

MA106 Tutorial Solutions

Linear Algebra (Indian Institute of Technology Bombay)



Scan to open on Studocu

Studocu is not sponsored or endorsed by any college or university Downloaded by Manish (mani.7805.singh@gmail.com) Department of Mathematics Indian Institute of Technology Bombay Powai, Mumbai 400076, India

MA 106 : Linear Algebra

Spring 2021

Instructors

Sudhir R. Ghorpade | Dipendra Prasad

Tutorial Solutions Booklet By Gyandev Gupta



Contents

1	Tutorial 1 (on Lectures 1 and 2)	1
2	Tutorial 2 (on Lectures 3, 4 and 5)	5
3	Tutorial 3 (on Lectures 6 and 7)	8
4	Tutorial 4 (on Lectures 8, 9 and 10)	13
5	Tutorial 5 (on Lectures 11, 12 and 13)	16
6	Tutorial 6 (on Lectures 14, 15 and 16)	19
7	Tutorial 7 (on Lectures 17, 18 and 19)	21
8	Tutorial 8 (on Lectures 20 and 21)	26

1 Tutorial 1 (on Lectures 1 and 2)

1.1 Let **A** be a square matrix. Show that there is a symmetric matrix **B** and there is a skew-symmetric matrix **C** such that $\mathbf{A} = \mathbf{B} + \mathbf{C}$. Are **B** and **C** unique?

Given **B** should be symmetric and **C** should be skew-symmetric such that $\overline{\mathbf{A} = \mathbf{B} + \mathbf{C}}$. Take transpose on both sides of this equation. This gives us $\mathbf{A}^{T} = \mathbf{B}^{T} + \mathbf{C}^{T} \Rightarrow \overline{\mathbf{A}^{T} = \mathbf{B} - \mathbf{C}}$. Solve these two boxed equations simultaneously to get $\mathbf{B} = \frac{\mathbf{A} + \mathbf{A}^{T}}{2}$ and $\mathbf{C} = \frac{\mathbf{A} - \mathbf{A}^{T}}{2}$. Thus we have $\mathbf{A} = \mathbf{B} + \mathbf{C}$ and clearly, **B** is symmetric and **C** is skew-symmetric. **By our solution**, **B and C must be unique**

1.2 Let $\mathbf{A} := \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$ and $\mathbf{B} := \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$. Write (i) the second row of \mathbf{AB} as a linear combination

of the rows of \mathbf{B} and (ii) the second column of \mathbf{AB} as a linear combination of the columns of \mathbf{A} .

(i) **AB** is a 3×3 matrix. The elements of the second row of **AB** are given by the expression: $AB_{2,j} = \sum_{k=1}^{2} A_{2,k}B_{k,j}$. Thus, the second row can be written as the linear combination of rows of B as follows:

 $3\begin{bmatrix}1 & 2 & 3\end{bmatrix} + 4\begin{bmatrix}4 & 5 & 6\end{bmatrix}$

(ii) Similarly, the second column of AB can be written as as the linear combination of columns of A as follows:

$$2\begin{bmatrix}1\\3\\5\end{bmatrix}+5\begin{bmatrix}2\\4\\6\end{bmatrix}$$

1.3 Let $\mathbf{A} := \begin{bmatrix} 1 & 1 & 1 & 0 \\ -3 & -17 & 1 & 2 \\ 4 & -24 & 8 & -5 \\ 0 & -7 & 2 & 2 \end{bmatrix}$. Assuming that \mathbf{A} is invertible, find the last column and the last row of \mathbf{A}^{-1} .

 $\mathbf{A}\mathbf{A}^{-1} = \mathbf{I}_{4}, \text{ Thus we have the following system of equations to get the last column of } \mathbf{A}^{-1}:$ $\begin{bmatrix} 1 & 1 & 1 & 0 \\ -3 & -17 & 1 & 2 \\ 4 & -24 & 8 & -5 \\ 0 & -7 & 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \text{ Solve this to get the last column of } \mathbf{A}^{-1}$ We get: $\begin{bmatrix} x_1 & x_2 & x_3 & x_4 \end{bmatrix}^T = \begin{bmatrix} 2.75 & -0.5 & -2.25 & 1 \end{bmatrix}^T$ Do a similar process to get the last row. Since we already know x_4 now we'll have to solve a

Do a similar process to get the last row. Since we already know x_4 , now we'll have to solve a system of only 3 equations and 3 unknowns. Last Row of $\mathbf{A}^{-1} = \begin{bmatrix} -1.5 & -0.5 & 0 & 1 \end{bmatrix}$



1.4 Show that the product of two upper triangular matrices is upper triangular. Is this true for lower triangular matrices?

Assume **A** and **B** are two upper triangular matrices. For these upper triangular matrices, A_{ij} and $B_{ij} = 0$ for i > j. We have to show that $AB_{ij} = 0$ for i > j also holds true. We have $AB_{ij} = A_i^T B_j$ where A_i^T is the ith row of A and B_j^T is the jth column of B.

Thus,
$$AB_{i,j} = A_i^T B_j = \sum_{k=1}^n A_{ik} B_{kj}$$
$$= \sum_{k=1}^j A_{ik} B_{kj} + \sum_{k=j+1}^n A_{ik} B_{kj}$$

Now given A, B are upper triangular. So $A_{ij} = 0, B_{ij} = 0$ for i > j. Here we are only checking AB_{ij} for i > j, so we get $\sum_{k=1}^{j} A_{ik}B_{kj} = 0$ since A_{ik} is zero in the summation. $\sum_{k=j+1}^{n} A_{ik}B_{kj} = 0$ since B_{kj} is zero in the summation.

Similarly we can show that product of two lower triangular matrix is also lower triangular but there we would consider i < j in our analysis.

1.5 The trace of a square matrix is the sum of its diagonal entries. Show that trace $(\mathbf{A}+\mathbf{B}) = \text{trace} (\mathbf{A}) + \text{trace} (\mathbf{B})$ and trace $(\mathbf{A}\mathbf{B}) = \text{trace} (\mathbf{B}\mathbf{A})$ for $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{n \times n}$.

Part (a) is trivial.

$$trace(AB) = \sum_{i=1}^{n} (AB)_{ii} = \sum_{i=1}^{n} \sum_{k=1}^{n} A_{ik} B_{ki}$$
$$trace(BA) = \sum_{i=1}^{n} (BA)_{ii} = \sum_{i=1}^{n} \sum_{k=1}^{n} B_{ik} A_{ki} = \sum_{k=1}^{n} \sum_{i=1}^{n} A_{ki} B_{ik}$$

We have just switched the order of summation as the two summations are over independent axes. Thus we see that trace(AB) = trace(BA) as the two expressions are equivalent

1.6 Find all solutions of the linear system $\mathbf{A}\mathbf{x} = \mathbf{b}$, where (i) $\mathbf{A} := \begin{vmatrix} 1 & 3 & -2 & 0 & 2 & 0 \\ 2 & 6 & -5 & -2 & 4 & -3 \\ 0 & 0 & 5 & 10 & 0 & 15 \\ 2 & 6 & 0 & 8 & 4 & 18 \end{vmatrix}$, $\mathbf{b} :=$

$$\begin{bmatrix} 0 & -1 & 6 & 6 \end{bmatrix}^{\mathsf{T}},$$

(ii) $\mathbf{A} := \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix}, \mathbf{b} := \begin{bmatrix} 5 & -2 & 9 \end{bmatrix}^{\mathsf{T}},$
(iii) $\mathbf{A} := \begin{bmatrix} 0 & 2 & -2 & 1 \\ 2 & -8 & 14 & -5 \\ 1 & 3 & 0 & 1 \end{bmatrix}$ and $\mathbf{b} := \begin{bmatrix} 2 & 2 & 8 \end{bmatrix}^{\mathsf{T}}$

by reducing **A** to a row echelon form.

(i) We perform the row operations to the augmented matrix $R_4 := R_4 - 2R_1$ $R_2 := R_2 - 2R_1$ $\begin{bmatrix} 1 & 3 & -2 & 0 & 2 & 0 & 0 \\ 0 & 0 & -1 & -2 & 0 & -3 & -1 \\ 0 & 0 & 5 & 10 & 0 & 15 & 6 \\ 0 & 0 & 4 & 8 & 0 & 18 & 6 \end{bmatrix}$ $R_3 := R_3 + 5R_2$ $\begin{bmatrix} 1 & 3 & -2 & 0 & 2 & 0 & 0 \\ 0 & 0 & -1 & -2 & 0 & -3 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 4 & 8 & 0 & 18 & 6 \end{bmatrix}$ Swap R_3 and R_4 $R_3 = R_3 + 4R_2$

The last row of the augmented matrix is inconsistent. So the system has no solution.

(ii) Performing row operations on the augmented matrix,

2	1	1	5
4	-6	0	-2
$\lfloor -2$	7	2	9



$R_2 := R_2 - 2R_1$	$\begin{bmatrix} 2 & 1 & 1 & 5 \\ 0 & -8 & -2 & -12 \\ -2 & 7 & 2 & 9 \end{bmatrix}$
$R_3 := R_3 + R_1$	$\begin{bmatrix} 2 & 1 & 1 & & 5 \\ 0 & -8 & -2 & & -12 \\ 0 & 8 & 3 & & 14 \end{bmatrix}$
$R_3 := R_3 + R_2$	$\left[\begin{array}{ccc c} 2 & 1 & 1 & 5 \\ 0 & -8 & -2 & -12 \\ 0 & 0 & 1 & 2 \end{array}\right]$

So we get $x_3 = 2$. Back-substituting in $8x_2 + 2x_3 = 12$ we get $x_2 = 1$ and back-substituting in $2x_1 + x_2 + x_3 = 5$, we get $x_1 = 1$. The solution is; $\mathbf{x} := \begin{bmatrix} 1 & 1 & 2 \end{bmatrix}^{\mathsf{T}}$

(iii) Here the augmented matrix is

0	2	-2	1	2
2	-8	14	-5	2
[1	3	0	1	8

Performing the following operations, we get; Swap R_1 and R_3

	$\left[\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$
$R_2 := R_2 - 2R_1$	$\left[\begin{array}{rrrrr rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$
Then $R_3 := 7R_3 + R_2$	$\left[\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$

Since the last row is 0, there are infinitely many solutions.

2 Tutorial 2 (on Lectures 3, 4 and 5)

Row1 Pivot1 = 1 Swap R_2 and R_3		
o ar	$\left[\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$	
$R_2 := R_2 - R_1$	$\left[\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$	
$Row2 Pivot2 = -1$ $R_2 := R_2/(-1)$		
	$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & -1 & 1 \end{bmatrix}$	
$R_1 := R_1 - 2R_2$	F 1 0 2 1]	
	$\begin{bmatrix} 1 & 0 & 3 & -1 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & 1 & -1 \end{bmatrix}$	
Row3 Pivot $3=1$		
$R_1 := R_1 - 3R_3$	$\left[\begin{array}{rrrrr}1 & 0 & 0 & 2\\0 & 1 & -1 & 1\\0 & 0 & 1 & -1\end{array}\right]$	
$R_2 := R_2 + R_3$	Г 1 0 0 2 Т	

2.2 Let $\mathbf{A} := \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$. Find \mathbf{A}^{-1} by Gauss-Jordan method.

