MA 110 Linear Algebra and Differential Equations Lecture 19

Prof. Sudhir R. Ghorpade Department of Mathematics IIT Bombay http://www.math.iitb.ac.in/~srg/

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Recall: In the last lecture, we proved the following theorem and then discussed its applications to classification of conic sections and quadric surfaces.

Theorem (Principal Axis Theorem)

Let Q be a real quadratic form and $\mathbf{A} \in \mathbb{R}^{n \times n}$ be the symmetric matrix associated with Q. If \mathbf{C} is an orthogonal matrix such that the matrix $\mathbf{D} := \mathbf{C}^{\mathsf{T}} \mathbf{A} \mathbf{C}$ is diagonal, then

$$Q(\mathbf{x}) = Q_{\mathsf{D}}(\mathbf{y}), \quad \text{where} \quad \mathbf{y} := \mathbf{C}^{\mathsf{T}} \mathbf{x} \text{ for all } \mathbf{x} \in \mathbb{R}^{n imes 1}.$$

Clarification about a Degenerate Conic: As discussed earlier, a **conic section** is the locus in \mathbb{R}^2 of an equation f(x, y) = 0, where $f(x, y) = ax^2 + by^2 + cxy + a'x + b'y + c'$, where $a, b, c, a', b', c' \in \mathbb{R}$ and at least one among a, b, c is nonzero. We call this **degenerate** if f(x, y) factors as a product of two linear polynomials (with coefficients in \mathbb{C}). This corresponds to the locus in \mathbb{R}^2 being a pair of lines (including the case of coincident lines), a single point, or the empty set.

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Equation	Surface	Eigenvalues of A
Equation $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$ $\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z}{c} = 0$	ellipsoid elliptic paraboloid	all three positive two positive, one zero
$\begin{vmatrix} \frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 0\\ \frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1\\ \frac{x^2}{a^2_2} - \frac{y^2}{b^2_2} - \frac{z^2}{c^2} = 1 \end{vmatrix}$	elliptic cone	two positive, one negative
	1-sheeted hyperboloid	two positive, one negative
	2-sheeted hyperboloid	one positive, two negative
$\frac{x^2}{a^2} - \frac{y^2}{b^2} - \frac{z}{c} = 0$	hyperbolic paraboloid	one positive, one negative,
		one zero.

We also discussed the above classification of quadric surface (leaving aside the degenrate cases).

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Example Consider the quadric surface given by

$$x^2 + y^2 + z^2 + 4xy + 4yz - 4zx - 27 = 0,$$

and the associated ternary quadratic form $Q(x, y, z) := x^2 + y^2 + z^2 + 4xy + 4yz - 4zx.$

We have already transformed the associated symmetric matrix $\mathbf{A} := \begin{bmatrix} 1 & 2 & -2 \\ 2 & 1 & 2 \\ -2 & 2 & 1 \end{bmatrix}$ to a diagonal form, and have obtained $Q(x, y, z) = Q_{\mathbf{D}}(u, v, w) = 3(u^2 + v^2 - w^2) \text{ (with } x_1, x_2, x_3 \text{ and } y_1, y_2, y_3 \text{ in place of } x, y, z \text{ and } u, v, w),$ where $\mathbf{D} := \text{diag}(3, 3, -3)$ and $u = (x+y)/\sqrt{2}, v = (-x+y+2z)/\sqrt{6}, w = (x-y+z)/\sqrt{3}.$ Under this change of coordinates, the quadric surface reduces

Under this change of coordinates, the quadric surface reduces to $u^2 + v^2 - w^2 = 9$.

This is an equation of a one-sheeted hyperboloid in the *uvw*-space, as shown in the following figure, where the *u*-axis, the *v*-axis and the *w*-axis are determined by the eigenvectors $\mathbf{u}_1 := \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \end{bmatrix}^T$, $\mathbf{u}_2 := \begin{bmatrix} -1/\sqrt{6} & 1/\sqrt{6} & 2/\sqrt{6} \end{bmatrix}^T$ and $\mathbf{u}_3 := \begin{bmatrix} 1/\sqrt{3} & -1/\sqrt{3} & 1/\sqrt{3} \end{bmatrix}^T$. (See Lecture 16.)



Orthogonal Projection

Let \mathbb{K} denote either \mathbb{R} or \mathbb{C} . Recall that in Lecture 13, we have defined the (perpendicular) projection of $\mathbf{x} \in \mathbb{K}^{n \times 1}$ in the direction of nonzero $\mathbf{y} \in \mathbb{K}^{n \times 1}$ as follows:

$$\mathsf{P}_{\mathbf{y}}(\mathbf{x}) := rac{\langle \mathbf{y}, \, \mathbf{x}
angle}{\langle \mathbf{y}, \, \mathbf{y}
angle} \mathbf{y}.$$

In particular, if **y** is a unit vector, then $P_{\mathbf{y}}(\mathbf{x}) = \langle \mathbf{y}, \mathbf{x} \rangle \mathbf{y}$.

