one of these: (i) the empty set (ii) a single point (iii) one or two straight lines (iv) an ellipse (v) a hyperbola

(vi) a parabola.

Terms of the second degree on the LHS of the equation give

$$Q(x,y) := a x^2 + b y^2 + c xy.$$

It is a binary quadratic form. It determines the type of the conic.

The (real symmetric) matrix associated with Q is

$$\mathbf{A} := \begin{bmatrix} a & c/2 \\ c/2 & b \end{bmatrix}.$$

Hence the equation of the given conic section becomes

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & c/2 \\ c/2 & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} a' & b' \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + c' = 0,$$

that is,

$$\begin{bmatrix} x & y \end{bmatrix} \mathbf{A} \begin{bmatrix} x & y \end{bmatrix}^{\mathsf{T}} + \begin{bmatrix} a' & b' \end{bmatrix} \begin{bmatrix} x & y \end{bmatrix}^{\mathsf{T}} + c' = \mathbf{0}.$$

Let $\mathbf{C} := [\mathbf{u}_1, \mathbf{u}_2]$ be an orthogonal matrix whose columns \mathbf{u}_1 and \mathbf{u}_2 are eigenvectors of \mathbf{A} with corresponding eigenvalues λ_1 and λ_2 , and let $\mathbf{D} := \text{diag}(\lambda_1, \lambda_2)$ so that $\mathbf{C}^{\mathsf{T}} \mathbf{A} \mathbf{C} = \mathbf{D}$.

We use the change of variables
$$\begin{bmatrix} x \\ y \end{bmatrix} = \mathbf{C} \begin{bmatrix} u \\ v \end{bmatrix}$$
 to transform the quadratic form $Q(x, y)$ to a diagonal form as follows.

$$Q(x, y) = \begin{bmatrix} x & y \end{bmatrix} \mathbf{A} \begin{bmatrix} x & y \end{bmatrix}^{\mathsf{T}} \\ = \begin{bmatrix} u & v \end{bmatrix} \mathbf{C}^{\mathsf{T}} \mathbf{A} \mathbf{C} \begin{bmatrix} u & v \end{bmatrix}^{\mathsf{T}} \\ = \begin{bmatrix} u & v \end{bmatrix} \mathbf{D} \begin{bmatrix} u & v \end{bmatrix}^{\mathsf{T}} \\ = \lambda_1 u^2 + \lambda_2 v^2 = Q_{\mathsf{D}}(u, v)$$

The ordered orthonormal basis $(\mathbf{u}_1, \mathbf{u}_2)$ determines a new set of coordinate axes, so that the locus of the original equation is given by

$$\begin{bmatrix} u & v \end{bmatrix} \operatorname{diag}(\lambda_1, \lambda_2) \begin{bmatrix} u \\ v \end{bmatrix} + \begin{bmatrix} a' & b' \end{bmatrix} \mathbf{C} \begin{bmatrix} u \\ v \end{bmatrix} + c'$$
$$= \lambda_1 u^2 + \lambda_2 v^2 + \begin{bmatrix} a' & b' \end{bmatrix} \begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} + c' = 0.$$

If the conic so determined is not degenerate, that is, if it does not reduce to an empty set, a point, or line(s), then the signs of λ_1 and λ_2 determine the type of the conic section as follows. The equation represents

1. ellipse if $\lambda_1 \lambda_2 > 0$, that is, both λ_1 and λ_2 are positive,

2. hyperbola if $\lambda_1\lambda_2 < 0$, that is, one of λ_1, λ_2 is positive and the other is negative,

3. parabola if $\lambda_1 \lambda_2 = 0$, that is, one of λ_1, λ_2 is zero.

Note: Since $Q(x, y) := ax^2 + by^2 + cxy = \lambda_1 u^2 + \lambda_2 v^2$, where not both *a* and *b* are negative, it follows that not both λ_1 and λ_2 can be negative, and since the conic is assumed to be nondegenerate, not both λ_1 and λ_2 can be equal to zero.