2.3 An $m \times m$ matrix **E** is called an **elementary matrix** if it is obtained from the identity matrix **I** by an elementary row operation. Write down all elementary matrices.

(i) Let $\mathbf{A} \in \mathbb{R}^{m \times n}$. If an elementary row operation transforms \mathbf{A} to \mathbf{A}' , then show that $\mathbf{A}' = \mathbf{E}\mathbf{A}$, where \mathbf{E} is the corresponding elementary matrix.

This document is available on 5 Studocu

(ii) Show that every elementary matrix is invertible, and find its inverse.

(iii) Show that a square matrix \mathbf{A} is invertible if and only if it is a product of finitely many elementary matrices.

Part i

Each row operation is represented by ${\bf E_i}$ matrices. Let's take ${\bf E_1}, {\bf E_2}, {\bf E_k}$ be elementary row transformation matrix such that ${\bf E}={\bf E_1}{\bf E_2}....{\bf E_k}{\bf I}$ so we get

$$\mathbf{A}' = \mathbf{E_1}\mathbf{E_2}....\mathbf{E_k}\mathbf{A}$$

Finally

$$\mathbf{A}' = \mathbf{E}\mathbf{A}$$

Part ii

Earlier we got to know that $\mathbf{E} = \mathbf{E}_1 \mathbf{E}_2 \dots \mathbf{E}_k \mathbf{I}$, here we can see that E_i are elementary matrices which are invertible and hence the product of all such \mathbf{E}_i are invertible. We can get the inverse by

$$\begin{split} \mathbf{E}^{-1} &= (\mathbf{E_1}\mathbf{E_2}....\mathbf{E_k})^{-1} \\ \mathbf{E}^{-1} &= \mathbf{E_k}^{-1}\mathbf{E_{k-1}}^{-1}....\mathbf{E_1}^{-1} \end{split}$$

Think how can you prove part3 on the basis of first part and second part Part iii

A square matrix A is invertible if and only if you can row reduce A to an identity matrix I Let's take the forward case so we have been given matrix is invertible .So on performing k row operations we obtain I

$$\begin{split} \mathbf{E_1}\mathbf{E_2}....\mathbf{E_k}\mathbf{A} &= \mathbf{I}\\ \mathbf{A} &= \mathbf{E_k^{-1}}\mathbf{E_{k-1}^{-1}}....\mathbf{E_1^{-1}} \end{split}$$

Hence its proved

2.4 Let S and T be subsets of $\mathbb{R}^{n \times 1}$ such that $S \subset T$. Show that if S is linearly dependent then so is T, and if T is linearly independent then so is S. Does the converse hold?

Let $S = [v_1, v_2, ... v_s]$. Since $S \subset T$ let $T = [v_1, v_2, ... v_s, u_1, u_2, ... u_t]$. Now suppose if S is **Linearly dependant** then $\exists \alpha_1, \alpha_2...\alpha_s$ such that $\alpha_1 v_1 + \alpha_2 v_2... + \alpha_s v_s = 0$ and not all α_i are zero. Now let $\beta_1 v_1 + \beta_2 v_2 + ... + \beta_s v_s + \beta_{s+1} u_1 + \beta_{s+2} u_2 + ... \beta_{s+t} u_t = 0$. Put $\beta_{s+i} = 0$ where $i \ge 1$ and $\beta_i = \alpha_i$ for $i \le s$. So this tuple value of β isnt zero hence T is **Linearly dependant**.

If T is Linearly independent then the only solution for $\beta_1 v_1 + \beta_2 v_2 + ... + \beta_s v_s + \beta_{s+1} u_1 + \beta_{s+2} u_2 + ... + \beta_{s+t} u_t = 0$ is $\beta_i = 0$. Suppose if S is **Linearly dependent** then it means $\exists \alpha_1, \alpha_2...\alpha_s$ such that $\alpha_1 v_1 + \alpha_2 v_2... + \alpha_s v_s = 0$. Sp put $\beta_i = \alpha_i$ for $i \leq s$ and $\beta_{s+i} = 0$. This tuple satisfies the above equation yet $\beta \neq 0$. So this contradicts that T is Linearly independent. Hence S is **Linearly independent**

2.5 Are the following sets linearly independent?

(i) {
$$\begin{bmatrix} 1 & -1 & 1 \end{bmatrix}$$
, $\begin{bmatrix} 3 & 5 & 2 \end{bmatrix}$, $\begin{bmatrix} 1 & 2 & 1 \end{bmatrix}$, $\begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$ } $\subset \mathbb{R}^{1 \times 3}$,
(ii) { $\begin{bmatrix} 1 & 9 & 9 & 8 \end{bmatrix}$, $\begin{bmatrix} 2 & 0 & 0 & 3 \end{bmatrix}$, $\begin{bmatrix} 2 & 0 & 0 & 8 \end{bmatrix}$ } $\subset \mathbb{R}^{1 \times 4}$,
(iii) { $\begin{bmatrix} 1 & -1 & 0 \end{bmatrix}^{\mathsf{T}}$, $\begin{bmatrix} 3 & -5 & 2 \end{bmatrix}^{\mathsf{T}}$, $\begin{bmatrix} 1 & -2 & 1 \end{bmatrix}^{\mathsf{T}}$ } $\subset \mathbb{R}^{3 \times 1}$.

2.6 Given a set of s linearly independent row vectors $\{\mathbf{a}_1, \ldots, \mathbf{a}_i, \ldots, \mathbf{a}_j, \ldots, \mathbf{a}_s\}$ in $\mathbb{R}^{1 \times n}$ and $\alpha \in \mathbb{R}$, show that the set $\{\mathbf{a}_1, \ldots, \mathbf{a}_{i-1}, \mathbf{a}_i + \alpha \mathbf{a}_j, \mathbf{a}_{i+1}, \ldots, \mathbf{a}_j, \ldots, \mathbf{a}_s\}$ is linearly independent.

 $\begin{array}{l} c_1a_1+c_2a_2+\ldots c_ia_i+\ldots c_ja_j\ldots+c_sa_s=0.\\ \text{Since these vectors are linearly independant, } \forall_k\ c_k=0.\\ \text{Now consider } \beta_1a_1+\beta_2a_2+\ldots\beta_i(a_i+\alpha a_j)+\ldots\beta_ja_j\ldots+\beta_sa_s=0.\\ \text{So } \beta_1a_1+\beta_2a_2+\ldots\beta_ia_i+\ldots(\beta_j+\beta_i\alpha)a_j\ldots+\beta_sa_s=0.\\ \text{So } \beta_1=\beta_2=\ldots\beta i\ldots=\beta_s=0, \beta_j+\alpha\beta_i=0.\\ \text{Hence } \forall_k\beta_k=0. \text{ So this set of vectors is also linearly independant.} \end{array}$

2.7 Find the ranks of the following matrices.

(i)
$$\begin{bmatrix} 8 & -4 \\ -2 & 1 \\ 6 & -3 \end{bmatrix}$$
, (ii) $\begin{bmatrix} 0 & 8 & -1 \\ 1 & 2 & 0 \\ 0 & 0 & 3 \\ 0 & 4 & 5 \end{bmatrix}$.

2.8 Are the following subsets of $\mathbb{R}^{3\times 1}$ subspaces?

(i)
$$\{ \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix}^{\mathsf{T}} : x_1, x_2, x_3 \in \mathbb{R}, x_1 + x_2 + x_3 = 0 \},$$

(ii) $\{ \begin{bmatrix} x_1 + x_2 + x_3 & x_2 + x_3 & x_3 \end{bmatrix}^{\mathsf{T}} : x_1, x_2, x_3 \in \mathbb{R} \},$
(iii) $\{ \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix}^{\mathsf{T}} : x_1, x_2, x_3 \in \mathbb{R}, x_1 x_2 x_3 = 0 \}$
(:...) $\{ \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix}^{\mathsf{T}} : x_1, x_2, x_3 \in \mathbb{R}, x_1 x_2 x_3 = 0 \}$

(iv) $\{ [x_1 \ x_2 \ x_3]^+ : x_1, x_2, x_3 \in \mathbb{R}, |x_1|, |x_2|, |x_3| \le 1 \}.$

If so, find a basis for each, and also its dimension.

2.9 Describe all subspaces of \mathbb{R} , $\mathbb{R}^{2\times 1}$, $\mathbb{R}^{3\times 1}$ and $\mathbb{R}^{4\times 1}$. Can you visualise them geometrically?



3 Tutorial 3 (on Lectures 6 and 7)

- 3.1 Let V be a subspace of $\mathbb{R}^{n \times 1}$ with dim V = r, and let S be a finite subset of V such that span S = V. Suppose S has s elements. Show that (i) $s \ge r$, (ii) if s = r, then S is a basis for V, (iii) if s > r, then S contains basis for V.
- 3.2 Let $\mathbf{A}' \in \mathbb{R}^{m \times n}$ be in a REF. Show that the pivotal columns of \mathbf{A}' form a basis for the column space $\mathcal{C}(\mathbf{A}')$.
- 3.3 Let $\mathbf{A} \in \mathbb{R}^{m \times n}$. The set $\mathcal{R}(\mathbf{A})$ consisting of all linear combinations of the rows of \mathbf{A} is called the **row space** of \mathbf{A} . Show that $\mathcal{R}(\mathbf{A})$ is a subspace of $\mathbb{R}^{1 \times n}$. If \mathbf{A}' is obtained from \mathbf{A} by EROs, then prove that $\mathcal{R}(\mathbf{A}') = \mathcal{R}(\mathbf{A})$. Further, show that the dimension of $\mathcal{R}(\mathbf{A})$ is equal to the rank of \mathbf{A} .
- 3.4 Let $\mathbf{A} \in \mathbb{R}^{m \times n}$ and $\mathbf{B} \in \mathbb{R}^{n \times p}$. Show that rank $\mathbf{AB} \leq \min\{\operatorname{rank} \mathbf{A}, \operatorname{rank} \mathbf{B}\}$.

3.5 Let $\mathbf{A} := \begin{bmatrix} 0 & 0 & 0 & -2 & 1 \\ 0 & 2 & -2 & 14 & -1 \\ 0 & 2 & 3 & 13 & 1 \end{bmatrix}$. Find the rank and the nullity of \mathbf{A} . What is the dimension of the

solution space of the homogeneous equation $\mathbf{A}\mathbf{x} = \mathbf{0}$? If $\mathbf{b} := \begin{bmatrix} 2 & 2 & 3 \end{bmatrix}^{\mathsf{T}}$, find the general solution of $\mathbf{A}\mathbf{x} = \mathbf{b}$.