We noted that the vector $P_{\mathbf{y}}(\mathbf{x})$ is a scalar multiple of the vector \mathbf{y} , and proved the important relation

$$(\mathbf{x} - P_{\mathbf{y}}(\mathbf{x})) \perp \mathbf{y}.$$

As a consequence,

$$\begin{aligned} \|\mathbf{x} - P_{\mathbf{y}}(\mathbf{x})\|^2 &= \langle \mathbf{x} - P_{\mathbf{y}}(\mathbf{x}), \, \mathbf{x} - P_{\mathbf{y}}(\mathbf{x}) \rangle \\ &= \langle \mathbf{x}, \, \mathbf{x} - P_{\mathbf{y}}(\mathbf{x}) \rangle \\ &= \|\mathbf{x}\|^2 - \langle \mathbf{x}, \, P_{\mathbf{y}}(\mathbf{x}) \rangle. \end{aligned}$$

More generally, let Y be a nonzero subspace of $\mathbb{K}^{n\times 1}$. We would like to find a (perpendicular) projection of $\mathbf{x} \in \mathbb{K}^{n\times 1}$ into Y, that is, we want to find $\mathbf{y} \in Y$ such that $(\mathbf{x} - \mathbf{y}) \in Y^{\perp}$. (This **y** is 'the foot of the perpendicular' from **x** into Y.)

If $\mathbf{u}_1, \ldots, \mathbf{u}_k$ is an orthonormal basis for the subspace Y, then a vector belongs to Y^{\perp} if and only if it is orthogonal to each \mathbf{u}_j for $j = 1, \ldots, k$. As we saw while studying G-S OP, the vector

$$\tilde{\mathbf{y}} := \mathbf{x} - P_{\mathbf{u}_1}(\mathbf{x}) - \cdots - P_{\mathbf{u}_k}(\mathbf{x}) = \mathbf{x} - \langle \mathbf{u}_1, \mathbf{x} \rangle \mathbf{u}_1 - \cdots - \langle \mathbf{u}_k, \mathbf{x} \rangle \mathbf{u}_k$$

is orthogonal to each \mathbf{u}_j for $j = 1, \ldots, k$, and so $\tilde{\mathbf{y}} \in Y^{\perp}$.

Since the vector $\mathbf{y} := \langle \mathbf{u}_1, \mathbf{x} \rangle \mathbf{u}_1 + \cdots + \langle \mathbf{u}_k, \mathbf{x} \rangle \mathbf{u}_k$ belongs to Y, it is a (perpendicular) projection of \mathbf{x} in Y.

The following result shows that this is the only vector in Y that works!

Proposition (Projection Theorem)

Let Y be a subspace of $\mathbb{K}^{n\times 1}$. Then for every $\mathbf{x} \in \mathbb{K}^{n\times 1}$, there are unique $\mathbf{y} \in Y$ and $\tilde{\mathbf{y}} \in Y^{\perp}$ such that $\mathbf{x} = \mathbf{y} + \tilde{\mathbf{y}}$, that is, $\mathbb{K}^{n\times 1} = Y \oplus Y^{\perp}$. The map $P_Y : \mathbb{K}^{n\times 1} \to \mathbb{K}^{n\times 1}$ given by $P_Y(\mathbf{x}) = \mathbf{y}$ is linear and satisfies $(P_Y)^2 = P_Y$. In fact, if $\mathbf{u}_1, \ldots, \mathbf{u}_k$ is an orthonormal basis for Y, then

$$\mathcal{P}_{\mathbf{Y}}(\mathbf{x}) = \langle \mathbf{u}_1, \, \mathbf{x} \rangle \mathbf{u}_1 + \cdots + \langle \mathbf{u}_k, \, \mathbf{x} \rangle \mathbf{u}_k.$$

Proof. If $Y = \{\mathbf{0}\}$, then every $\mathbf{x} \in Y^{\perp}$, and so $\mathbf{x} = \mathbf{0} + \mathbf{x}$. Suppose $Y \neq \{\mathbf{0}\}$, and let $\mathbf{u}_1, \ldots, \mathbf{u}_k$ be an orthonormal basis for Y. For $\mathbf{x} \in \mathbb{K}^{n \times 1}$, define

$$P_{Y}(\mathbf{x}) := \langle \mathbf{u}_{1}, \mathbf{x} \rangle \mathbf{u}_{1} + \cdots + \langle \mathbf{u}_{k}, \mathbf{x} \rangle \mathbf{u}_{k}.$$