Examples

1. Consider the conic section given by $2x^2 + 4xy + 5y^2 + 4x + 13y - 1/4 = 0$, and the binary quadratic form $Q(x, y) := 2x^2 + 4xy + 5y^2$. Then the associated symmetric matrix $\mathbf{A} := \begin{bmatrix} 2 & 2 \\ 2 & 5 \end{bmatrix}$ has eigenvalues $\lambda_1 := 1$ and $\lambda_2 := 6$, and the corresponding eigenvectors $\mathbf{u}_1 := \begin{bmatrix} 2 & -1 \end{bmatrix}^T / \sqrt{5}$ and $\mathbf{u}_2 := \begin{bmatrix} 1 & 2 \end{bmatrix}^T / \sqrt{5}$ form an orthonormal basis for $\mathbb{R}^{2 \times 1}$. Hence let

$$\mathbf{C} := rac{1}{\sqrt{5}} egin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix}$$
 and $\mathbf{D} := ext{diag}(1,6).$

Then $\mathbf{C}^{\mathsf{T}}\mathbf{A}\mathbf{C} = \mathbf{D}$. So $Q(x, y) = Q_{\mathsf{D}}(u, v) = u^2 + 6v^2$, where $\begin{bmatrix} u \\ v \end{bmatrix} := \mathbf{C}^{\mathsf{T}} \begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$, that is, $u = (2x - y)/\sqrt{5}$ and $v = (x + 2y)/\sqrt{5}$.

Since
$$\begin{bmatrix} x \\ y \end{bmatrix} := \mathbf{C} \begin{bmatrix} u \\ v \end{bmatrix}$$
, substituting $x = (2u + v)/\sqrt{5}$ and $y = (-u + 2v)/\sqrt{5}$ in the given equation of the conic section, we obtain

$$u^2 + 6v^2 - \sqrt{5}u + 6\sqrt{5}v - \frac{1}{4} = 0.$$

Completing the squares, we see that

$$\left(u-\frac{\sqrt{5}}{2}\right)^2+6\left(v+\frac{\sqrt{5}}{2}\right)^2=9.$$

This is an equation of an ellipse with its centre at $(\sqrt{5}/2, -\sqrt{5}/2)$ in the *uv*-plane, where the *u*-axis and the *v*-axis are determined by the eigenvectors **u**₁ and **u**₂.

2. Consider the conic section given by $2x^2 - 4xy - y^2 - 4x + 10y - 13 = 0$, and the binary quadratic form $Q(x, y) := 2x^2 - 4xy - y^2$. The associated symmetric matrix $\mathbf{A} := \begin{bmatrix} 2 & -2 \\ -2 & -1 \end{bmatrix}$ has eigenvalues $\lambda_1 = 3, \lambda_2 = -2$, and the corresponding eigenvectors $\mathbf{u}_1 := \begin{bmatrix} 2 & -1 \end{bmatrix}^T / \sqrt{5}$ and $\mathbf{u}_2 := \begin{bmatrix} 1 & 2 \end{bmatrix}^T / \sqrt{5}$ form an orthonormal basis for $\mathbb{R}^{2 \times 1}$. Hence let

$$\mathbf{C} := rac{1}{\sqrt{5}} \begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix}$$
 and $\mathbf{D} := \operatorname{diag}(3, -2).$