3.6 Prove that det $\begin{bmatrix} 1 & 1 & 1 \\ a & b & c \\ a^2 & b^2 & c^2 \end{bmatrix} = (b-a)(c-a)(c-b)$, where $a, b, c \in \mathbb{R}$. Also, prove an analogous

formula for a determinant of order n, known as the Vandermonde determinant.

$$\det \begin{bmatrix} 1 & 1 & 1 \\ a & b & c \\ a^2 & b^2 & c^2 \end{bmatrix}$$

Use $det(A) = det(A^T)$ and perform $R_k = R_k - R_1 \forall k=2$ to 3

$$\det \begin{bmatrix} 1 & a & a^2 \\ 1 & b & b^2 \\ 1 & c & c^2 \end{bmatrix} = \det \begin{bmatrix} 1 & a & a^2 \\ 0 & b - a & b^2 - a^2 \\ 0 & c - a & c^2 - a^2 \end{bmatrix} = (b - a)(c - a)(c - b)$$

Part 2 To prove general result use induction for n=2 we have

$$\det \left[\begin{array}{cc} 1 & 1\\ a_1 & a_2 \end{array} \right] = (a_2 - a_1)$$

Now assume it to be true for n-1 order matrix and if we are able to prove n order matrix from the n-1 order matrix we are done

$$\det \begin{bmatrix} 1 & 1 & 1 & 1 & \dots & \dots & 1 \\ a_1 & a_2 & a_3 & \dots & \dots & a_n \\ \vdots & \vdots & \vdots & \vdots \\ a_1^{n-1} & a_2^{n-1} & a_3^{n-1} & \dots & \dots & a_n^{n-1} \end{bmatrix} = \prod_{1 \le i < j \le n} (a_j - a_i)$$
$$det(A) = det(A^T)$$
$$det \begin{bmatrix} 1 & a_1 & a_1^2 & \dots & \dots & a_n^{n-1} \\ 1 & a_2 & a_2^2 & \dots & \dots & a_n^{n-1} \\ 1 & a_n & a_n^2 & \dots & \dots & a_n^{n-1} \end{bmatrix} = \prod_{1 \le i < j \le n} (a_j - a_i)$$
$$R_k = R_k - R_1 \forall k = 2 \text{ to n}$$
$$det \begin{bmatrix} 1 & a_1 & a_1^2 & a_1^2 & \dots & \dots & a_n^{n-1} \\ 0 & a_2 - a_1 & a_2^2 - a_1^2 & \dots & \dots & a_n^{n-1} - a_n^{n-1} \\ 0 & a_n - a_1 & a_n^2 - a_1^2 & \dots & \dots & a_n^{n-1} - a_n^{n-1} \end{bmatrix} - > eqn(I)$$
$$\prod_{1 \le j \le n} (a_j - a_1) \det \begin{bmatrix} 1 & a_2 + a_1 & \dots & \dots & \sum_{n=1}^{n-1} a_n^{n-2-i}a_i^i \\ \vdots & \vdots \\ 1 & a_n + a_1 & \dots & \dots & \sum_{n=1}^{n-1} a_n^{n-2-i}a_i^i \end{bmatrix}$$
Now keep on splitting the det by column wise starting from col(2) to col(n) and see only one non zero det would surive and others would vanish
$$\prod_{1 \le j \le n} (a_j - a_1) \det \begin{bmatrix} 1 & a_1 & a_1^2 & \dots & \dots & a_{n-1}^{n-2} \\ 1 & a_2 & a_2^2 & \dots & \dots & a_{n-1}^{n-2} \\ 1 & a_{n-1} & a_{n-1}^2 & \dots & \dots & a_{n-1}^{n-2} \\ \vdots & \vdots \\ 1 & a_{n-1} & a_{n-1}^2 & \dots & \dots & a_{n-1}^{n-2} \end{bmatrix}$$

This document is available on 9 **Studocu** Downloaded by Manish (mani.7805.singh@gmail.com)

$$\begin{split} \prod_{1 \leq i < j \leq n} (a_j - a_1) * \prod_{2 \leq j \leq n} (a_j - a_i) \\ \prod_{1 \leq j \leq n} (a_j - a_i) \\ & \text{Other method} \\ & \text{Look at eqn}(\mathbf{I}) \text{ matrix} \\ & \text{Use } \det(A) = \det(A^T) \text{ and consecutively perform } R_k = R_k - R_{k-1} * a_1 \forall \mathbf{k} = 2 \text{ to n Try out} \end{split}$$

3.7 For $n \in \mathbb{N}$, prove that

 $\det \begin{bmatrix} 0 & 0 & 0 & \dots & 0 & 0 & 1 \\ 0 & 0 & 0 & \dots & 0 & 1 & 0 \\ & & & \ddots & & & \\ & & & \ddots & & & \\ 0 & 1 & 0 & \dots & 0 & 0 & 0 \\ 1 & 0 & 0 & \dots & 0 & 0 & 0 \end{bmatrix} = (-1)^{n(n-1)/2}.$

Use induction Method: For n=1 we have,

det
$$\begin{bmatrix} 1 \end{bmatrix} = (-1)^{1(1-1)/2} = 1$$

Now assume it to be true for n-1 order matrix and if we are able to prove n order matrix from the n-1 order matrix we are done

To prove:: det $\begin{bmatrix} 0 & 0 & 0 & \dots & 0 & 0 & 1 \\ 0 & 0 & 0 & \dots & 0 & 1 & 0 \\ & & & \ddots & & & \\ 0 & 1 & 0 & \dots & 0 & 0 & 0 \\ 1 & 0 & 0 & \dots & 0 & 0 & 0 \end{bmatrix} = (-1)^{n(n-1)/2}$ $det \begin{bmatrix} 0 & 0 & 0 & \dots & 0 & 0 & 1 \\ 0 & 0 & 0 & \dots & 0 & 1 & 0 \\ & & & \ddots & & \\ 0 & 1 & 0 & \dots & 0 & 0 & 0 \\ 1 & 0 & 0 & \dots & 0 & 0 & 0 \end{bmatrix}$

Now if we expand via the first row to find det and use result of $det(A)_{n-1}$, we get

 $\begin{array}{c} 10 \\ \text{Downloaded by Manish} \ (\text{mani.7805.singh@gmail.com}) \end{array}$

$$(-1)^{n+1} \det \begin{bmatrix} 0 & 0 & 0 & \dots & 0 & 0 & 1 \\ 0 & 0 & 0 & \dots & 0 & 1 & 0 \\ & & & \ddots & & & \\ & & \ddots & & & & \\ 0 & 1 & 0 & \dots & 0 & 0 & 0 \\ 1 & 0 & 0 & \dots & 0 & 0 & 0 \end{bmatrix}_{n-1}$$
$$(-1)^{n+1} * (-1)^{(n-1)(n-2)/2} = (-1)^{n(n-1)/2}$$

3.8 For $n \in \mathbb{N}$, prove that

	$\frac{1}{2}$	$2 \\ 2$	$\frac{3}{3}$	· · ·	$n - 1 \\ n - 1$	${n \atop n}$	
1	3	3	3		n-1	n	(1)n+1
det	:	÷	÷		÷	÷	$= (-1)^{n+1}n.$
	n-1	n-1	n-1		n-1	n	
	n	n	n		n	n	

$$R_n \mapsto \frac{1}{n} R_n$$

$$R_i \mapsto R_i - iR_n$$
 for all $i \in \{1, \ldots, n-1\}$.

For example, in the case of n = 4, you should have arrived at the following conclusion:

	Γ1	2	3	4]		[0]	1	2	3]
1-4	2	2	3	4	$= 4 \det$	0	0	1	2
det	3	3	3	4		0	0	0	1
	4	4	4	4		[1	1	1	1

Write the general case.

Now, expand along the first column. This is simple to do as it has only one non-zero entry. (Note that you'll get a $(-1)^n$.)

Thus, you get that the original determinant equals the following expression:

$$(-1)^n n \det \begin{bmatrix} 1 & 2 & \cdots & n-1 \\ 0 & 1 & \cdots & n-2 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

Note that the determinant written above is just 1 as it's a triangular matrix with all diagonal entries 1.

Thus, the answer is $(-1)^n n$.



3.9 Find rank \mathbf{A} using determinants, where \mathbf{A} is

(i)
$$\begin{bmatrix} 0 & 2 & -3 \\ 2 & 0 & 5 \\ -3 & 5 & 0 \end{bmatrix}$$
, (ii) $\begin{bmatrix} 4 & 3 \\ -8 & -6 \\ 16 & 12 \end{bmatrix}$.

Verify by transforming ${\bf A}$ to a REF.

4 Tutorial 4 (on Lectures 8, 9 and 10)

4.1 Find the value(s) of α for which Cramer's rule is applicable. For the remaining value(s) of α , find the number of solutions, if any.

4.2 Find the cofactor matrix **C** of the matrix **A**, and verify $\mathbf{C}^{\mathsf{T}}\mathbf{A} = (\det \mathbf{A})\mathbf{I} = \mathbf{A}\mathbf{C}^{\mathsf{T}}$. If det $\mathbf{A} \neq 0$, find \mathbf{A}^{-1} , where **A** is

(i)
$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}$$
, (ii) $\begin{bmatrix} 0 & 9 & 5 \\ 2 & 0 & 0 \\ 0 & 2 & 0 \end{bmatrix}$, (iii) $\begin{bmatrix} 1 & 1/2 & 1/3 \\ 1/2 & 1/3 & 1/4 \\ 1/3 & 1/4 & 1/5 \end{bmatrix}$.

4.3 Find the matrix of the linear transformation $T : \mathbb{R}^{3\times 1} \to \mathbb{R}^{4\times 1}$ defined by $T(\begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix}^{\mathsf{T}}) := \begin{bmatrix} x_1 + x_2 & x_2 + x_3 & x_3 + x_1 & x_1 + x_2 + x_3 \end{bmatrix}^{\mathsf{T}}$ with respect to the ordered bases (i) $E = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ of $\mathbb{R}^{3\times 1}$ and $F = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3, \mathbf{e}_4)$ of $\mathbb{R}^{4\times 1}$,

(ii) $E' = (\mathbf{e}_1 + \mathbf{e}_2, \mathbf{e}_2 + \mathbf{e}_3, \mathbf{e}_3 + \mathbf{e}_1)$ of $\mathbb{R}^{3 \times 1}$ and $F' = (\mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3, \mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4, \mathbf{e}_3 + \mathbf{e}_4 + \mathbf{e}_1, \mathbf{e}_4 + \mathbf{e}_1 + \mathbf{e}_2)$ of $\mathbb{R}^{4 \times 1}$, first showing that E' is a basis for $\mathbb{R}^{3 \times 1}$ and F' is a basis for $\mathbb{R}^{4 \times 1}$.