Clearly, $\mathbf{y} := P_Y(\mathbf{x}) \in Y$. Define $\tilde{\mathbf{y}} := \mathbf{x} - P_Y(\mathbf{x})$. Then

$$\begin{split} \langle \mathbf{u}_j, \, \tilde{\mathbf{y}} \rangle &= \langle \mathbf{u}_j, \, \mathbf{x} - \mathcal{P}_Y(\mathbf{x}) \rangle \\ &= \langle \mathbf{u}_j, \, \mathbf{x} \rangle - \sum_{\ell=1}^k \langle \mathbf{u}_\ell, \, \mathbf{x} \rangle \langle \mathbf{u}_j, \, \mathbf{u}_\ell \rangle \\ &= \langle \mathbf{u}_j, \, \mathbf{x} \rangle - \langle \mathbf{u}_j, \, \mathbf{x} \rangle = 0 \end{split}$$

for j = 1, ..., k by orthonormality. Hence $\tilde{\mathbf{y}} \in Y^{\perp}$. Thus $\mathbf{x} = \mathbf{y} + \tilde{\mathbf{y}}$ with $\mathbf{y} \in Y$ and $\tilde{\mathbf{y}} \in Y^{\perp}$. This proves existence.

To prove uniqueness, let $z \in Y$ and $\tilde{z} \in Y^{\perp}$ be such that $x = z + \tilde{z}$. Then $(y - z) \in Y$ and also $y - z = (\tilde{z} - \tilde{y}) \in Y^{\perp}$, so that $(y - z) \in Y \cap Y^{\perp}$. Hence $(y - z) \perp (y - z)$, and so y - z = 0. Thus z = y, and in turn, $\tilde{z} = \tilde{y}$.

The map P_Y is linear since the inner product is linear in the second variable. Also, $P_Y(\mathbf{u}_j) = \mathbf{u}_j$ for all j = 1, ..., k. Hence $P_Y(\mathbf{x}) = \mathbf{x}$ if and only if $\mathbf{x} \in Y$. As a consequence, $P_Y^2(\mathbf{x}) = P_Y(P_Y(\mathbf{x})) = P_Y(\mathbf{x})$ for all $\mathbf{x} \in \mathbb{K}^{n \times 1}$.

Let Y be a subspace of $\mathbb{K}^{n \times 1}$. Then the linear map $P_Y : \mathbb{K}^{n \times 1} \to \mathbb{K}^{n \times 1}$ whose existence and uniqueness is proved in the above result is called the **orthogonal projection map** of $\mathbb{K}^{n \times 1}$ onto the subspace Y.

Given $\mathbf{x} \in \mathbb{K}^{n \times 1}$, we shall show that its orthogonal projection $P_Y(\mathbf{x})$ is the unique vector in Y which is closest to \mathbf{x} .

Definition

Let *E* be a nonempty subset of $\mathbb{K}^{n \times 1}$ and let $\mathbf{x} \in \mathbb{K}^{n \times 1}$. A **best approximation** to \mathbf{x} from *E* is an element $\mathbf{y}_0 \in E$ such that $\|\mathbf{x} - \mathbf{y}_0\| \le \|\mathbf{x} - \mathbf{y}\|$ for all $\mathbf{y} \in E$.

Simple examples show that a best approximation to a vector **x** from a nonempty subset *E* of $\mathbb{K}^{n \times 1}$ may not exist, and if it exists, it may not be unique. However, if *E* is in fact a subspace of $\mathbb{K}^{n \times 1}$, then the following noteworthy result holds.

Proposition

Let Y be a subspace of $\mathbb{K}^{n \times 1}$ and let $\mathbf{x} \in \mathbb{K}^{n \times 1}$. Then there is a unique best approximation to \mathbf{x} from Y, namely, $P_Y(\mathbf{x})$. Further, $P_Y(\mathbf{x})$ is the unique element of Y such that $\mathbf{x} - P_Y(\mathbf{x})$ is orthogonal to Y. Also, the square of the distance from \mathbf{x} to its best approximation from Y is

$$\|\mathbf{x} - P_Y(\mathbf{x})\|^2 = \|\mathbf{x}\|^2 - \langle \mathbf{x}, P_Y(\mathbf{x}) \rangle.$$

Proof. We note that $P_Y(\mathbf{x}) \in Y$ and $(\mathbf{x} - P_Y(\mathbf{x})) \in Y^{\perp}$. Let $\mathbf{y} \in Y$. Then $P_Y(\mathbf{x}) - \mathbf{y}$ also belongs to Y. Hence by the Pythagorus theorem,

$$\begin{aligned} \|\mathbf{x} - \mathbf{y}\|^2 &= \|(\mathbf{x} - P_Y(\mathbf{x})) + (P_Y(\mathbf{x}) - \mathbf{y})\|^2 \\ &= \|\mathbf{x} - P_Y(\mathbf{x})\|^2 + \|P_Y(\mathbf{x}) - \mathbf{y}\|^2 \\ &\geq \|\mathbf{x} - P_Y(\mathbf{x})\|^2, \end{aligned}$$

where equality holds if and only if $\mathbf{y} = P_Y(\mathbf{x})$. This shows that

 $P_Y(\mathbf{x})$ is the unique best approximation to \mathbf{x} from Y.