Then $\mathbf{C}^{\mathsf{T}}\mathbf{A}\mathbf{C} = \mathbf{D}$. Hence $Q(x, y) = Q_{\mathsf{D}}(u, v) = 3u^2 - 2v^2$, where $\begin{bmatrix} u \\ v \end{bmatrix} := \mathbf{C}^{\mathsf{T}} \begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$, that is, $u = (2x - y)/\sqrt{5}$ and $v = (x + 2y)/\sqrt{5}$. Thus substituting $x = (2u + v)/\sqrt{5}$ and $y = (-u + 2v)/\sqrt{5}$ in the given equation of the conic section, we obtain

$$3u^2 - 2v^2 - \frac{4}{\sqrt{5}}(2u + v) + \frac{10}{\sqrt{5}}(-u + 2v) - 13 = 0,$$

that is,

$$3u^2 - 2v^2 - \frac{1}{\sqrt{5}}(18u - 16v) - 13 = 0.$$

Completing the squares, we see that

$$\frac{(u-3/\sqrt{5})^2}{4} - \frac{(v-4/\sqrt{5})^2}{6} = 1.$$

This is an equation of a hyperbola with its centre $(3/\sqrt{5}, 4/\sqrt{5})$ in the *uv*-plane, where the *u*-axis and the *v*-axis are determined by the eigenvectors **u**₁ and **u**₂.

3. Consider the conic section given by $\overline{9x^2} + 24xy + 16y^2 - 20x + 15y = 0$, and the binary quadratic form $Q(x, y) := 9x^2 + 24xy + 16y^2$. Then the associated symmetric matrix $\mathbf{A} := \begin{bmatrix} 9 & 12 \\ 12 & 16 \end{bmatrix}$ has eigenvalues $\lambda_1 := 25$ and $\lambda_2 := 0$, and the corresponding eigenvectors $\mathbf{u}_1 := \begin{bmatrix} 3 & 4 \end{bmatrix}^{\mathsf{T}} / 5$ and $\mathbf{u}_2 := \begin{bmatrix} -4 & 3 \end{bmatrix}^T / 5$ form an orthonormal basis for $\mathbb{R}^{2 \times 1}$. Hence let $\mathbf{C} := \frac{1}{5} \begin{bmatrix} 3 & -4 \\ 4 & 3 \end{bmatrix}$ and $\mathbf{D} := \text{diag}(25, 0)$. Then $\mathbf{C}^{\mathsf{T}}\mathbf{A}\mathbf{C} = \mathbf{D}$. Thus $Q(x, y) = Q_{\mathsf{D}}(u, v) = 25u^2$, where $\begin{vmatrix} u \\ v \end{vmatrix} := \mathbf{C}^{\mathsf{T}} \begin{vmatrix} x \\ v \end{vmatrix} = \frac{1}{5} \begin{vmatrix} 3 & 4 \\ -4 & 3 \end{vmatrix} \begin{vmatrix} x \\ v \end{vmatrix},$ that is, u = (3x + 4y)/5 and v = (-4x + 3y)/5. Substituting x = (3u - 4v)/5 and y = (4u + 3v)/5 in the equation of the conic, we obtain $u^2 + 25v = 0$, an equation of a parabola with its vertex at (0,0) in the *uv*-plane.

Quadric Surfaces

A quadric surface is the locus in \mathbb{R}^3 of an equation $a x^2 + b y^2 + c z^2 + a'xy + b'yz + c'zx + a''x + b''y + c''z + d = 0$, where $a, b, c, a', b', c', a'', b'', c'', d \in \mathbb{R}$. We assume WLOG

that not all three a, b and c are negative.

Terms of the second degree on the LHS of the equation give

$$Q(x, y, z) := a x^{2} + b y^{2} + c z^{2} + a' xy + b' yz + c' zx.$$

It is a ternary quadratic form. It determines the type of the quadric surface. The real symmetric matrix associated with the quadratic form Q is

$$\mathbf{A} := egin{bmatrix} \mathbf{a} & a'/2 & c'/2 \ a'/2 & b & b'/2 \ c'/2 & b'/2 & c \end{bmatrix}.$$