Part(i) We have the basis set $E = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ of $\mathbb{R}^{3 \times 1}$ and $F = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3, \mathbf{e}_4)$ of $\mathbb{R}^{4 \times 1}$, $\mathbf{T}(\mathbf{e}_1) = \begin{bmatrix} 1 & 0 & 1 & 1 \end{bmatrix}^{\mathsf{T}} = \mathbf{1}\mathbf{e}_1 + \mathbf{0}\mathbf{e}_2 + \mathbf{1}\mathbf{e}_3 + \mathbf{1}\mathbf{e}_4$ $\mathbf{T}(\mathbf{e}_2) = \begin{bmatrix} 1 & 1 & 0 & 1 \end{bmatrix}^{\mathsf{T}} = \mathbf{1}\mathbf{e}_1 + \mathbf{1}\mathbf{e}_2 + \mathbf{0}\mathbf{e}_3 + \mathbf{1}\mathbf{e}_4$ $\mathbf{T}(\mathbf{e}_3) = \begin{bmatrix} 0 & 1 & 1 & 1 \end{bmatrix}^{\mathsf{T}} = \mathbf{0}\mathbf{e}_1 + \mathbf{1}\mathbf{e}_2 + \mathbf{1}\mathbf{e}_3 + \mathbf{1}\mathbf{e}_4$ $\mathbf{M}_F^E(T) = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ Part(ii) Check whether the set E' and set F' forms a basis set? Indeed yes they form (Try it out) $\mathbf{T}(\mathbf{e}_1 + \mathbf{e}_2) = \begin{bmatrix} 2 & 1 & 1 & 2 \end{bmatrix}^{\mathsf{T}} = \mathbf{0}(\mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3) + \mathbf{0}(\mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4) + \mathbf{1}(\mathbf{e}_3 + \mathbf{e}_4 + \mathbf{e}_1) + \mathbf{1}(\mathbf{e}_4 + \mathbf{e}_1 + \mathbf{e}_2)$ = $\mathbf{T}(\mathbf{e}_2 + \mathbf{e}_3) = \begin{bmatrix} 1 & 2 & 1 & 2 \end{bmatrix}^{\mathsf{T}} = \mathbf{0}(\mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3) + \mathbf{1}(\mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4) + \mathbf{0}(\mathbf{e}_3 + \mathbf{e}_4 + \mathbf{e}_1) + \mathbf{1}(\mathbf{e}_4 + \mathbf{e}_1 + \mathbf{e}_2)$ = $\mathbf{T}(\mathbf{e}_3 + \mathbf{e}_1) = \begin{bmatrix} 1 & 1 & 2 & 2 \end{bmatrix}^{\mathsf{T}} = \mathbf{0}(\mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3) + \mathbf{1}(\mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4) + \mathbf{1}(\mathbf{e}_3 + \mathbf{e}_4 + \mathbf{e}_1) + \mathbf{0}(\mathbf{e}_4 + \mathbf{e}_1 + \mathbf{e}_2)$ = $\mathbf{M}_{F''}^{E'}(T) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$

4.4 Let $\mathbf{A} \in \mathbb{R}^{4 \times 4}$. Let $\mathbf{P} := \begin{bmatrix} 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix}$. Show that \mathbf{P} is invertible. Find an ordered bases E of $\mathbb{R}^{4 \times 1}$ This document is available on **Studocu** Downloaded by Manish (mani.7805.singh@gmail.com) such that $\mathbf{P}^{-1}\mathbf{A}\mathbf{P} = \mathbf{M}_E^E(T_\mathbf{A}).$

Using the theorem we get $\mathbf{E} = \{\mathbf{P}_1, \mathbf{P}_2, \mathbf{P}_3, \mathbf{P}_4\}$

4.5 Let $\lambda \in \mathbb{K}$. Find the geometric multiplicity of the eigenvalue λ of each of the following matrices:

 $\mathbf{A} := \begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix}, \ \mathbf{B} := \begin{bmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix}, \ \mathbf{C} := \begin{bmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 1 \\ 0 & 0 & \lambda \end{bmatrix}.$

Also, find the eigenspace associated with λ in each case.

For $|\mathbf{A} - \mu \mathbf{I}| = 0 = (\mu - \lambda)^3$ its true for all vector $\mathbf{x} = (x_1, x_2, x_3)$ and hence eigen space is \mathbb{R}^3 For $|\mathbf{B} - \mu \mathbf{I}| = 0 = (\mu - \lambda)^3$ and for corresponding eigen vector $\mathbf{x} = (x_1, x_2, x_3)$ Solve $(\mathbf{B} - \lambda \mathbf{I})\mathbf{x} = 0 \implies \mathbf{x}_2 = 0$ and hence eigen space is \mathbb{R}^2 For $|\mathbf{C} - \mu \mathbf{I}| = 0 = (\mu - \lambda)^3$ and for corresponding eigen vector $\mathbf{x} = (x_1, x_2, x_3)$ Solve $(\mathbf{B} - \lambda \mathbf{I})\mathbf{x} = 0 \implies \mathbf{x}_2 = 0$, $x_3 = 0$ and hence eigen space is \mathbb{R}

4.6 Let $\mathbf{A} := \begin{bmatrix} 3 & 0 & 0 \\ -2 & 4 & 2 \\ -2 & 1 & 5 \end{bmatrix}$. Show that 3 is an eigenvalue of \mathbf{A} , and find all eigenvectors of \mathbf{A} corresponding to it. Also, show that $\begin{bmatrix} 0 & 1 & 1 \end{bmatrix}^{\mathsf{T}}$ is an eigenvector of \mathbf{A} , and find the corresponding eigenvalue of \mathbf{A} .

Check $|\mathbf{A} - 3\mathbf{I}| = 0$, we get det $\begin{bmatrix} 0 & 0 & 0 \\ -2 & 1 & 2 \\ -2 & 1 & 2 \end{bmatrix} = 0$ $\mathbf{A}\mathbf{x} = 3\mathbf{x}$, $\begin{bmatrix} 3 & 0 & 0 \\ -2 & 4 & 2 \\ -2 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 3 \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$

We get $x_1 = 0$ and $x_2 + 2x_3 = 0$. So all eigen vectors $\mathbf{x} = x_3(0, -2, 1)$ where $x_3 \in \mathbb{R}$ To prove $\begin{bmatrix} 0 & 1 & 1 \end{bmatrix}^\mathsf{T}$ is an eigenvector of \mathbf{A}

$$\begin{bmatrix} 3 & 0 & 0 \\ -2 & 4 & 2 \\ -2 & 1 & 5 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 6 \\ 6 \end{bmatrix} = 6 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

We get the eigen value to be 6.

4.7 Let $\theta \in (-\pi, \pi]$, $\mathbf{A} := \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ and $\mathbb{K} = \mathbb{C}$. Show that $\cos \theta \pm i \sin \theta$ are eigenvalues of \mathbf{A} . Find an invertible matrix \mathbf{P} such that $\mathbf{P}^{-1}\mathbf{A}\mathbf{P}$ is a diagonal matrix, and check your answer.

For
$$|\mathbf{A} - \mu \mathbf{I}| = 0$$
,

$$\det \left(\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} - \mu \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0$$

$$\det \left(\begin{bmatrix} \cos \theta - \mu & -\sin \theta \\ \sin \theta & \cos \theta - \mu \end{bmatrix} \right) = 0$$

$$\mu^2 - 2\mu \cos \theta + 1 = 0 \implies \mu = \cos \theta \pm i \sin \theta$$

$$\mathbf{x} = (x_1, x_2) \text{ where } x_1, x_2 \in \mathbb{C}$$

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \mu \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
We get $\cos \theta x_1 - \sin \theta x_2 = (\cos \theta - i \sin \theta) x_1 \implies x_2 = i x_1$
We get $\mathbf{x} = x_1(1, i)$ where $x_1 \in \mathbb{C}$
For other eigen value $\cos \theta x_1 + \sin \theta x_2 = (\cos + i \sin \theta) x_1 \implies x_2 = -i x_1$
We get $\mathbf{x} = x_1(1, -i)$ where $x_1 \in \mathbb{C}$

$$\mathbf{P} := \begin{bmatrix} 1 & 1 \\ i & -i \end{bmatrix} \text{ and Check it } \mathbf{P}^{-1} \mathbf{A} \mathbf{P} = \begin{bmatrix} \cos \theta - i \sin \theta & 0 \\ 0 & \cos + i \sin \theta \end{bmatrix}$$

4.8 Let $n \ge 2$ and $\mathbf{A} := \begin{bmatrix} 1 & \cdots & 1 \\ \vdots & \vdots & \vdots \\ 1 & \cdots & 1 \end{bmatrix} \in \mathbb{R}^{n \times n}$, that is, $a_{jk} = 1$ for all $j, k = 1, \dots, n$. Find rank \mathbf{A} and

nullity **A**. Find an eigenvector of **A** corresponding to a nonzero eigenvalue by inspection. Find two distinct eigenvalues of **A** along with their geometric multiplicities, and find bases for the eigenspaces. Show that **A** is diagonalizable, and find an invertible matrix **P** such that $\mathbf{P}^{-1}\mathbf{A}\mathbf{P}$ is a diagonal matrix.

 $\begin{aligned} Rank\mathbf{A} &= 1, Nullity\mathbf{A} = n - 1\\ \text{Eigen vector} &= \begin{bmatrix} 1 & 1 & \dots & 1 \end{bmatrix}^T \text{ for eigen value} = n\\ \text{To find } |\mathbf{A} - \mu \mathbf{I}| &= 0, \text{ Swap all rows initially and perform } R_1 \mapsto \sum_{i=1}^n R_i \text{ and take } (n-\mu) \text{ common}\\ \text{and then } R_k \mapsto R_k - R_1 \forall \mathbf{k} = 2 \text{ to n and then expand via last column}\\ \text{we get } \mu^{n-1}(\mu - n) = 0 \implies \mu = 0 \text{ GM is n-1}, \mu = n \text{ GM is 1}\\ \text{Now find eigen vectors corresponding to all eigen values } (\mathbf{A} - \mu \mathbf{I})\mathbf{x} = 0 \text{ we get}\\ \text{For } \mu = 0, v = \{ \mathbf{x} : \sum_{i=1}^n x_i = 0 \}\\ \text{For } \mu = n \text{ we get } \mathbf{v} = x_1(1, 1, 1, 1, \dots)^T \forall x_1 \in \mathbb{R} \mathbf{P} := \begin{bmatrix} -1 & -1 & -1 & 1 & 1\\ 1 & 0 & 0 & \dots & 0 & 1\\ 0 & 1 & 0 & \dots & 0 & 1\\ 0 & 0 & 1 & \dots & 0 & 1\\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots\\ 0 & 0 & 0 & \dots & 1 & 1 \end{bmatrix}\\ \text{Perform } \mathbf{P}^{-1}\mathbf{A}\mathbf{P} \text{ to get to a diagonal matrix} \end{aligned}$



5 Tutorial 5 (on Lectures 11, 12 and 13)

5.1 Find all eigenvalues, and their geometric as well as algebraic multiplicities of the following matrices. Are they diagonalizable? If so, find invertible \mathbf{P} such that $\mathbf{P}^{-1}\mathbf{A}\mathbf{P}$ is a diagonal matrix.

(i)
$$\mathbf{A} := \begin{bmatrix} 5 & -1 \\ 1 & 3 \end{bmatrix}$$
, (ii) $\mathbf{A} := \begin{bmatrix} 3 & 2 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 2 & -1 & 0 \\ 0 & 0 & 0 & 1/2 \end{bmatrix}$, (iii) $\mathbf{A} := \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{bmatrix}$.