Further, let $\mathbf{y} \in Y$ be such that $(\mathbf{x} - \mathbf{y}) \in Y^{\perp}$. Then $\mathbf{x} = \mathbf{y} + (\mathbf{x} - \mathbf{y})$, and since $\mathbb{K}^{n \times 1} = Y \oplus Y^{\perp}$, it follows that $\mathbf{y} = P_Y(\mathbf{x})$.



Applications to Approximate Solutions of Systems of Linear Equations

Consider the system of linear equations

$$\mathbf{A}\mathbf{x} = \mathbf{b} \quad \text{where} \quad \mathbf{A} \in \mathbb{K}^{m \times n} \text{ and } \mathbf{b} \in \mathbb{K}^{m \times 1}.$$

Clearly, if $\mathbf{A} = \begin{bmatrix} \mathbf{c}_1 & \cdots & \mathbf{c}_n \end{bmatrix}$ in terms of its *n* columns and if $\mathbf{x} := \begin{bmatrix} x_1 & \cdots & x_n \end{bmatrix}^{\mathsf{T}}$, then $\mathbf{A}\mathbf{x} = x_1\mathbf{c}_1 + \cdots + x_n\mathbf{c}_n = \mathbf{b}$. Thus

the system Ax = b has a solution $\iff b \in C(A)$.

Now what if $\mathbf{b} \notin \mathcal{C}(\mathbf{A})$? Then we can find an approximate solution to the linear system $\mathbf{A}\mathbf{x} = \mathbf{b}$ by finding the best approximation to \mathbf{b} from the subspace $\mathcal{C}(\mathbf{A})$ of $\mathbb{K}^{m \times 1}$. For this, we first find an ordered orthonormal basis $(\mathbf{u}_1, \ldots, \mathbf{u}_k)$ of $\mathcal{C}(\mathbf{A})$, where $k \leq n$. [This can be done using Gram-Schmidt OP.] Then the best approximation to \mathbf{b} from $\mathcal{C}(\mathbf{A})$ is

$$P_{\mathcal{C}(\mathbf{A})}(\mathbf{b}) = \sum_{j=1}^{k} \langle \mathbf{u}_{j}, \mathbf{b} \rangle \mathbf{u}_{j} = \sum_{j=1}^{k} (\mathbf{u}_{j}^{*}\mathbf{b})\mathbf{u}_{j}.$$

Example: Let
$$\mathbf{A} := \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$
 and $\mathbf{b} := \begin{bmatrix} 1 \\ 0 \\ -5 \end{bmatrix}$. Then $\mathcal{C}(\mathbf{A})$ is
the span of the 2 column vectors $\begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}}$ and $\begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\mathsf{T}}$
of \mathbf{A} . Then $\mathbf{u}_1 := \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \end{bmatrix}^{\mathsf{T}}$ and $\mathbf{u}_2 := \begin{bmatrix} \frac{1}{\sqrt{6}} & \frac{-1}{\sqrt{6}} & \frac{2}{\sqrt{6}} \end{bmatrix}^{\mathsf{T}}$ form
an orthonormal basis for $\mathcal{C}(\mathbf{A})$. Hence the best approximation
to \mathbf{b} from $\mathcal{C}(\mathbf{A})$ is $\langle \mathbf{u}_1, \mathbf{b} \rangle \mathbf{u}_1 + \langle \mathbf{u}_2, \mathbf{b} \rangle \mathbf{u}_2$, which is
 $\frac{1}{2} \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}} - \frac{3}{2} \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}^{\mathsf{T}} = \begin{bmatrix} -1 & 2 & -3 \end{bmatrix}_{\cdot}^{\mathsf{T}} = \mathbf{a}$ (say).

The distance from **b** to its best approximation **a** from $C(\mathbf{A})$ is

$$\|\mathbf{b} - \mathbf{a}\| = \|\begin{bmatrix} 2 & -2 & -2 \end{bmatrix}^{\mathsf{T}}\| = 2\sqrt{3}.$$

The square of this distance could also have been computed directly using the above proposition as follows:

$$\|\mathbf{b}\|^2 - |\langle \mathbf{u}_1, \, \mathbf{b} \rangle|^2 - |\langle \mathbf{u}_2, \, \mathbf{b} \rangle|^2 = 26 - \frac{1}{2} - \frac{27}{2} = 12,$$