Hence the equation of the given quadric surface becomes

$$\begin{bmatrix} x & y & z \end{bmatrix} \begin{bmatrix} a & a'/2 & c'/2 \\ a'/2 & b & b'/2 \\ c'/2 & b'/2 & c \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} + \begin{bmatrix} a'' & b'' & c'' \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} + d = 0,$$

that is,

 $\begin{bmatrix} x & y & z \end{bmatrix} \mathbf{A} \begin{bmatrix} x & y & z \end{bmatrix}^{\mathsf{T}} + \begin{bmatrix} a'' & b'' & c'' \end{bmatrix} \begin{bmatrix} x & y & z \end{bmatrix}^{\mathsf{T}} + d = 0.$ Let $\mathbf{C} := \begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 & \mathbf{u}_3 \end{bmatrix}$ be an orthogonal matrix whose columns \mathbf{u}_1 , \mathbf{u}_2 , \mathbf{u}_3 are eigenvectors of \mathbf{A} with corresponding eigenvalues λ_1 , λ_2 , λ_3 , and let $\mathbf{D} := \operatorname{diag}(\lambda_1, \lambda_2, \lambda_3)$.

We use the change of variables
$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \mathbf{C} \begin{bmatrix} u \\ v \\ w \end{bmatrix}$$
 to transform

the quadratic form Q(x, y, z) to a diagonal form as follows.

$$Q(x, y, z) = \begin{bmatrix} x & y & z \end{bmatrix} \mathbf{A} \begin{bmatrix} x & y & z \end{bmatrix}^{\mathsf{T}} \\
= \begin{bmatrix} u & v & w \end{bmatrix} \mathbf{C}^{\mathsf{T}} \mathbf{A} \mathbf{C} \begin{bmatrix} u & v & w \end{bmatrix}^{\mathsf{T}} \\
= \begin{bmatrix} u & v & w \end{bmatrix} \mathbf{D} \begin{bmatrix} u & v & w \end{bmatrix}^{\mathsf{T}} \\
= \lambda_1 u^2 + \lambda_2 v^2 + \lambda_3^2 w^2 = Q_{\mathsf{D}}(u, v, w).$$

The ordered orthonormal basis $(\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3)$ determines a new set of coordinate axes, so that the locus of the original equation is given by

$$\begin{bmatrix} u & v & w \end{bmatrix} \operatorname{diag}(\lambda_1, \lambda_2, \lambda_3) \begin{bmatrix} u \\ v \\ w \end{bmatrix} + \begin{bmatrix} a'' & b'' & c'' \end{bmatrix} \mathbf{C} \begin{bmatrix} u \\ v \\ w \end{bmatrix} + d = 0.$$

Leaving aside the degenerate cases, the primary cases are:

Equation	Surface	Eigenvalues of A
Equation $ \frac{x^{2}}{a^{2}} + \frac{y^{2}}{b^{2}} + \frac{z^{2}}{c^{2}} = 1 $ $ \frac{x^{2}}{a^{2}} + \frac{y^{2}}{b^{2}} - \frac{z}{c} = 0 $ $ \frac{x^{2}}{a^{2}} + \frac{y^{2}}{b^{2}} - \frac{z^{2}}{c^{2}} = 0 $ $ \frac{x^{2}}{a^{2}} + \frac{y^{2}}{b^{2}} - \frac{z^{2}}{c^{2}} = 1 $ $ \frac{x^{2}}{a^{2}} - \frac{y^{2}}{b^{2}} - \frac{z^{2}}{c^{2}} = 1 $ $ \frac{x^{2}}{a^{2}} - \frac{y^{2}}{b^{2}} - \frac{z^{2}}{c^{2}} = 1 $	Surface ellipsoid elliptic paraboloid elliptic cone 1-sheeted hyperboloid 2-sheeted hyperboloid	Eigenvalues of <i>A</i> all three positive two positive, one zero two positive, one negative two positive, one negative one positive, two negative
$\frac{x^2}{a^2} - \frac{y^2}{b^2} - \frac{z}{c} = 0$	hyperbolic paraboloid	one positive, one negative,
$\overline{a^2} - \overline{b^2} - \overline{c} = 0$		one zero.

Pictures of these surfaces can be found on the Internet by searching with their names.

Prof. S. R. Ghorpade, IIT Bombay Linear Algebra: Lecture 18