Similar to exercise 4.7 and 4.8

5.2 Let
$$\mathbf{A} := \begin{bmatrix} 2 & a & b \\ 0 & 1 & c \\ 0 & 0 & 2 \end{bmatrix}$$
. Find a necessary and sufficient condition on a, b, c for \mathbf{A} to be diagonalizable.

You can easily see eigen values are 2,1,2 Just you need to check for nullspace $(\mathbf{A} - \mu \mathbf{I})\mathbf{x} = 0$ or find nullity for $\mu = 2$ $\begin{bmatrix} 2 - \mu & a & b \\ 0 & 1 - \mu & c \\ 0 & 0 & 2 - \mu \end{bmatrix} \mapsto \begin{bmatrix} 0 & a & b \\ 0 & -1 & c \\ 0 & 0 & 0 \end{bmatrix}$ So for nullity equal to 2 we need rank =1 hence R_2 must to be a scalar multiple of R_1 $\frac{a}{-1} = \frac{b}{c} \implies b=-ac$

5.3 Let $k \in \mathbb{N}$ and

	[0	-1	0	0	0	•••	•••	0]	
	1	0	0	0	0	• • •	•••	0	
	0	0	0	-1	0	•••	•••	0	
	0	0	1	0	0	•••	•••	0	
$\mathbf{A} :=$	0	0	0	0	0	·		0	$\in \mathbb{K}^{2k \times 2k}$
	:	÷	۰.	۰.	·	۰.	۰.	÷	
	0	• • •		0	0	0	0	-1	
	0	•••	•••	0	0	0	1	0	

that is, **A** has all diagonal entries 0, the subdiagonal entries are 1, 0, 1, 0, ..., 1, 0, and the superdiagonal entries are -1, 0, -1, 0, ..., -1, 0. Find the characteristic polynomial of **A**, all eigenvalues of **A**, and their algebraic as well as geometric multiplicities.

Take $(\mathbf{A} - \mu \mathbf{I})$ and perform $R_{2i} \mapsto R_{2i} + R_{2i-1}/\mu \forall i=1$ to k There was a catch that $\mu \neq 0$ (how would you prove that). Hint (find nullity of A) It's a Upper triangular matrix and whose det is product of diagonal entries $\mu^k(\mu + 1/\mu)^k = 0 \implies (\mu^2 + 1)^k = 0 \implies \mu = \pm i$ Find Nullity of $(\mathbf{A} - i\mathbf{I})$ by performing $R_{2i} \mapsto R_{2i} - iR_{2i-1} \forall i=1$ to k Characteristic polynomial is $(\mathbf{A}^2 + 1)^k = 0$

5.4 Let $\lambda \in \mathbb{K}$. Show that λ is an eigenvalue of **A** if and only if $\overline{\lambda}$ is an eigenvalue of **A**^{*}, but their eigenvectors can be very different.

For forward part,

$$\lambda \|\mathbf{x}\|^2 = \lambda \langle x, x \rangle = \langle x, \lambda x \rangle = \langle x, Ax \rangle$$

Transformation property: $\langle Ax, y \rangle = (Ax)^* y = x^* (A * y) \langle x, A^* y \rangle$

 $\lambda \|\mathbf{x}\|^2 = \langle A^* x, x \rangle$

Take conjugate on both sides

$$\overline{\lambda} \|\mathbf{x}\|^2 = \overline{\langle A^* x, x \rangle}$$

$$\overline{\lambda} \|\mathbf{x}\|^2 = \langle x, A^* x \rangle$$

Similarly prove the backward part (Try it) Other method: $|\mathbf{A} - \lambda \mathbf{I}| = 0$. Choose $\mathbf{B} = \mathbf{A} - \lambda \mathbf{I}$ and we get det(B) = 0 We can claim that det(B^{*})=0. So $\mathbf{B}^* = \mathbf{A}^* - \overline{\lambda}\mathbf{I}$. Now $|\mathbf{A}^* - \overline{\lambda}\mathbf{I}| = 0$ hence $\overline{\lambda}$ is an eigen value of \mathbf{A}^*

5.5 Let $\mathbf{A} \in \mathbb{K}^{n \times n}$. Show that 0 is an eigenvalue of \mathbf{A} if and only if 0 is an eigenvalue of $\mathbf{A}^*\mathbf{A}$, and its geometric multiplicity is the same. Deduce rank $\mathbf{A}^*\mathbf{A} = \operatorname{rank} \mathbf{A}$.

 $\begin{array}{l} \mathbf{A}x=0 \implies A^*Ax=0 \implies x \in N(A^*A)\\ N(A) \subseteq N(A^*A)\\ \text{Now consider } A*Ax=0 \implies x^*A^*Ax=0 \implies (Ax)^*Ax=0 \implies Ax=0 \implies x \in N(A)\\ N(A^*A) \subseteq N(A)\\ \text{Hence } N(A) = N(A^*A)\\ \text{All part follows from this because geometric multiplicity of 0 is nullity of the matrix.} \end{array}$

5.6 Let $\mathbf{A} := \begin{bmatrix} 2 & i & 1+i \\ -i & 3 & 1 \\ 1-i & -1 & 8 \end{bmatrix}$. Show that no eigenvalue of \mathbf{A} is away from one of the diagonal entries of \mathbf{A} by more than $1 + \sqrt{2}$.

By the Gerschgorin Theorem we know $|\lambda - a_{jj}| \leq \sum_{j \neq k} |a_{jk}|$ Lets calculate $\sum_{j \neq k} |a_{jk}|$ for j=1 it's $1 + \sqrt{2}$ For j=2 it's 2, For j=3 it's $1 + \sqrt{2}$

5.7 A square matrix $\mathbf{A} := [a_{jk}]$ is called **strictly diagonally dominant** if $|a_{jj}| > \sum_{k \neq j} |a_{jk}|$ for each $j = 1, \ldots, n$. If \mathbf{A} strictly diagonally dominant, show that \mathbf{A} is invertible.

By the Gerschgorin Theorem we know $|\lambda - a_{jj}| \leq \sum_{j \neq k} |a_{jk}|$ We have $\lambda - a_{jj} > -\sum_j |a_{jk}| \mapsto I$ We already have that $|a_{jj}| > \sum_{k \neq j} |a_{jk}| \implies a_{jj} - \sum_{k \neq j} |a_{jk}| > 0 \mapsto II$ From I and II we get $\lambda > 0$ hence the matrix is invertible

5.8 Let $\mathbf{A} \in \mathbb{K}^{n \times n}$. Define $\alpha_2 := \max\{\|\mathbf{A}\mathbf{x}\| : \|\mathbf{x}\| = 1\}$, $\alpha_{\infty} := \max\{\sum_{k=1}^{n} |a_{jk}| : j = 1, \dots, n\}$ and $\alpha_1 := \max\{\sum_{j=1}^{n} |a_{jk}| : k = 1, \dots, n\}$, where $\mathbf{A} := [a_{jk}]$. Show that $|\lambda| \le \min\{\alpha_2, \alpha_{\infty}, \alpha_1\}$ for every eigenvalue λ .



consider λ to be max of all eigen value $\alpha_2 \geq \|\mathbf{A}\mathbf{x}\| = \|\lambda\mathbf{x}\| = |\lambda|$ By the Gerschgorin Theorem we know $|\lambda - a_{jj}| \leq \sum_{j \neq k} |a_{jk}|$ $||\lambda| - |a_{jj}|| \leq |\lambda - a_{jj}| \leq \sum_{j \neq k} |a_{jk}| \implies |\lambda| - |a_{jj}| \leq \sum_{j \neq k} |a_{jk}|$ $||\lambda| - |a_{jj}|| \leq \sum_{j \neq k} |a_{jk}| \implies |\lambda| - |a_{jj}| \leq \sum_{j \neq k} |a_{jk}|$ $|\lambda| = |a_{jj}| + \sum_{j \neq k} |a_{jk}| \leq \alpha_{\infty}$ Eigen values of \mathbf{A} and \mathbf{A}^T are same and performing same operations as we did above we can say $|\lambda| \leq \alpha_1$ Other method (An Important General result): Let (λ, \mathbf{x}) be eigen pair s.t $\rho(\mathbf{A}) = max|\lambda|$ Find $\mathbf{y} \neq 0$ s.t $\mathbf{x}\mathbf{y}^*$ is a non zero matrix , $\|.\|$ is a matrix norm $\lambda \mathbf{x} = \mathbf{A}\mathbf{x} \implies \lambda \mathbf{x}\mathbf{y}^* = \mathbf{A}\mathbf{x}\mathbf{y}^* \implies |\lambda| \|\mathbf{x}\mathbf{y}^*\| = \|\mathbf{A}\mathbf{x}\mathbf{y}^*\| \leq \|\mathbf{A}\|\|\mathbf{x}\mathbf{y}^*\| \implies \rho(\mathbf{A}) \leq \|\mathbf{A}\|$

5.9 Let $\mathbf{x}, \mathbf{y} \in \mathbb{K}^{n \times 1}$. Prove the **parallelogram law**: $\|\mathbf{x} + \mathbf{y}\|^2 + \|\mathbf{x} - \mathbf{y}\|^2 = 2\|\mathbf{x}\|^2 + 2\|\mathbf{y}\|^2$. In case \mathbf{x} and \mathbf{y} are both nonzero, prove the **cosine law**, which says that $\|\mathbf{x} - \mathbf{y}\|^2 = \|\mathbf{x}\|^2 + \|\mathbf{y}\|^2 - 2\|\mathbf{x}\|\|\mathbf{y}\|\cos\theta$, where the angle $\theta \in [0, \pi]$ between nonzero \mathbf{x} and \mathbf{y} is defined to be $\cos^{-1}(\Re \langle \mathbf{x}, \mathbf{y} \rangle / \|\mathbf{x}\| \|\mathbf{y}\|)$.

Part.a) You need to use $\|\mathbf{x} + \mathbf{y}\|^2 = \langle \mathbf{x} + \mathbf{y}, \mathbf{x} + \mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{x} + \mathbf{y} \rangle + \langle \mathbf{y}, \mathbf{x} + \mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{x} \rangle + \langle \mathbf{x}, \mathbf{y} \rangle + \langle \mathbf{y}, \mathbf{x} \rangle + \langle \mathbf{y}, \mathbf{y} \rangle$ and Similarly for the other term $\|\mathbf{x} - \mathbf{y}\|^2 = \langle \mathbf{x} - \mathbf{y}, \mathbf{x} - \mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{x} - \mathbf{y} \rangle + \langle -\mathbf{y}, \mathbf{x} - \mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{x} \rangle - \langle \mathbf{x}, \mathbf{y} \rangle - \langle \mathbf{y}, \mathbf{x} \rangle + \langle \mathbf{y}, \mathbf{y} \rangle$ Part.b) $(\Re \langle x, y \rangle) = \|\mathbf{x}\| \|\mathbf{y}\| \cos \theta$ where $\theta \in [0, \pi]$

6 Tutorial 6 (on Lectures 14, 15 and 16)

- 6.1 Orthonormalize the following ordered subsets of $\mathbb{K}^{4\times 1}$.
 - (i) $(\mathbf{e}_1, \mathbf{e}_1 + \mathbf{e}_2, \mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3, \mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4)$
 - (ii) $\mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4, -\mathbf{e}_1 + \mathbf{e}_2, -\mathbf{e}_1 + \mathbf{e}_3, -\mathbf{e}_1 + \mathbf{e}_4).$
- 6.2 Use the Gram-Schmidt Orthogonalization Process to orthonormalize the ordered subset

 $(\begin{bmatrix} 1 & -1 & 2 & 0 \end{bmatrix}^{\mathsf{T}}, \begin{bmatrix} 1 & 1 & 2 & 0 \end{bmatrix}^{\mathsf{T}}, \begin{bmatrix} 3 & 0 & 0 & 1 \end{bmatrix}^{\mathsf{T}})$

and obtain an ordered orthonormal set $(\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3)$. Also, find \mathbf{u}_4 such that $(\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4)$ is an ordered orthonormal basis for $\mathbb{K}^{4 \times 1}$. Express the vector $\begin{bmatrix} 1 & -1 & 1 & -1 \end{bmatrix}^{\mathsf{T}}$ as a linear combination of these four basis vectors.

Let W be the subspace of
$$\mathbb{K}^{4\times 1}$$
 spanned by the vectors $\mathbf{x}_1 := \begin{bmatrix} 1 & -1 & 2 & 0 \end{bmatrix}^{\mathsf{T}}$,
 $\mathbf{x}_2 := \begin{bmatrix} 1 & 1 & 2 & 0 \end{bmatrix}^{\mathsf{T}}$ and $\mathbf{x}_3 := \begin{bmatrix} 3 & 0 & 0 & 1 \end{bmatrix}^{\mathsf{T}}$ Let us apply the G-S OP.
Let $u_1 := \frac{x_1}{\|x_1\|} = \frac{\begin{bmatrix} 1 & -1 & 2 & 0 \end{bmatrix}^{\mathsf{T}}}{\sqrt{6}}$,
 $u_2 := \frac{x_2 - P_{u_1}(x_2)}{\|x_2 - P_{u_1}(x_2)\|} = \frac{\begin{bmatrix} 1 & 5 & 2 & 0 \end{bmatrix}^{\mathsf{T}}}{\sqrt{30}}$
 $u_3 := \frac{x_3 - P_{u_1}(x_3) - P_{u_2}(x_3)}{\|x_3 - P_{u_2}(x_3)\|} = \frac{\begin{bmatrix} 12 & 0 & -6 & 5 \end{bmatrix}^{\mathsf{T}}}{\sqrt{205}}$
You can check for yourself that $\{u_1, u_2, u_3\}$ is an orthonormal basis
To extend $\{u_1, u_2, u_3\}$ to an orthonormal basis for $\mathbf{V} := \mathbb{K}^{4\times 1}$, we look for $u_4 := \begin{bmatrix} \alpha_1 & \alpha_2 & \alpha_3 & \alpha_4 \end{bmatrix}^{\mathsf{T}}$
which is orthogonal to the set $\{x_1, x_2, x_3\}$. Try on your own

- 6.3 Show that $\mathbf{A} \in \mathbb{K}^{n \times n}$ is unitary if and only if its rows form an orthonormal subset of $\mathbb{K}^{1 \times n}$.
- 6.4 Let $E := (\mathbf{e}_1, \dots, \mathbf{e}_n)$ be the standard basis for $\mathbb{K}^{n \times 1}$, and let $F := (\mathbf{u}_1, \dots, \mathbf{u}_n)$ be an orthonormal basis for $\mathbb{K}^{n \times 1}$. If I denotes the identity map from $\mathbb{K}^{n \times 1}$ to $\mathbb{K}^{n \times 1}$, then show that the matrix $\mathbf{M}_E^F(I)$ is unitary.
- 6.5 Let $\mathbf{A} \in \mathbb{C}^{n \times n}$ and let λ be an eigenvalue of \mathbf{A} . Show that $p(\lambda)$ is an eigenvalue of $p(\mathbf{A})$ for every polynomial p(t).
- 6.6 Suppose $\mathbf{A} \in \mathbb{C}^{3 \times 3}$ satisfies $\mathbf{A}^3 6\mathbf{A}^2 + 11\mathbf{A} = 6\mathbf{I}$. If $5 \leq \det \mathbf{A} \leq 7$, determine the eigenvalues of \mathbf{A} . Is \mathbf{A} diagonalizable?
- 6.7 Let $\mathbf{A} \in \mathbb{K}^{n \times n}$, and let $\lambda_1, \ldots, \lambda_n$ be the eigenvalues of \mathbf{A} with a corresponding orthonormal set of eigenvectors $\mathbf{u}_1, \ldots, \mathbf{u}_n$. Show that $\mathbf{A} = \lambda_1 \mathbf{u}_1 \mathbf{u}_1^* + \cdots + \lambda_n \mathbf{u}_n \mathbf{u}_n^*$. $(\mathbf{x}\mathbf{y}^* = \text{outer product of } \mathbf{x}, \mathbf{y})$
- 6.8 Let $\mathbf{A} \in \mathbb{K}^{n \times n}$, and $\lambda \in \mathbb{K}$.
 - (i) Show that λ is an eigenvalue of **A** if and only $\overline{\lambda}$ is an eigenvalue of **A**^{*}.

(ii) Let **A** be unitary. Show that $\|\mathbf{A}\mathbf{x}\| = \|\mathbf{x}\|$ for all $\mathbf{x} \in \mathbb{K}^{n \times 1}$. If λ is an eigenvalue of **A**, then show that $|\lambda| = 1$.

(iii) Let $\mathbb{K} = \mathbb{C}$ and let **A** skew self-adjoint. If λ is an eigenvalue of **A**, then show that $i\lambda \in \mathbb{R}$.

This document is available on 19 Studocu Downloaded by Manish (mani.7805.singh@gmail.com)

- 6.9 Let $\mathbf{A} := [a_{jk}] \in \mathbb{C}^{n \times n}$, and let $\lambda_1, \ldots, \lambda_n$ be the eigenvalues of \mathbf{A} , counting algebraic multiplicities. Show that \mathbf{A} is normal $\iff \sum_{1 \le j,k \le n} |a_{jk}|^2 = \sum_{j=1}^n |\lambda_j|^2$.
- 6.10 A matrix $\mathbf{A} \in \mathbb{K}^{n \times n}$ is called **nilpotent** if there is $m \in \mathbb{N}$ such that $\mathbf{A}^m = \mathbf{O}$. If \mathbf{A} is upper triangular with all diagonal entries equal to 0, then show that \mathbf{A} is nilpotent. Further, if $\mathbf{A} \in \mathbb{C}^{n \times n}$, then show that \mathbf{A} is nilpotent if and only if 0 is the only eigenvalue of \mathbf{A} .

Tutorial 7 (on Lectures 17, 18 and 19) 7

- 7.1 Let $\mathbf{A} \in \mathbb{C}^{n \times n}$. Show that \mathbf{A} is self-adjoint if and only if \mathbf{A} is normal and all eigenvalues of \mathbf{A} are real.
- 7.2 State and prove a spectral theorem for skew self-adjoint matrices with complex entries.
- 7.3 Find an orthonormal basis for $\mathbb{K}^{4\times 1}$ consisting of eigenvectors of

$$\mathbf{A} := \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & -4 \\ 0 & 0 & -4 & -1 \end{bmatrix}.$$

Write down a spectral representation of **A**, and find $\mathbf{A}^{7}\mathbf{x}$, where $\mathbf{x} := \begin{bmatrix} 1 & 2 & 3 & 4 \end{bmatrix}^{\mathsf{T}}$

- 7.4 A self adjoint matrix **A** is called **positive definite** if $\langle \mathbf{A} \mathbf{x}, \mathbf{x} \rangle > 0$ for all nonzero $\mathbf{x} \in \mathbb{K}^{n \times 1}$. Show that a self-adjoint matrix is positive definite if and only if all eigenvalues of **A** are positive.
- 7.5 Real numbers $\alpha_1, \alpha_2, \alpha_3, \alpha_4$ are placed on the 4 corners of a square in clockwise order initially. In the next step,
 - α_1 is replaced by $\beta_1 := (\alpha_2 + \alpha_4)/2$,
 - α_2 is replaced by $\beta_2 := (\alpha_3 + \alpha_1)/2$,
 - α_3 is replaced by $\beta_3 := (\alpha_4 + \alpha_2)/2$ and
 - α_4 is replaced by $\beta_4 := (\alpha_1 + \alpha_3)/2$.

Find the numbers placed on the corners of the square after k such steps. (Hint: Find a set of 4

orthonormal eigenvectors of the matrix $\mathbf{A} := \begin{bmatrix} 0 & 1/2 & 0 & 1/2 \\ 1/2 & 0 & 1/2 & 0 \\ 0 & 1/2 & 0 & 1/2 \\ 1/2 & 0 & 1/2 & 0 \end{bmatrix}$ and use the spectral theorem

for \mathbf{A} .)

7.6 Let Q be a real quadratic form, and let A denote the associated real symmetric matrix. Let $g(\mathbf{x}) =$ $\|\mathbf{x}\|^2 - 1$. If \mathbb{Q} has a local extremum at a vector \mathbf{x}_0 subject to the constraint $g(\mathbf{x}) = 0$, then show that \mathbf{x}_0 is a unit eigenvector of \mathbf{A} , and the corresponding eigenvalue λ_0 is the corresponding Lagrange multiplier and equals $Q(\mathbf{x}_0)$.

In particular, the largest eigenvalue of \mathbf{A} is the constrained maximum and the smaller eigenvalue of **A** is the constrained minimum of Q.

7.7 Which quadric surface does the equation $7x^2 + 7y^2 - 2z^2 + 20yz - 20zx - 2xy - 36 = 0$ describe? Explain by reducing the quadratic form involved to a diagonal form. Express x, y, z in terms of the new coordinates u, v, w.

 $\mathbf{Q}(x) = 7x^2 + 7y^2 - 2z^2 + 20yz - 20zx - 2xy - 36 \text{ to a diagonal form.}$ Here $\mathbf{A} := \begin{bmatrix} 7 & -1 & -10 \\ -1 & 7 & 10 \\ -10 & 10 & -2 \end{bmatrix}$ is the associated matrix. Hence the equation of the given quadric surface becomes

> This document is available on 21 Studocu Downloaded by Manish (mani.7805.singh@gmail.com)

$$\begin{bmatrix} x & y & z \end{bmatrix} \begin{bmatrix} 1 & -1 & -10 \\ -1 & 7 & 10 \\ -10 & 10 & -2 \end{bmatrix} \begin{bmatrix} x & y & z \end{bmatrix}^T - 36 = 0$$

Now find eigen value and corresponding eigen vector and then using GSOP find $\{u_1, u_2, u_3\}$
Change of variable from $\begin{bmatrix} x & y & z \end{bmatrix}^T = \mathbf{C} \begin{bmatrix} u & v & w \end{bmatrix}^T$, where $\mathbf{C} = [\mathbf{u}_1 \mathbf{u}_2 \mathbf{u}_3]$
Characteristic polynomial is $\lambda^3 - 12\lambda - 180\lambda + 1296 = 0$
Eigen values are $\{18, -12, 6\}$
Eigen vectors are $\{\begin{bmatrix} -1 & 1 & 1 \end{bmatrix}^T, \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}^T, \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^T\}$
By GSOP Orthonormal eigen vectors are $\{\begin{bmatrix} -1 & 1 & 1 \end{bmatrix}^T, \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}^T, \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}^T, \begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^T\}$
 $\mathbf{Q}_D(u, v, w) = 18u^2 - 12v^2 + 6w^2$
The quadric surface reduces to $18u^2 - 12v^2 + 6w^2 = 36$
Since eigen values two positive, one negative its **1 sheeted hyperboloid**
 $\begin{bmatrix} x & y & z \end{bmatrix}^T = \mathbf{C} \begin{bmatrix} u & v & w \end{bmatrix}^T$
 $\begin{bmatrix} x & y & z \end{bmatrix}^T = \begin{bmatrix} \frac{-1}{\sqrt{3}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & \frac{\sqrt{2}}{\sqrt{6}} & 0 \end{bmatrix} \begin{bmatrix} u & v & w \end{bmatrix}^T$
 $x = \frac{-1}{\sqrt{3}}u + \frac{1}{\sqrt{6}}v + \frac{1}{\sqrt{2}}w, y = \frac{1}{\sqrt{3}}u + \frac{-1}{\sqrt{6}}v + \frac{1}{\sqrt{2}}w, z = \frac{1}{\sqrt{3}}u + \frac{2}{\sqrt{6}}v + 0w$

7.8 Let Y be a subspace of $\mathbb{K}^{n \times 1}$. Show that $(Y^{\perp})^{\perp} = Y$.

F 7

10]

Let $\{u_1, u_2, ..., u_k\}$ and $\{w_1, w_2, ..., w_l\}$ be an orthonormal basis for subspace respectively Y and Y^{\perp} Every vector $\mathbf{s} \in (Y^{\perp})^{\perp}$ will be perpendicular to $w_j \forall j=1$ to 1 Any vector can be represented in the form of $\mathbf{s} = \mathbf{x} + \mathbf{y}$ where $x \in Y$ and $y \in Y^{\perp}$ $\langle s, w_j \rangle = 0 \forall j$ $\langle x + y, \sum \alpha_j w_j \rangle = 0 \forall j$ Since $\langle x, w_j \rangle = 0$ and $y \in Y^{\perp} \exists$ some α_j s.t. $y = \sum \alpha_j w_j$ $\langle \sum \alpha_j w_j, \sum \alpha_j w_j \rangle = 0 \forall j$ It gives us all $\alpha'_i s$ are zero, so y=0, then $s \in Y$ Hence every vector in $(Y^{\perp})^{\perp}$ lies in Y, i.e $(Y^{\perp})^{\perp} \subseteq Y$ Now let $\mathbf{x} \in Y$ then $x = \sum \alpha_j u_j$ $\langle x, w_i \rangle = \langle \sum \alpha_j u_j, w_i \rangle = 0$ So $x \in W^{\perp} \implies x \in (Y^{\perp})^{\perp} \implies Y \subseteq (Y^{\perp})^{\perp}$

7.9 Let **A** be a self-adjoint matrix. If $\langle \mathbf{A}\mathbf{x}, \mathbf{x} \rangle = 0$ for all $\mathbf{x} \in \mathbb{K}^{n \times 1}$, then show that $\mathbf{A} = \mathbf{O}$. Deduce that

if $\|\mathbf{A}^*\mathbf{x}\| = \|\mathbf{A}\mathbf{x}\|$ for all $\mathbf{x} \in \mathbb{K}^{n \times 1}$, then \mathbf{A} is a normal matrix, and if $\|\mathbf{A}\mathbf{x}\| = \|\mathbf{x}\|$ for all $\mathbf{x} \in \mathbb{K}^{n \times 1}$, then \mathbf{A} is a unitary matrix.

Part i Self adjoint $\mathbf{A}^* = \mathbf{A}$ and $\langle \mathbf{A}\mathbf{x}, \mathbf{x} \rangle = \mathbf{x}^* \mathbf{A}^* \mathbf{x} = \mathbf{x}^* \mathbf{A}\mathbf{x} = 0, \forall \mathbf{x} \in \mathbb{K}^{n \times 1}$ Choose $\mathbf{x} = \mathbf{e}_k$ you get $a_{kk} = 0 \forall k = 1$ to n Choose $\mathbf{x} = \mathbf{e}_k + \mathbf{e}_j$ and we get $a_{kj} + a_{jk} = 0 \ \forall \ \mathbf{k}, \mathbf{j} = 1$ to n and $k \neq j$ Choose $\mathbf{x} = \mathbf{e}_k - i\mathbf{e}_j$ and we get $a_{kj} - a_{jk} = 0 \ \forall \ \mathbf{k}, \mathbf{j} = 1$ to n and $k \neq j$ Hence $\mathbf{A} = \mathbf{O}$ Part ii) Choose $\mathbf{B} = \mathbf{A}\mathbf{A}^* - \mathbf{A}^*\mathbf{A}, \mathbf{B} = \mathbf{B}^*$ $\|\mathbf{A}^*\mathbf{x}\| = \|\mathbf{A}\mathbf{x}\|$ Square on both sides $\|\mathbf{A}^*\mathbf{x}\|^2 = \|\mathbf{A}\mathbf{x}\|^2 \implies \langle \mathbf{A}^*\mathbf{x}, \mathbf{A}^*\mathbf{x} \rangle = \langle \mathbf{A}\mathbf{x}, \mathbf{A}\mathbf{x} \rangle$ $(\mathbf{A}^*\mathbf{x})^*\mathbf{A}^*\mathbf{x} = \langle \mathbf{x}, \, \mathbf{A}^*\mathbf{A}\mathbf{x} \rangle \implies \mathbf{x}^*\mathbf{A}\mathbf{A}^*\mathbf{x} = \mathbf{x}^*\mathbf{A}^*\mathbf{A}\mathbf{x}$ We get $\langle \mathbf{Bx}, \mathbf{x} \rangle = 0$ Hence \mathbf{A} is normal Part iii) Choose $\mathbf{B} = \mathbf{A}\mathbf{A}^* - \mathbf{I}, \mathbf{B} = \mathbf{B}^*$ $\|\mathbf{A}\mathbf{x}\| = \|\mathbf{x}\|$ Square on both sides $\|\mathbf{A}\mathbf{x}\|^2 = \|\mathbf{x}\|^2 \implies \langle \mathbf{A}\mathbf{x}, \mathbf{A}\mathbf{x} \rangle = \langle \mathbf{x}, \mathbf{x} \rangle$

 $\langle \mathbf{x}, \, \mathbf{A}^* \mathbf{A} \mathbf{x} \rangle = \langle \mathbf{x}, \, \mathbf{x} \rangle \implies \mathbf{x}^* \mathbf{A}^* \mathbf{A} \mathbf{x} = \mathbf{x}^* \mathbf{x}$

We get $\langle \mathbf{B}\mathbf{x}, \, \mathbf{x} \rangle = 0$

Hence \mathbf{A} is unitary

7.10 Let E be a nonempty subset of $\mathbb{K}^{n \times 1}$.

(i) If E is not closed, then show that there is $\mathbf{x} \in \mathbb{K}^{n \times 1}$ such that no best approximation to \mathbf{x} exists from E.

(ii) If E is convex, then show that for every $\mathbf{x} \in \mathbb{K}^{n \times 1}$, there is at most one best approximation to \mathbf{x} from E.

Part i

Definition: A non empty subset E of $\mathbb{K}^{n \times 1}$ is not closed, then $\exists \mathbf{x} \in \mathbb{K}^{n \times 1}$ and a sequence (x_n) of points of E s.t $x_n \mapsto x$, but $\mathbf{x} \notin E$ Suppose x had a best approximation from E, say y then



 $||x - y|| \le ||x - u|| \forall u \in E$ $||x - y|| \le ||x - x_n|| \forall n \in N$

Now by passing limit we get $||x - y|| \le 0 \implies ||x - y|| = 0 \implies x = y$ But it is a contradiction since $x \notin E$ and $y \in E$ Part ii **Definition**: A set E is convex if $u, v \in E \iff (1-\lambda)u + \lambda v \in E \ \forall \lambda \in [0, 1]$ Suppose there are u_1 and u_2 two best approximations from E to \mathbf{x} s.t $||\mathbf{x} - u_i|| = \lambda$ Since E is convex the line joining u_1 and u_2 lies in E $||\mathbf{x} - \frac{u_1 + u_2}{2}|| = ||\frac{\mathbf{x} - u_1}{2} + \frac{\mathbf{x} - u_2}{2}|| \le ||\frac{\mathbf{x} - u_1}{2}|| + ||\frac{\mathbf{x} - u_2}{2}|| = \lambda$ But then it contradicts the definition of best approximation Hence atmost one approximation

7.11 Find $\mathbf{x} := [x_1, x_2]^{\mathsf{T}} \in \mathbb{R}^{2 \times 1}$ such that the straight line $t = x_1 + x_2 s$ fits the data points (-1, 2), (0, 0), (1, -3) and (2, -5) best in the 'least squares' sense.

The data points are (s,t) = (-1,2), (0,0), (1,-3) and (2,-5)

$$\mathbf{Ax} = \mathbf{b} \implies \begin{bmatrix} 1 & -1 \\ 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ -3 \\ -5 \end{bmatrix}$$

To minimise, we need to find the best approximation to the vector ${\bf b}$ from the column space ${\bf C}({\bf A})$

 $\mathbf{A} = [\mathbf{y}_1 \mathbf{y}_2] \text{ and } \mathbf{u}_1 = \frac{y_1}{||y_1||} = \frac{\begin{bmatrix} 1 & 1 & 1 \end{bmatrix}^T}{\sqrt{4}} \text{ and } \mathbf{u}_2 = \frac{\begin{bmatrix} -1 & 0 & 1 & 2 \end{bmatrix}^T}{\sqrt{6}}$ Best approximation is $\langle \mathbf{u}_1, b \rangle \mathbf{u}_1 + \langle \mathbf{u}_2, b \rangle \mathbf{u}_2 = \begin{bmatrix} 1 & -1.5 & -4 & -6.5 \end{bmatrix}^T$ Now solve $x_1 - x_2 = -1$ and $x_1 + x_2 = -4$ gives $x_1 = -2.5, x_2 = -1.5$

7.12. Let $Q(x_1, \ldots, x_n) := \sum_{j=1}^n \sum_{k=1}^n \alpha_{jk} x_k \overline{x}_j$, where $\alpha_{jk} \in \mathbb{C}$, be a **complex quadratic form**. Show that there is a unique self-adjoint matrix **A** such that

 $Q(x_1,\ldots,x_n) = \mathbf{x}^* \mathbf{A} \mathbf{x}$ for all $\mathbf{x} := \begin{bmatrix} x_1 & \cdots & x_n \end{bmatrix}^\mathsf{T} \in \mathbb{C}^{n \times 1}.$

 $Q(x_1, \dots, x_n) = \sum_{j=1}^n \sum_{k=1}^n \alpha_{jk} x_k \overline{x}_j = \overline{Q} = \sum_{j=1}^n \sum_{k=1}^n \overline{\alpha_{jk} x_k} x_j$ The variable j,k are dummy variable for the summation $Q = \sum_{j=1}^n \sum_{k=1}^n \overline{\alpha_{kj} x_j} x_k \implies \alpha_{jk} = \overline{\alpha_{kj}}$ To prove uniqueness: Suppose $Q = \sum_{j=1}^n \sum_{k=1}^n \alpha_{jk} x_k \overline{x}_j = \sum_{j=1}^n \sum_{k=1}^n \beta_{jk} x_k \overline{x}_j$

Choose $\mathbf{x} = \mathbf{e}_k$ you get $\alpha_{kk} = \beta_{jj} \forall k = 1$ to n where k=jChoose $\mathbf{x} = \mathbf{e}_k + \mathbf{e}_j$ and we get $\alpha_{kj} + \alpha_{jk} = \beta_{kj} + \beta_{jk} \forall k, j = 1$ to n and $k \neq j$ Choose $\mathbf{x} = \mathbf{e}_k - i\mathbf{e}_j$ and we get $\alpha_{kj} - \alpha_{jk} = \beta_{kj} - \beta_{jk} \forall k, j = 1$ to n and $k \neq j$

Hence unique

7.13. Let $\mathbf{A} \in \mathbb{C}^{n \times n}$ be normal, and let μ_1, \ldots, μ_k be the distinct eigenvalues of \mathbf{A} . Let $Y_j := \mathcal{N}(\mathbf{A} - \mu_j \mathbf{I})$ for $j = 1, \ldots, k$. Show that $\mathbb{C}^{n \times 1} = Y_1 \oplus \cdots \oplus Y_k$. Also, if P_j is the orthogonal projection onto Y_j , then show that $P_1 + \cdots + P_k = I$, $P_i P_j = O$ if $i \neq j$ and $\mathbf{A}\mathbf{x} = \mu_1 P_1(\mathbf{x}) + \cdots + \mu_k P_k(\mathbf{x})$ for all $\mathbf{x} \in \mathbb{C}^{n \times 1}$.

Since **A** is normal, it is unitarily diagonalizable. So \mathbb{C}^n has a basis of eigen vectors of **A** The form would be $\{u_{11}, ..., u_{1g_1}, ..., u_{k1}, u_{k2}, ..., u_{kg_k}\}$ where g_j = geometric multiplicity of $\mu_j = dim \mathcal{N}(\mathbf{A} - \mu_j \mathbf{I})$ and $\mu_{j1}, ..., \mu_{jg_j}$ are eigen vectors of eigen value μ_j for j=1,2,...,k. We know $g_1 + g_2 \dots + g_k = n$ and since **A** is diagonalizable. So given any $\mathbf{x} \in \mathbb{C}^n$ we can write

$$x = \sum_{j=1}^{k} \sum_{l=1}^{g_j} \alpha_{jl} u_{jl} = y_1 + y_2 + \dots + y_k$$

where $y_j = \sum_{l=1}^{g_j} \alpha_{jl} u_{jl} \in Y_j = \mathcal{N}(\mathbf{A} - \mu_j \mathbf{I})$. Thus $\mathbb{C}^n = Y_1 + \cdots + Y_k$ Since coefficients α_{jl} are uniquely determined by $\mathbf{x}, \alpha_{jl} = \langle u_{jl}, x \rangle$, hence the decomposition is unique and we get $\mathbb{C}^n = Y_1 \oplus \cdots \oplus Y_k$

The orthogonal projection map is defined by $P_j(x) = y_j$ $(1 \le j \le k)$ and it is clear that $x = P_1(x) + \dots + P_k(x) \ \forall x \in \mathbb{C}^n$ So $P_1 + \dots P_k = I$ Also $P_i P_j = P_i(y_j) = 0$ if $i \ne j$. Thus $P_i P_j = 0$ if $i \ne j$ Finally since $y_j \in \mathcal{N}(\mathbf{A} - \mu_j \mathbf{I})$, we get $\mathbf{A}y_j = \mu_j y_j$

$$\mathbf{A}\mathbf{x} = \mathbf{A}\mathbf{y}_1 + \dots \mathbf{A}\mathbf{y}_k$$
$$\mathbf{A}\mathbf{x} = \mu_1 \mathbf{y}_1 + \dots \mu_k \mathbf{y}_k$$
$$\mathbf{A}\mathbf{x} = \mu_1 P_1(\mathbf{x}) + \dots + \mu_k P_k(\mathbf{x}) \forall x \in \mathbb{C}^n$$



8 Tutorial 8 (on Lectures 20 and 21)

- 8.1 State why the following sets are not subspaces:
 - (i) All $m \times n$ matrices with nonnegative entries.
 - (ii) All solutions of the differential equation $xy' + y = 3x^2$.
 - (iii) All solutions of the differential equation $y' + y^2 = 0$.
 - (iv) All invertible $n \times n$ matrices.
 - (a) $\alpha \mathbf{M}$ if $\alpha < 0$ then it doesn't lie in subspace
 - (b) $xy'_1 + y_1 = 3x^2$ and $xy'_2 + y_2 = 3x^2$ and $x(y_1 + y_2)' + y_1 + y_2 3x^2 = 3x^2 \neq 0$ it doesn't lie in subspace
 - (c) $y'_1 + y^2_1 = 0$ and $y'_2 + y^2_2 = 0$ and $(y_1 + y_2)' + (y_1 + y_2)^2 = 2y_1y_2 \neq 0$ it doesn't lie in subspace
 - (d) $det(\mathbf{A}), det(\mathbf{B}) \neq 0$ but det(A+B) can be zero if det(A) = -det(B) its not invertible and hence doesnt lie
- 8.2 Let V denote the vector space of all polynomial functions on \mathbb{R} of degree at most n. Are the following subsets of V in fact subspaces of V? (i) $W_1 := \{p \in V : p(0) = 0\},\$
 - (ii) $W_2 := \{ p \in V : p'(0) = 0 = p''(0) \},\$
 - (iii) $W_3 := \{ p \in V : p \text{ is an odd function} \}.$

If so, find a spanning set for each.

- 8.3 Let $V := C([-\pi, \pi])$. Show that $S_1 := \{1, \cos, \sin\}$ is a linearly independent subset of V, while $S_2 := \{1, \cos^2, \sin^2\}$ is a linearly dependent subset of V.
- 8.4 Let $V := \mathbb{R}^{1 \times 2}$, and let $v_1 := [1 \ 0], v_2 := [1 \ 1], v_3 := [1 \ -1]$. Explain why (24, 12) can be written as a linear combination of v_1, v_2, v_3 in two different ways, namely, $4v_1 + 16v_2 + 4v_3$ and $6v_1 + 15v_2 + 3v_3$.
- 8.5 Let $n \in \mathbb{N}$. Let W_1, W_2, W_3, W_4 denote the subspaces of $n \times n$ real matrices which are diagonal, upper triangular, symmetric and skew-symmetric. Find their dimensions.
- 8.6 Let V and W be vector spaces over K. Show that $V \times W := \{(v, w) : v \in V \text{ and } w \in W\}$ is a vector space over K with componentwise addition and scalar multiplication. If dim V = n and dim W = m, find dim $V \times W$.
- 8.7 Let $\mathbf{A} := [a_{jk}] \in \mathbb{K}^{4 \times 4}$. Define $T : \mathbb{K}^{2 \times 2} \to \mathbb{K}^{2 \times 2}$ by

$$T\left(\begin{bmatrix}x_{11} & x_{12}\\x_{21} & x_{22}\end{bmatrix}\right) = \begin{bmatrix}y_{11} & y_{12}\\y_{21} & y_{22}\end{bmatrix},$$

where $\begin{bmatrix} y_{11} & y_{12} & y_{21} & y_{22} \end{bmatrix}^\mathsf{T} := \mathbf{A} \begin{bmatrix} x_{11} & x_{12} & x_{21} & x_{22} \end{bmatrix}^\mathsf{T}$. Show that *T* is linear, and find the matrix of *T* with respect to the ordered basis $(\mathbf{E}_{11}, \mathbf{E}_{12}, \mathbf{E}_{21}, \mathbf{E}_{22})$ of $\mathbb{K}^{2 \times 2}$.

8.8 Define $T: \mathcal{P}_2 \to \mathbb{K}^{2 \times 1}$ by

$$T(\alpha_0 + \alpha_1 t + \alpha_2 t^2) := \begin{bmatrix} \alpha_0 + \alpha_1 & \alpha_1 + \alpha_2 \end{bmatrix}^{\mathsf{T}}$$

for $\alpha_0, \alpha_1, \alpha_2 \in \mathbb{R}$. If $E := (1, t, t^2)$ and $F := (\mathbf{e}_1, \mathbf{e}_2)$, then find \mathbf{M}_F^E . Also, if $E' := (1, 1+t, (1+t)^2)$ and $F' := (\mathbf{e}_1, \mathbf{e}_1 + \mathbf{e}_2)$, then find $\mathbf{M}_{F'}^{E'}$. 8.9 (Parallelogram law) Let V be an inner product space. Prove that the norm on V induced by the inner product satisfies $||v + w||^2 + ||v - w||^2 = 2||v||^2 + 2||w||^2$ for all $v, w \in V$.

(Conversely, if there is a norm $\|\cdot\|$ on a vector space V which satisfies the parallelogram law, then it can be shown that there is an inner product $\langle\cdot,\cdot\rangle$ on V such that $\langle v, v \rangle = \|v\|^2$ for all $v \in V$.)

8.10 For $\mathbf{A}, \mathbf{B} \in \mathbb{K}^{m \times n}$, define $\langle \mathbf{A}, \mathbf{B} \rangle := \operatorname{tr} \mathbf{A}^* \mathbf{B}$. Show that $\langle \cdot, \cdot \rangle$ is an inner product on $\mathbb{K}^{m \times n}$.

8.11 Show that

$$\left\{\frac{1}{\sqrt{2\pi}}, \frac{\cos t}{\sqrt{\pi}}, \frac{\sin t}{\sqrt{\pi}}, \frac{\cos 2t}{\sqrt{\pi}}, \frac{\sin 2t}{\sqrt{\pi}}, \dots\right\}$$

is an orthonormal subset of $C([-\pi,\pi])$.

(This is the beginning of the theory of Fourier Series.)

- 8.12 Let T be a Hermitian operator on a finite dimensional inner product space V over \mathbb{K} . Prove the following.
 - (i) $\langle T(v), v \rangle \in \mathbb{R}$ for every $v \in V$.
 - (ii) Every eigenvalue of T is real.
 - (iii) If $\lambda \neq \mu$ are eigenvalues of T with v and w corresponding eigenvectors of T, then $v \perp w$.
 - (iv) Let W be a subspace of V such that $T(W) \subset W$. Then $T(W^{\perp}) \subset W^{\perp}$.

